Feedback on Problem Set 1

Ph.D. Course:
An Introduction to DG-FEM
for solving partial differential equations

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Feedback On Problem Set 1

Consider the linear advection equation

$$\partial_t u + a\partial_x u = 0, \quad x \in [0, L]$$

with IC and BC conditions

$$u(x, 0) = \sin\left(\frac{2\pi}{L}x\right), \quad u(0, t) = -\sin\left(\frac{2\pi}{L}t\right)$$

The exact solution to this problem is given as

$$u(x, t) = f(x - at) = \sin\left(\frac{2\pi}{L}(x - at)\right)$$

where $f(\cdot)$ is an arbitrary initial function.

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```
% Driver script for solving the 1D advection equations
Globals1D;

% Order of polymomials used for approximation
N = 8;

% Generate simple mesh
[Nv, VX, K, EToV] = MeshGen1D(0.0,2.0,10);

% Initialize solver and construct grid and metric
StartUp1D;

% Set initial conditions
u = sin(x);

% advection speed
a = 2*pi;

% numerical flux (stable: 0<=alpha<=1)
alpha = 1;

% CFL constant
CFL=0.75;

% Solve Problem
FinalTime = 10;
[u] = Advec1D(u,FinalTime,a,alpha);
```

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```
function [u] = Advec1D(u, FinalTime, a, alpha)
% Purpose  : Integrate 1D advection until FinalTime starting with
%            initial the condition, u

Globals1D;
time = 0;

% Runge-Kutta residual storage
resu = zeros(Np,K);

% compute time step size
dxmin = min(abs(x(1,:)-x(2,:)));
dt = CFL*dxmin/a;
Nsteps = ceil(FinalTime/dt); dt = FinalTime/Nsteps;

% outer time step loop
for tstep=1:Nsteps
    for INTRK = 1:5
        timelocal = time + rk4c(INTRK)*dt;
        [rhsu] = AdvecRHS1D(u, timelocal, a, alpha);
        resu = rk4a(INTRK)*resu + dt*rhsu;
        u = u+rk4b(INTRK)*resu;
    end;
    % Increment time
    time = time+dt;
end;
return
```

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```
function [rhsu] = AdvecRHS1D(u,time, a,alpha)

% function [rhsu] = AdvecRHS1D(u,time)
% Purpose  : Evaluate RHS flux in 1D advection

Globals1D;

% form flux differences at faces
df    = zeros(Nfp*Nfaces,K);
df(:) = 0.5*a*(u(vmapM)-u(vmapP)).*(nx(:)-(1-alpha));

% impose boundary condition at x=0
uin      = -sin(a*time);
df(mapI) = 0.5*a*(u(vmapI)-uin).*(nx(mapI)-(1-alpha));
df(mapO) = 0;

% compute right hand sides of the semi-discrete PDE
rhsu = -a*rx.*(Dr*u) + LIFT*(Fscale.*(df));
return
```

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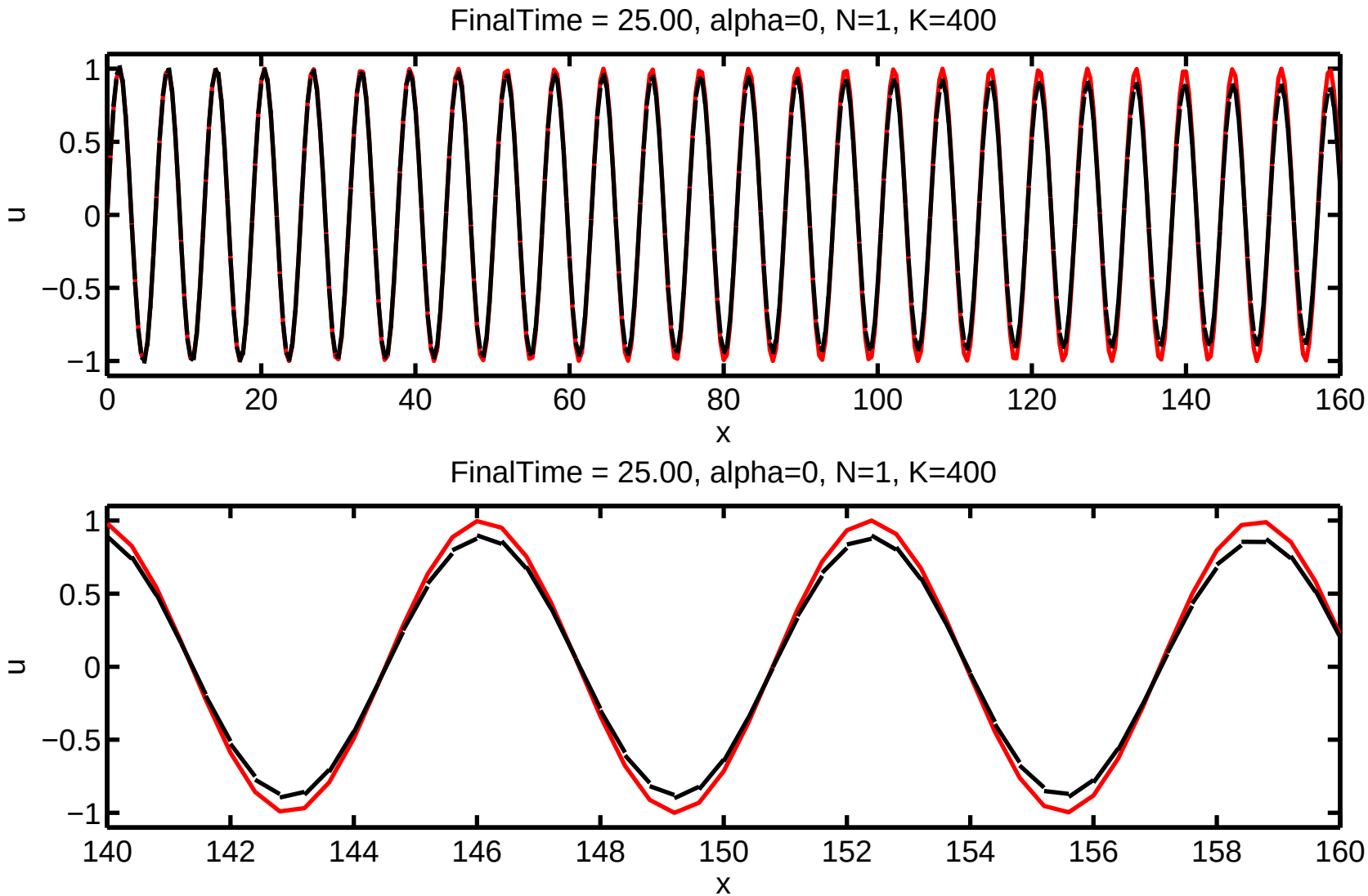

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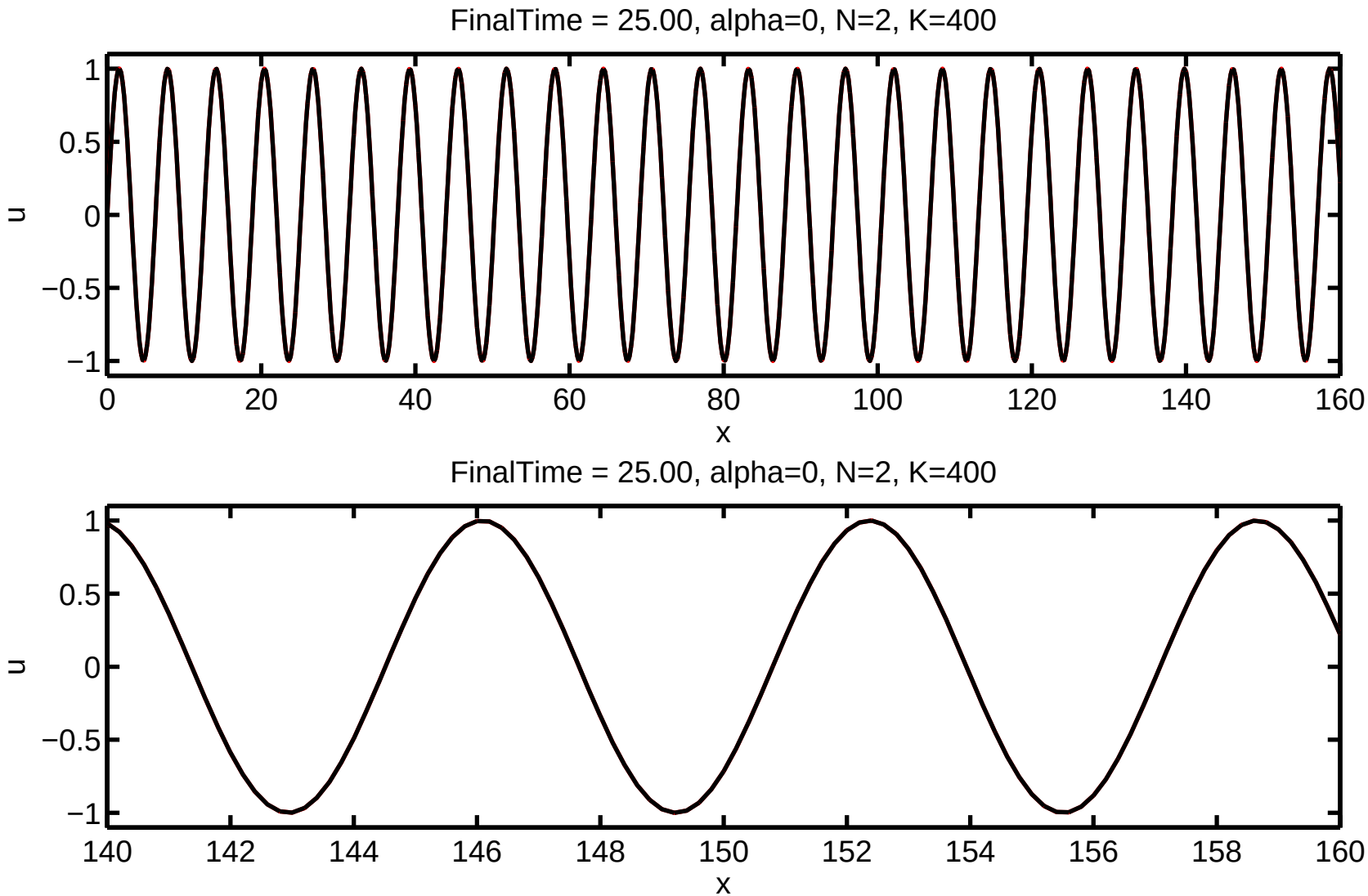

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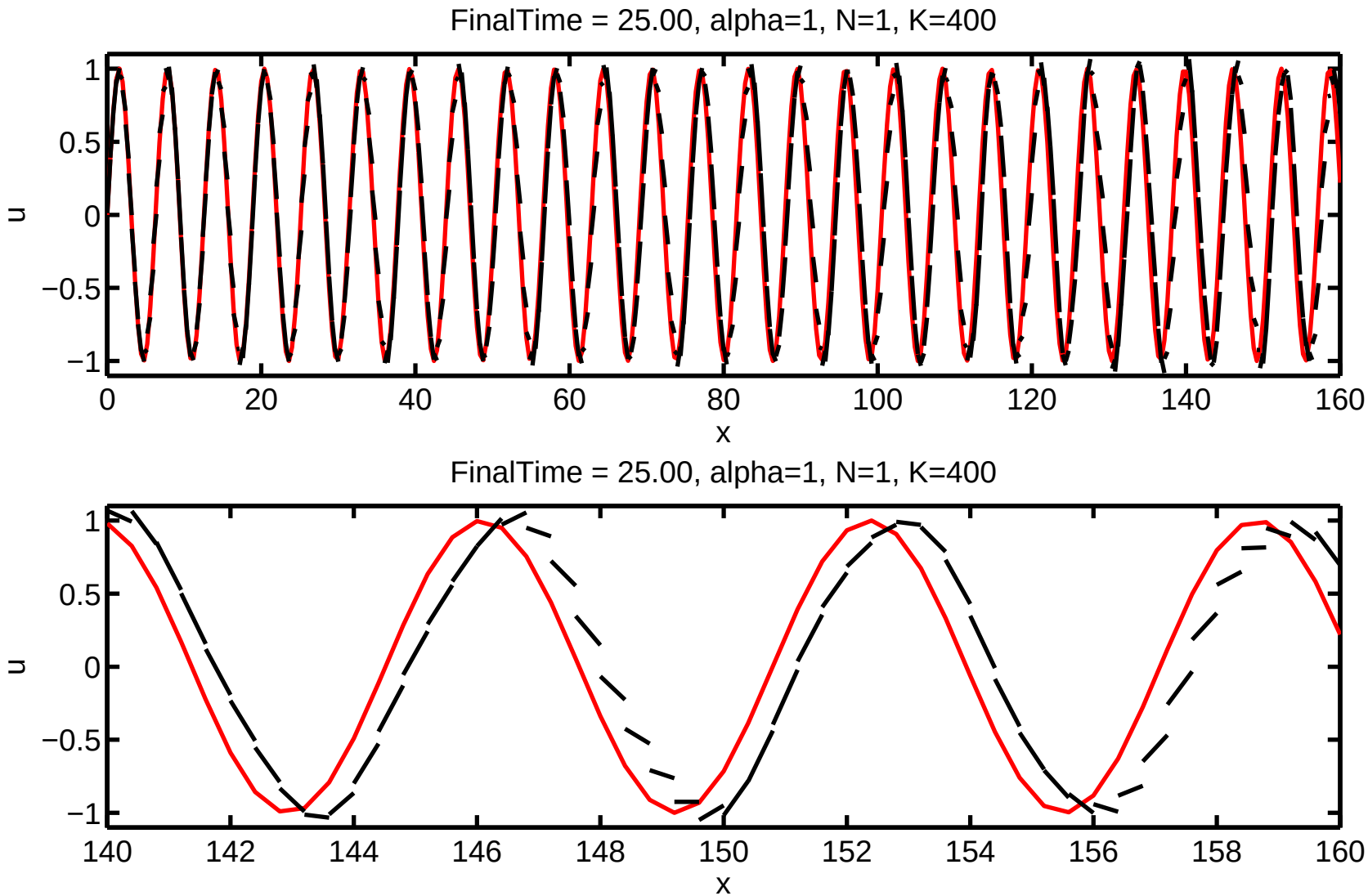

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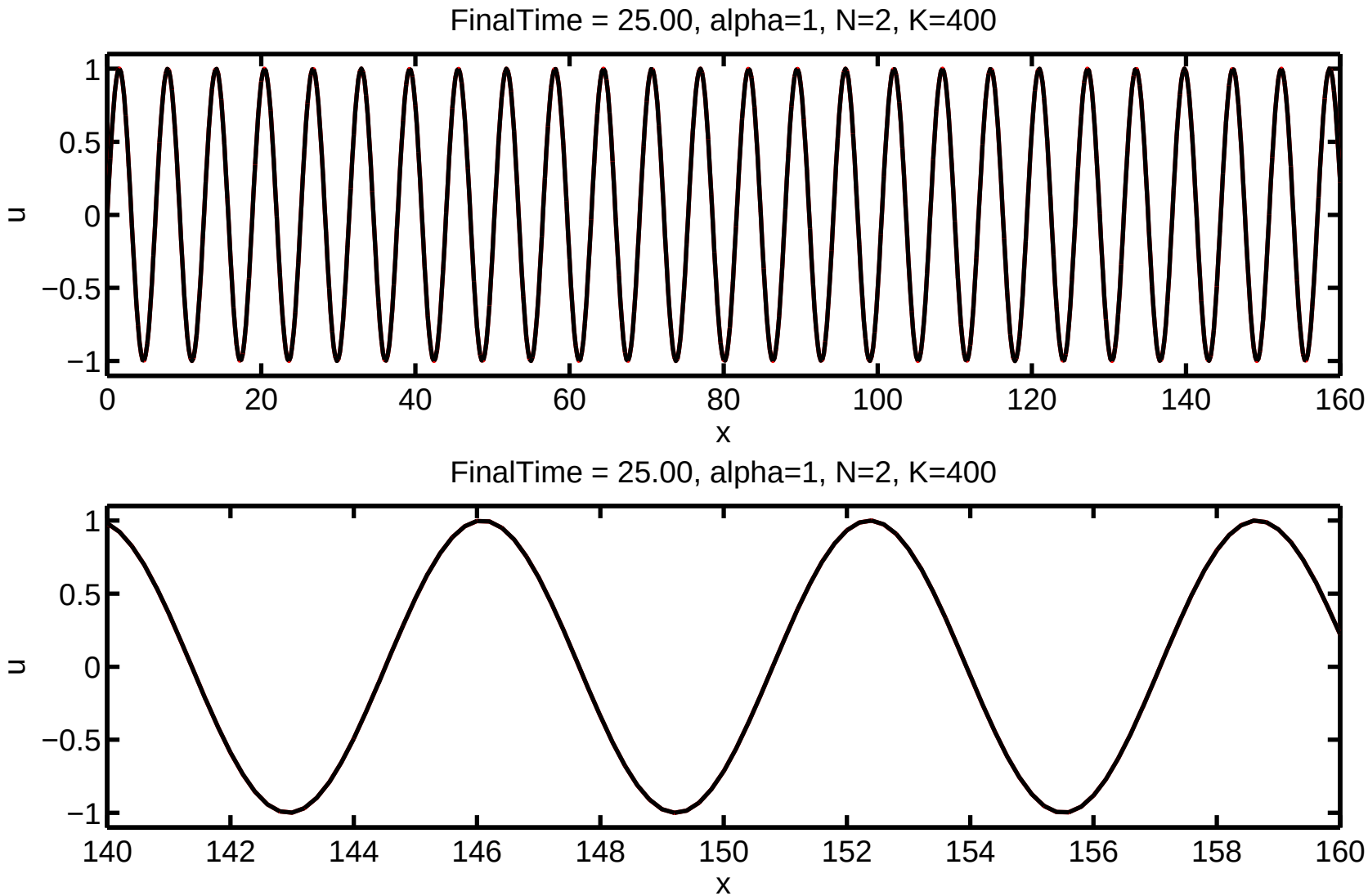

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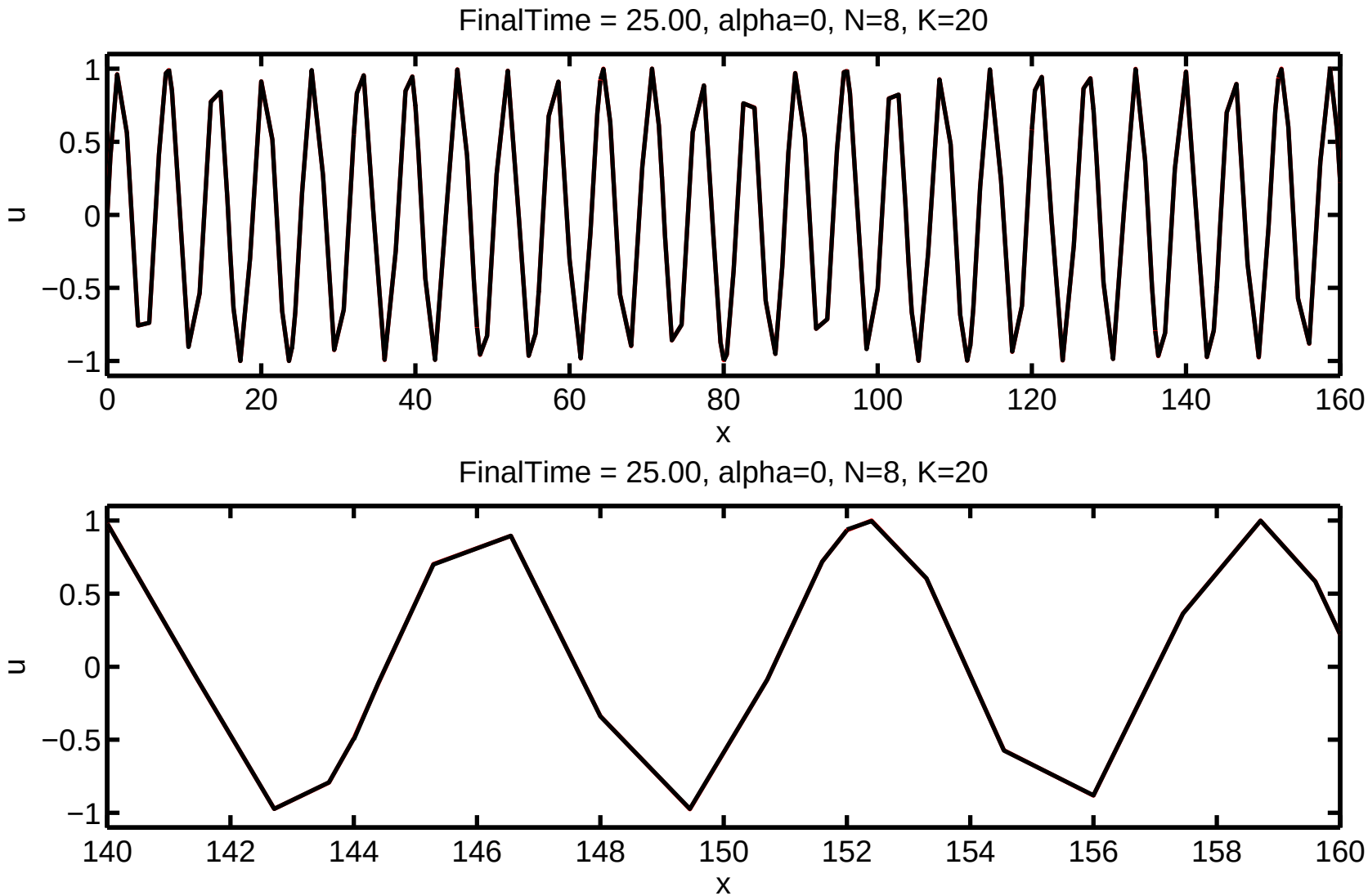

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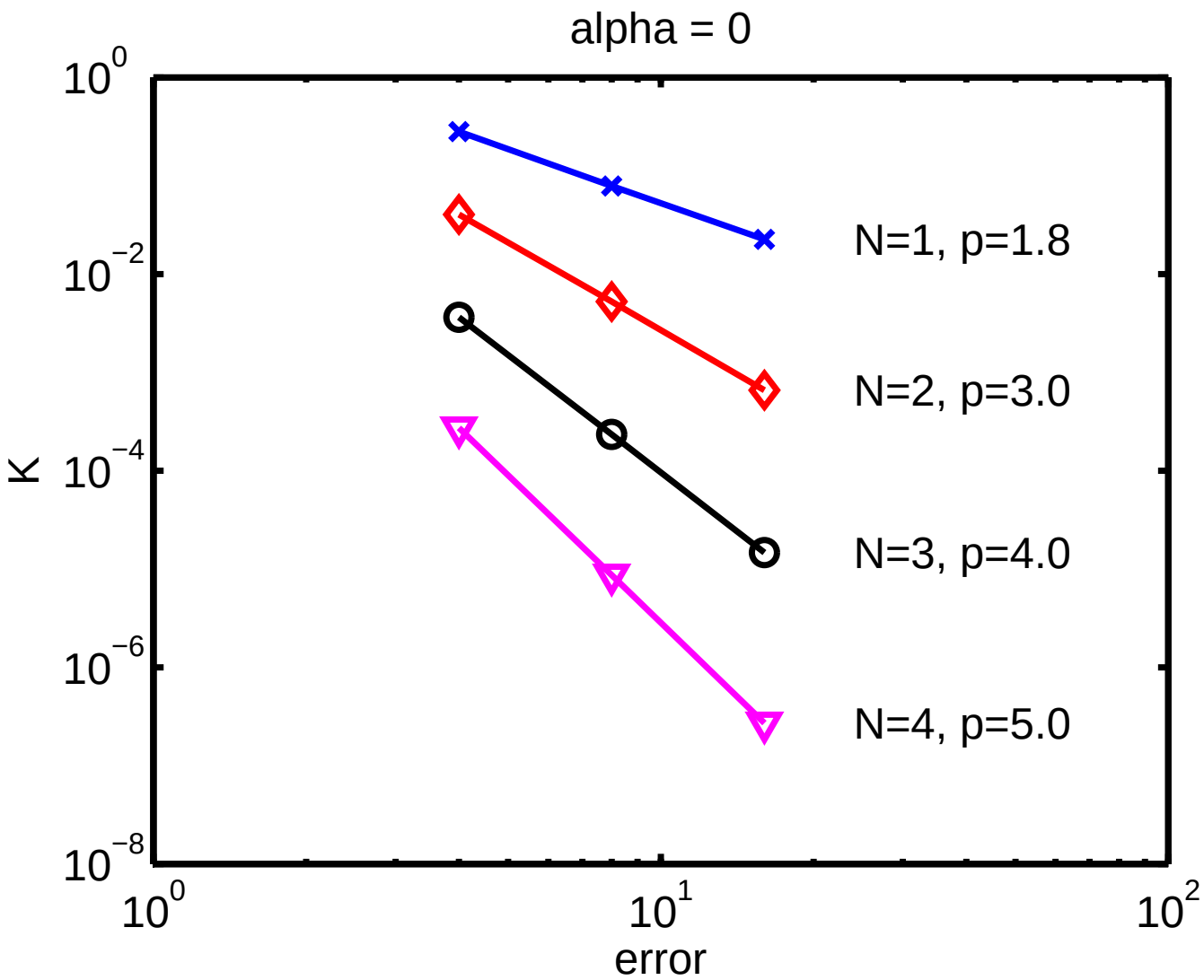

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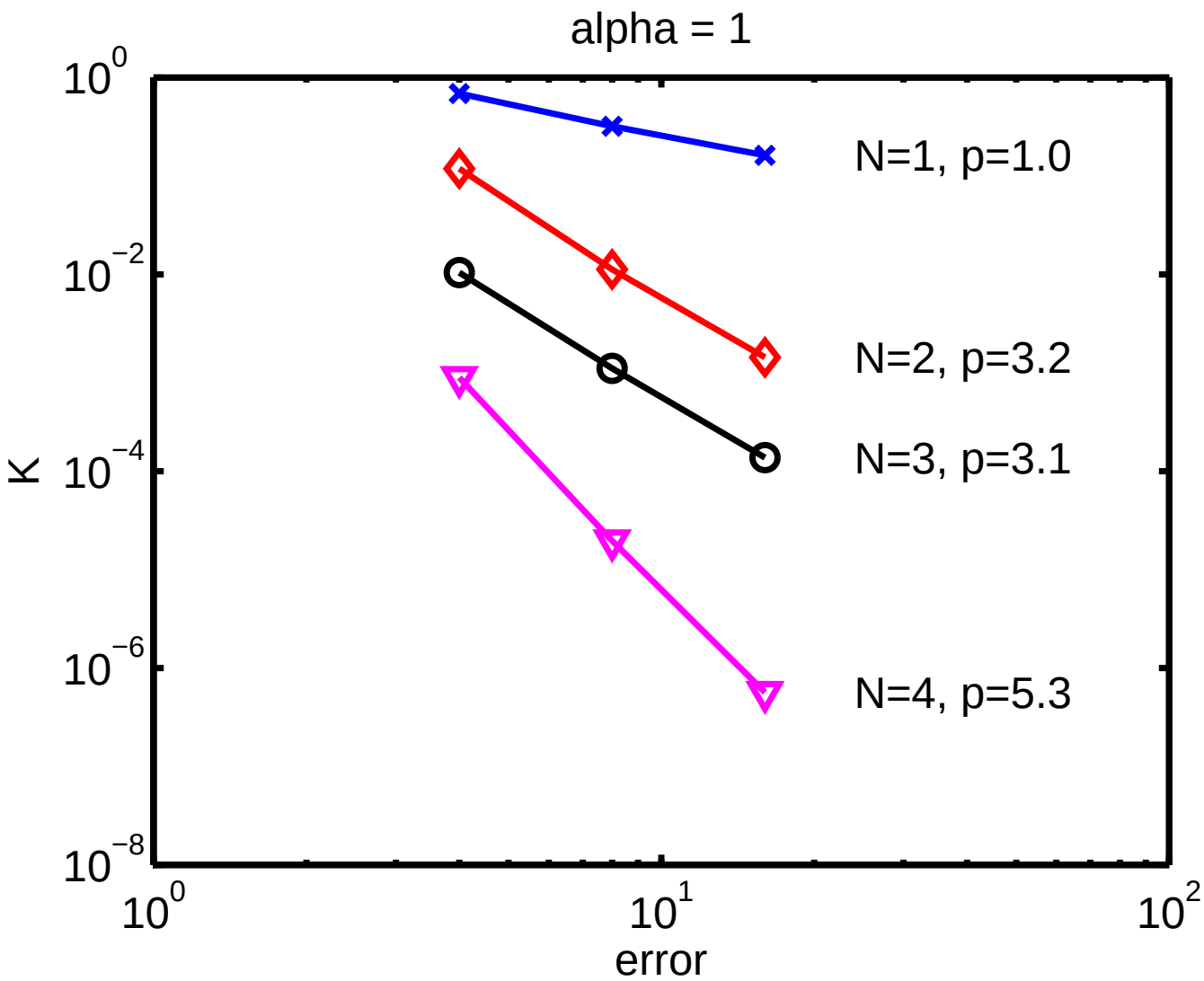

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$$\Delta t \propto \frac{h}{N^2}$$

- To increase the poly. order near the stability limit we would need to decrease the time step quadratically with 1/N.
- To reduce the size of elements h, i.e. increase K, we would need to reduce the time step linearly.