## Course 02158

# **Properties of Concurrent Programs**

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### **Properties of Concurrent Programs**

- Concurrent programs are (usually) reactive
- Properties must deal with *behaviour*, not results
- Two kinds of *functional properties*:
  - Safety properties Program does nothing wrong
  - Liveness properties Program does something (good)
- Real-time and performance requirements may be added

#### Formal treatment

- Let  $\alpha = \mathbf{s_0} \xrightarrow{a_0} \mathbf{s_1} \xrightarrow{a_1} \mathbf{s_2} \cdots$  be a (finite or infinite) execution
- Let  $\phi[\alpha]$  denote that property  $\phi$  holds for execution  $\alpha$
- A property  $\phi$  holds for a program P iff

 $\forall \alpha \in \textit{Exec}(\textit{P}) : \phi[\alpha]$ 

where Exec(P) is the set of all executions of P

### **Safety Properties**

• A safety property ensures that the program does nothing wrong

#### Examples

- At most one process may use the printer at a time
- The variable x never decreases
- The motor turns off only if the key has been removed

### Formal treatment

- Property  $\phi$  is satisfied for execution  $\alpha$ :  $\phi[\alpha]$
- $\phi$  is a *safety property* iff

 $\forall \alpha: \neg \phi[\alpha] \Rightarrow \exists \beta \prec \alpha: \forall \gamma: \neg \phi[\beta \gamma]$ 

- Can be stated by *invariants* (and history variables)
- Can be shown by *model-checking* or *inductive proofs*

### **Liveness Properties**

• A liveness property ensures that the program makes progress

### Examples

- The program will return to input mode again and again
- The variable x will never become constant
- The green light is lit when the Go button is pressed

### Formal treatment

•  $\phi$  is a (pure) *liveness property* iff

$$\forall \beta : \mathsf{fin}(\beta) \Rightarrow \exists \gamma : \phi[\beta\gamma]$$

- Can be stated using *Temporal Logic*
- Can be shown by temporal reasoning, e.g. proof lattices

## **Race Conditions**

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• A race condition is the possibility of an unintended result or effect
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• Caused by a particular execution

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Example (Java)
class job extends Thread {
  private boolean finish;
  public void run() {
    finish = false;
    while (finish==false) {
        :
        }
    public void endThread() { finish = true; }
    ;
    ;
}
```

## Lack-of-progress Properties

### Deadlock

- *Deadlock* = cycle of processes waiting for each other (for ever)
- Typical cause: incremental reservation of shared resources

### Starvation

- A process suffers from *starvation* if it could make progress, but never does so
- Typical causes: Unfair scheduling, priorities, bad luck

### Livelock

- *Livelock* = mutual starvation (*after-you-after-you*)
- Like deadlock, but can be *escaped*
- Typical cause: Symmetrical strategies
- Note: Andrews sets *livelock* = *deadlock* we don't