

Course 02158

Invariants

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DTU Compute

Invariants

- Let I be a *state predicate* over the global state of a concurrent program P
- I is an *invariant* of P if it holds at any time in any execution
- Safety properties can be expressed as invariants (+ *history variables*)

Syntax

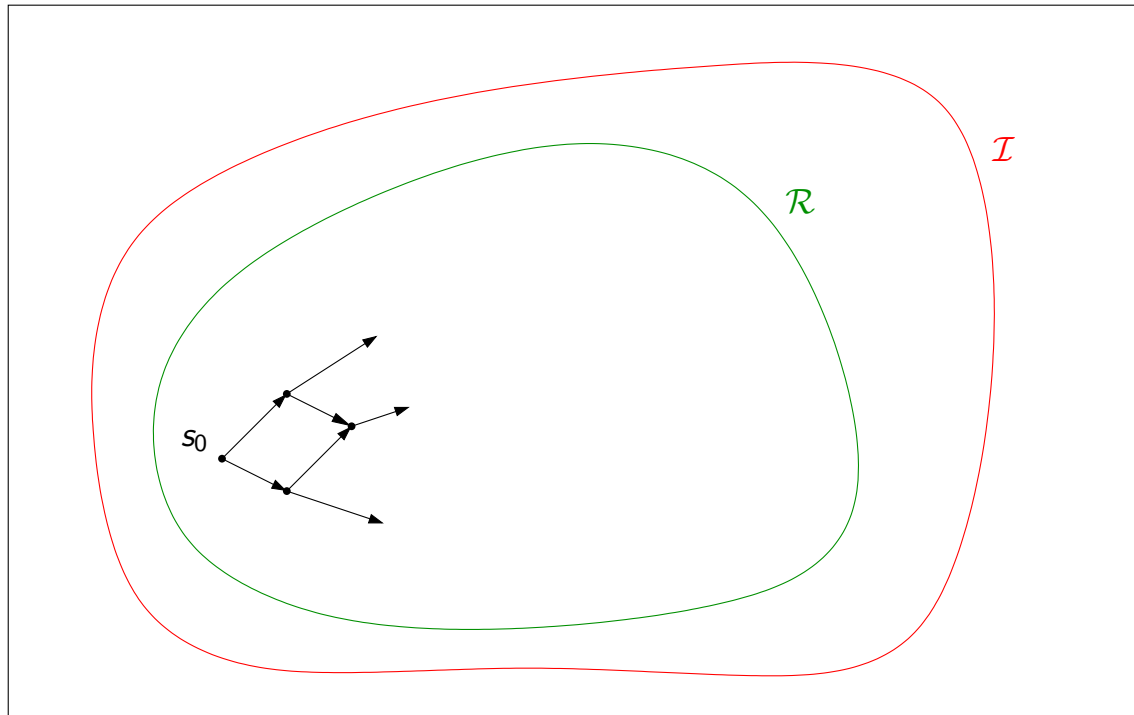
- May refer to the value of *global variables*, e.g. $x = 5$ or $\neg done$.
- May refer to the *control state* of each process, e.g. $\pi_i = I$.
- Abbreviations (for action a in process P_i)

$$\begin{aligned} at\ I &\triangleq \pi_i = I \\ at\ a &\triangleq \pi_i = preloc(a) \end{aligned}$$

- For a statement $S : a_1; a_2; \dots; a_n$:

$$\begin{aligned} in\ S &\triangleq at\ a_1 \vee at\ a_2 \vee \dots \vee at\ a_n \\ at\ S &\triangleq at\ a_1 \\ after\ S &\triangleq after\ a_n \end{aligned}$$

Invariance Notion



Inductive Invariance Technique

- Let there be given a concurrent program with atomic actions
- A state predicate I is said to be *inductive* if
 - ▶ I holds for the initial state.
 - ▶ Any atomic action a of the program *preserves* I , i.e. for any state s for which I is satisfied, it is either the case that:
 - a) a cannot be executed in s , or
 - b) the execution of a in state s results in a state s' that again satisfies I .
- If I is inductive, it is an invariant of the program.
- To show a), *known invariants* and may be used.
- If I fails to be inductive, it may be *strengthened*.

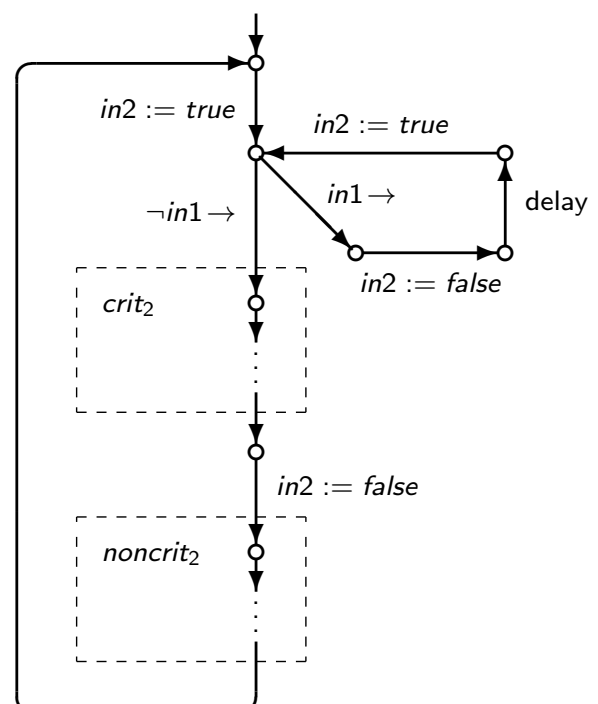
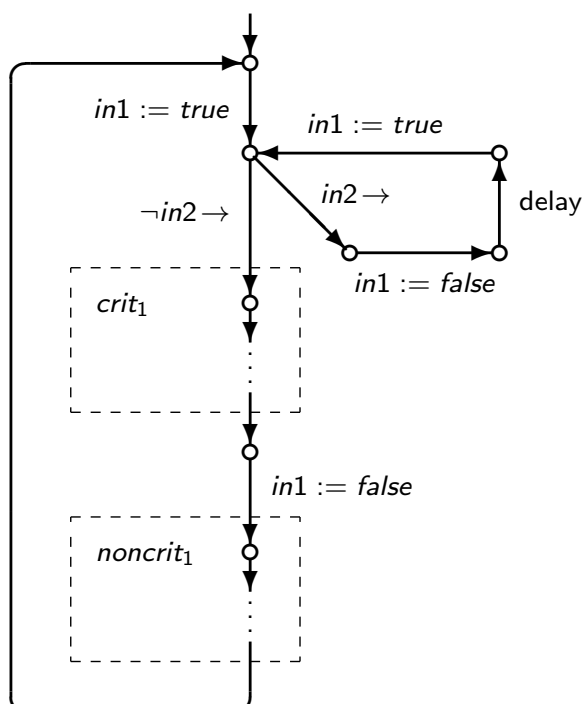
Critical Region with Shared Variables

Fine-grained attempt III (Back-off)

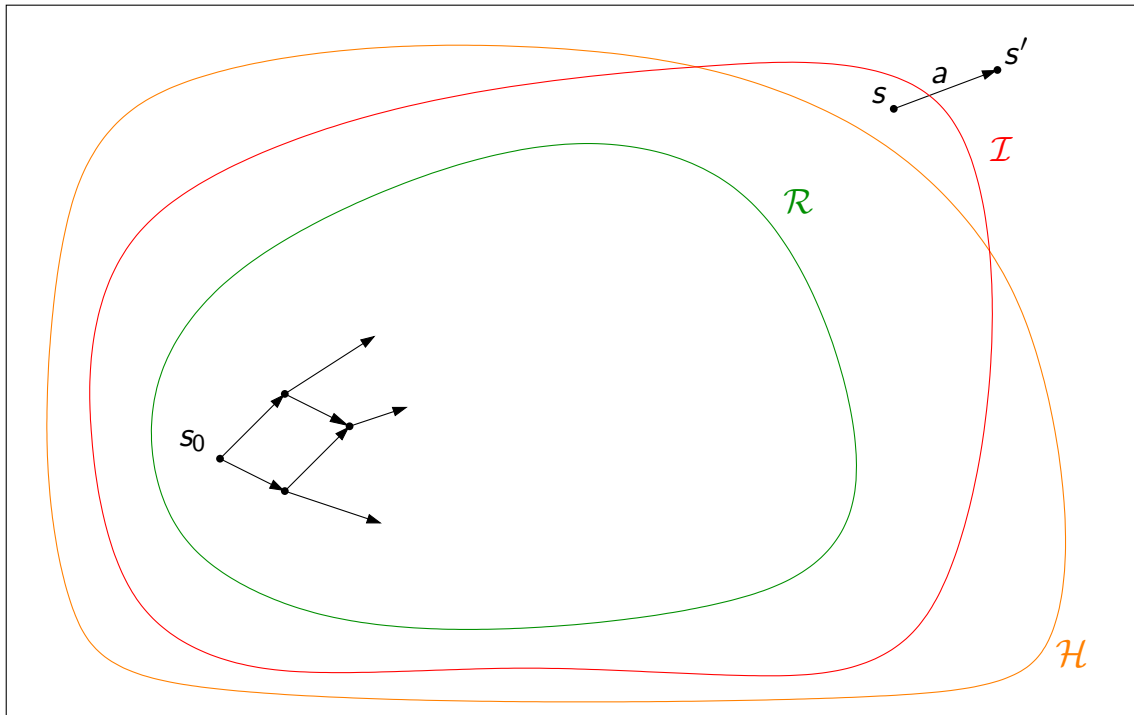
- var** *in1, in2* : *bool* := *false*;
process *P*₁
loop
 in1 := *true*;
 while *in2* **do** { *in1* := *false*;
 delay;
 in1 := *true* }
 critical section₁;
 in1 := *false*;
 noncritical section₁
end loop

process *P*₂
loop
 in2 := *true*;
 while *in1* **do** { *in2* := *false*;
 delay;
 in2 := *true* }
 critical section₂;
 in2 := *false*;
 noncritical section₂
end loop

Example: Back-off attempt



Invariance Using Auxiliary Invariant



Backoff attempt — Invariants

- Mutual Exclusion

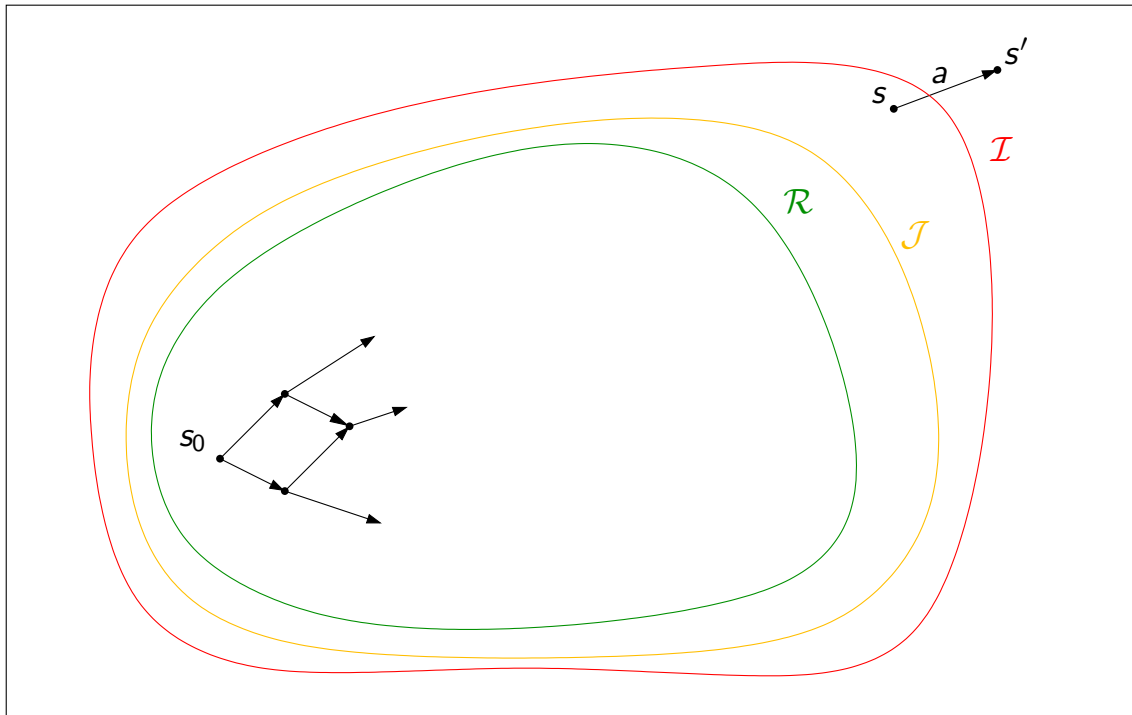
$$I \triangleq \neg(in\ crit_1 \wedge in\ crit_2)$$

- Local invariants

$$I_1 \triangleq in\ crit_1 \Rightarrow in_1$$

$$I_2 \triangleq in\ crit_2 \Rightarrow in_2$$

Invariance Using Strengthened Invariant



Example: Peterson's algorithm

• **var** try_A, try_B : *boolean*;
 $turn$: (A, B);

$try_A := false$; $try_B := false$; $turn := A$;

process P_A

repeat

$Non-Crit_A$;

$try_A := true$;

$turn := B$;

W_A : **while** $try_B \wedge turn = B$ **do** ;

$Crit_A$;

$try_A := false$

forever

process P_B

repeat

$Non-Crit_B$;

$try_B := true$;

$turn := A$;

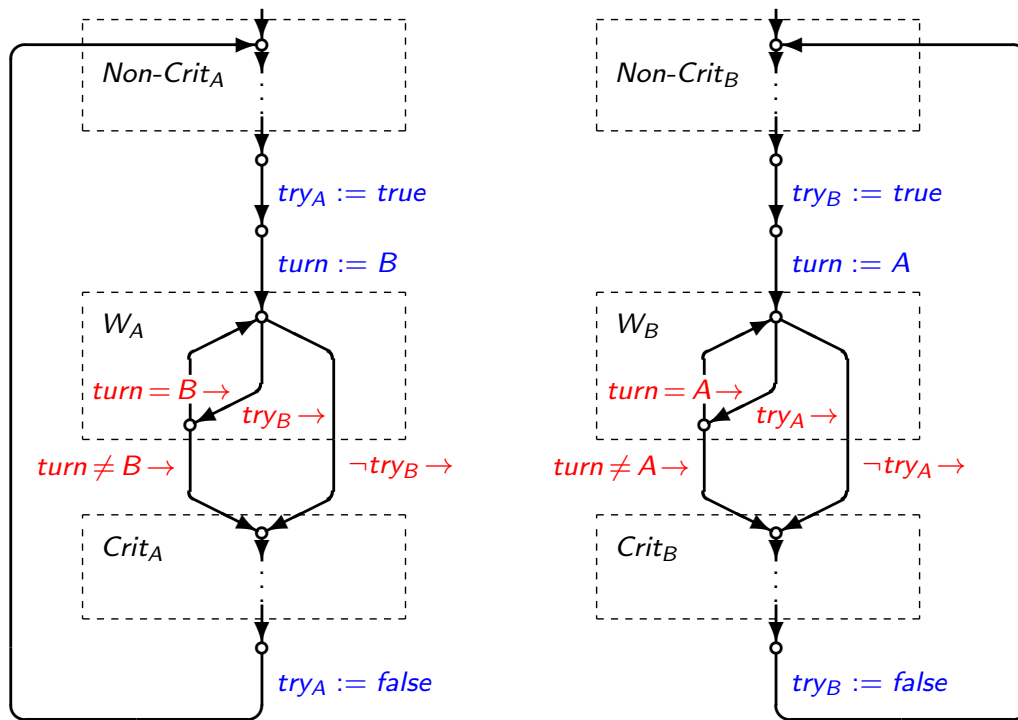
W_B : **while** $try_A \wedge turn = A$ **do** ;

$Crit_B$;

$try_B := false$

forever

Example: Peterson's algorithm



Peterson's algorithm – Invariants

- Mutual Exclusion

$$I \triangleq \neg(in\ Crit_A \wedge in\ Crit_B)$$

- Local invariants

$$I_1 \triangleq in\ W_A..Crit_A \Rightarrow try_A$$

$$I_2 \triangleq in\ W_B..Crit_B \Rightarrow try_B$$

- Value invariants

$$I_3 \triangleq turn = A \vee turn = B$$

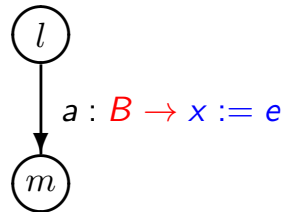
- Auxiliary invariants

$$I_a \triangleq in\ W_A \wedge in\ Crit_B \Rightarrow turn = B$$

$$I_b \triangleq in\ W_B \wedge in\ Crit_A \Rightarrow turn = A$$

Pre/post Notation

- Let a be a given action:



- Let $(\dots)'$ refer to the state *after* execution of a
- Action a *preserves* predicate I iff

$$I \wedge B \wedge \text{at } l \wedge \text{"effect of } a" \Rightarrow I'$$

where the effect is formally given by

$$\begin{aligned}
 x' &= e \wedge \text{at } m', \\
 y' &= y && \text{for all variables } y \text{ different from } x, \\
 q' &= q && \text{for all control predicates } q \text{ not involving } l \text{ or } m.
 \end{aligned}$$

Pre/post Notation — Example

Peterson's algorithm

- Prove: $I_a \triangleq \text{in } W_A \wedge \text{in } \text{Crit}_B \Rightarrow \text{turn} = B$ is an invariant
- Initially: $\text{at } \text{Non-Crit}_A \Rightarrow \neg \text{in } W_A \Rightarrow I_a$

Process	Action	Proof	Argument
P_A	$\text{turn} := B$	I_a'	$\text{turn}' = B$
P_B	$\text{turn} := A$	$\neg \text{in } \text{Crit}_B'$ I_a'	$\text{at } W_B'$
	$\neg \text{try}_A \rightarrow$	$\neg \text{in } W_A$ $\neg \text{in } W_A'$ I_a'	Cond., I_1 $\text{in } W_A' = \text{in } W_A$
	$\text{turn} \neq A \rightarrow$	$\text{turn} = B$ $\text{turn}' = B$ I_a'	Cond., I_3 $\text{turn}' = \text{turn}$