- Data Structures
- Stacks and Queues
- Linked Lists
- Dynamic Arrays

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Data Structures

- Stacks and Queues
- Linked Lists
- Dynamic Arrays

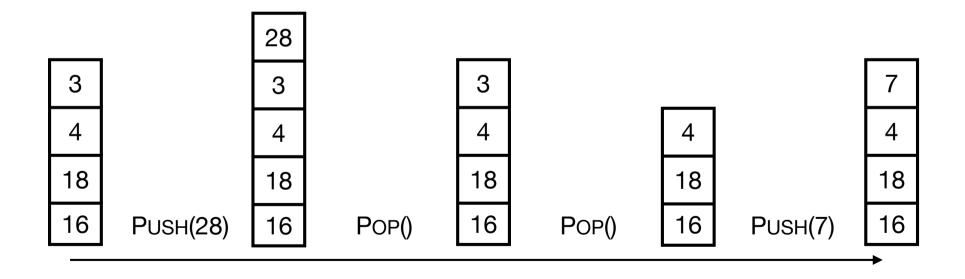
Data Structures

- Data structure. Method for organizing data for efficient access, searching, manipulation, etc.
- Goal.
 - Fast.
 - Compact
- Terminology.
 - Abstract vs. concrete data structure.
 - Dynamic vs. static data structure.

- Data Structures
- Stacks and Queues
- Linked Lists
- Dynamic Arrays

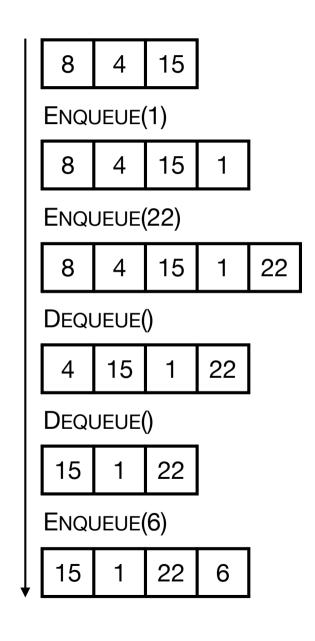
Stack

- Stack. Maintain dynamic sequence (stack) S supporting the following operations:
 - PUSH(x): add x to S.
 - POP(): remove and return the most recently added element in S.
 - ISEMPTY(): return true if S is empty.



Queue

- Queue. Maintain dynamic sequence (queue) Q supporting the following operations:
 - ENQUEUE(x): add x to Q.
 - DEQUEUE(): remove and return the earliest added element in Q.
 - ISEMPTY(): return true if Q is empty.



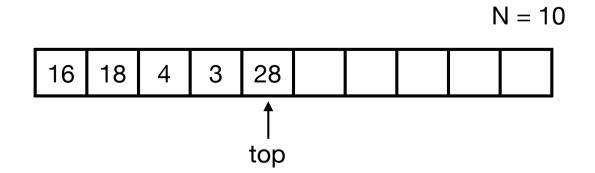
Applications

• Stacks.

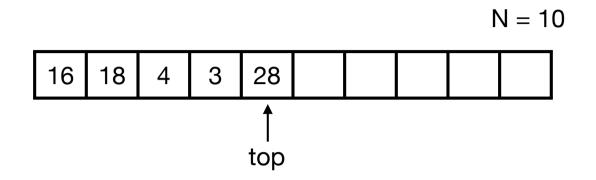
- Virtual machines
- Parsing
- Function calls
- Backtracking
- Queues.
 - Scheduling processes
 - Buffering
 - Breadth-first searching

Stack Implementation

- Stack. Stack with capacity N
- Data structure.
 - Array S[0..N-1]
 - Index top. Initially top = -1
- Operations.
 - PUSH(x): Add x at S[top+1], top = top + 1
 - POP(): return S[top], top = top 1
 - ISEMPTY(): return true if top = -1.
 - Check for overflow and underflow in PUSH and POP.



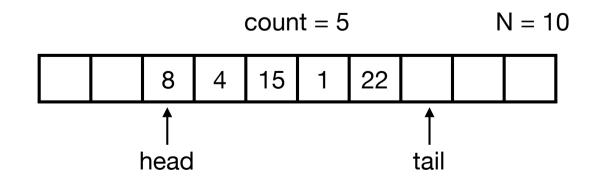
Stack Implementation



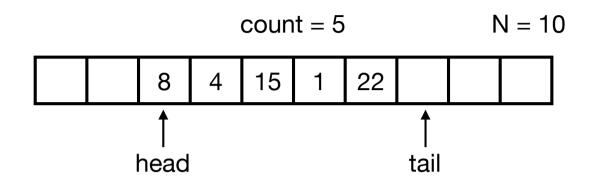
- Time
 - PUSH in O(1) time.
 - POP in O(1) time.
 - ISEMPTY in O(1) time.
- Space.
 - O(N) space.
- Limitations.
 - · Capacity must be known.
 - Wasting space.

Queue Implementation

- Queue. Queue with capacity N.
- Data structure.
 - Array Q[0..N-1]
 - Indices head and tail and a counter.
- Operations.
 - ENQUEUE(x): add x at Q[tail], update count and tail cyclically.
 - DEQUEUE(): return Q[head], update count and head cyclically.
 - ISEMPTY(): return true if count = 0.
 - Check for overflow and underflow in DEQUEUE and ENQUEUE.



Queue Implementation

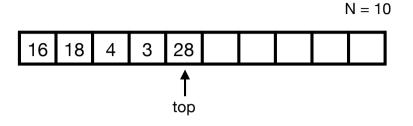


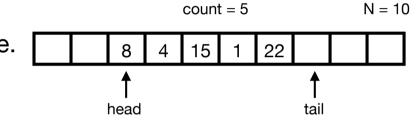
- Time.
 - ENQUEUE in O(1) time.
 - DEQUEUE in O(1) time.
 - ISEMPTY in O(1) time.
- Space.
 - O(N) space.
- Limitations.
 - Capacity must be known.
 - Wasting space.

Stacks and Queues

- Stack.
 - Time. PUSH, POP, ISEMPTY in O(1) time.
 - Space. O(N)
- Queue.
 - Time. ENQUEUE, Dequeue, ISEMPTY in O(1) time.
 - Space. O(N)

• Challenge. Can we get linear space and constant time?

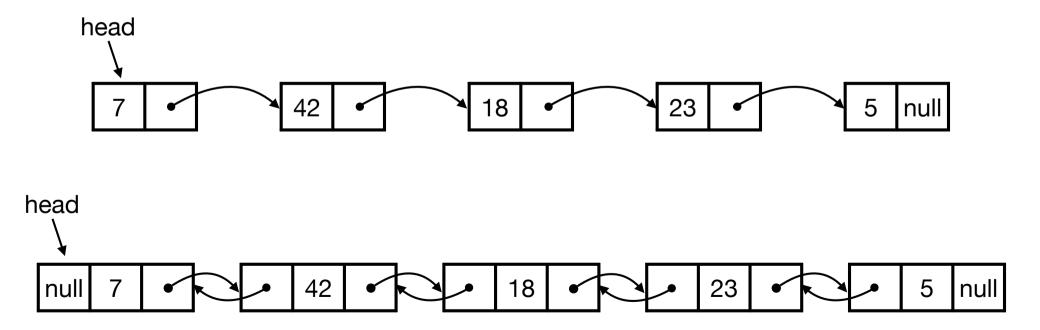




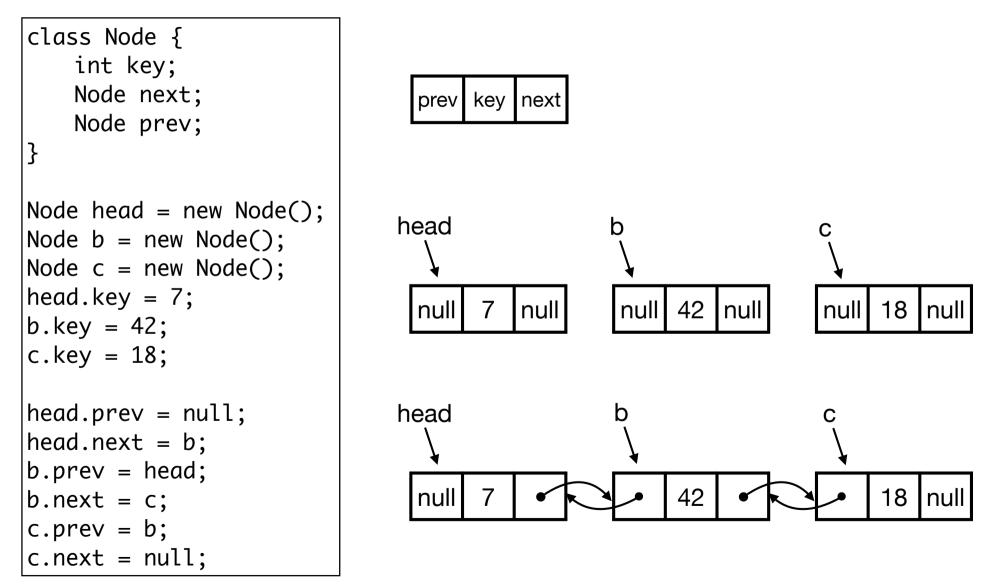
- Data Structures
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• Linked lists.

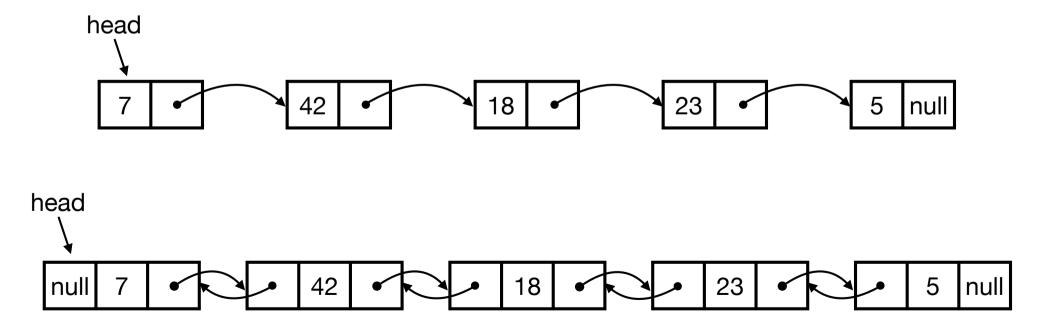
- Data structure to maintain dynamic sequence of elements in linear space.
- Sequence order determined by pointers/references called links.
- Fast insertion and deletion of elements and contiguous sublists.
- Singly-linked vs doubly-linked.

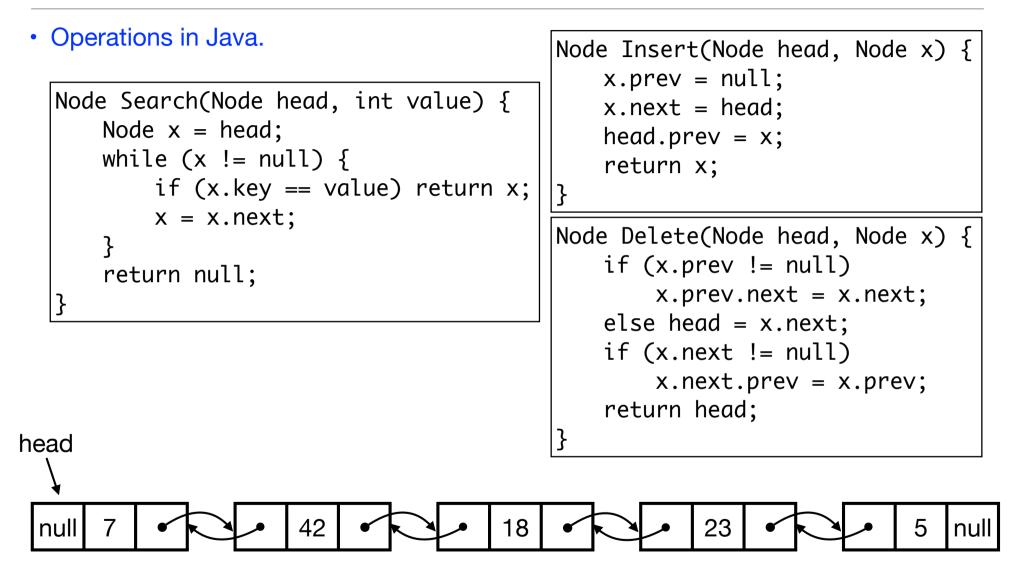


• Doubly-linked lists in Java.

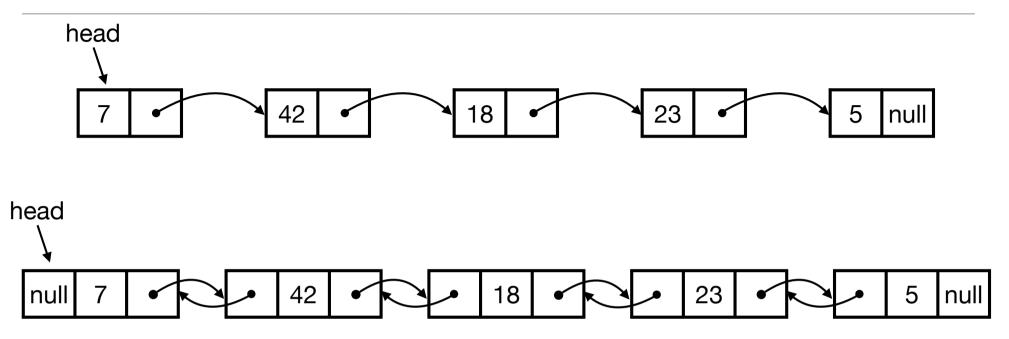


- Simple operations.
 - SEARCH(head, k): return node with key k. Return null if it does not exist.
 - INSERT(head, x): insert node x in front of list. Return new head.
 - DELETE(head, x): delete node x in list.





Ex. Let p be a new with key 10 and let q be node with key 23 in list. Trace execution of Search(head, 18), Insert(head, p) og Delete(head, q).



- Time.
 - SEARCH in O(n) time.
 - INSERT and DELETE in O(1) time.
- Space.
 - O(n)

Stack and Queue Implementation

- Ex. Consider how to implement stack and queue with linked lists efficiently.
- Stack. Maintain dynamic sequence (stack) S supporting the following operations:
 - PUSH(x): add x to S.
 - POP(): remove and return the most recently added element in S.
 - ISEMPTY(): return true if S is empty.
- Queue. Maintain dynamic sequence (queue) Q supporting the following operations:
 - ENQUEUE(x): add x to Q.
 - DEQUEUE(): remove and return the earliest added element in Q.
 - ISEMPTY(): return true if S is empty.

Stack and Queue Implementation

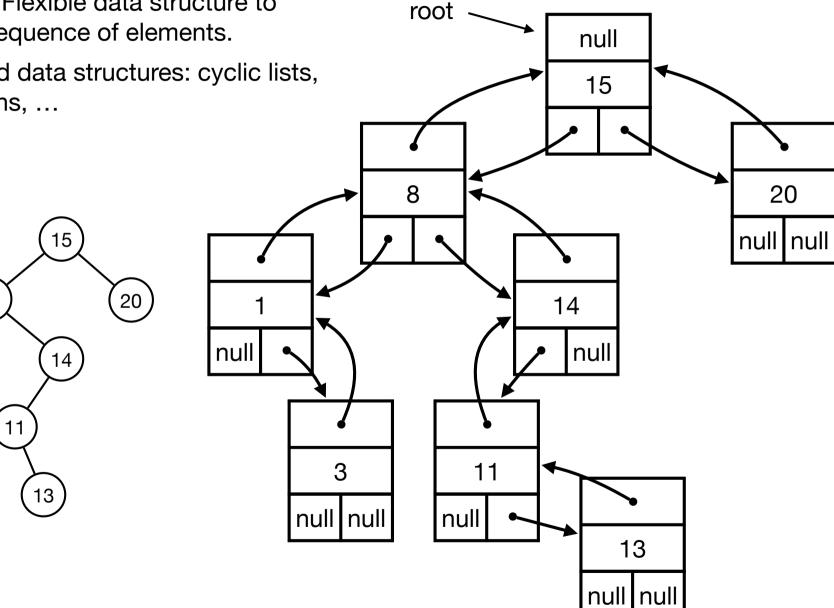
- Stacks and queues using linked lists
- Stack.
 - Time. PUSH, POP, ISEMPTY in O(1) time.
 - Space. O(n)
- Queue.
 - Time. ENQUEUE, DEQUEUE, ISEMPTY in O(1) time.
 - Space. O(n)

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- Linked list. Flexible data structure to maintiain sequence of elements.
- Other linked data structures: cyclic lists, trees, graphs, ...



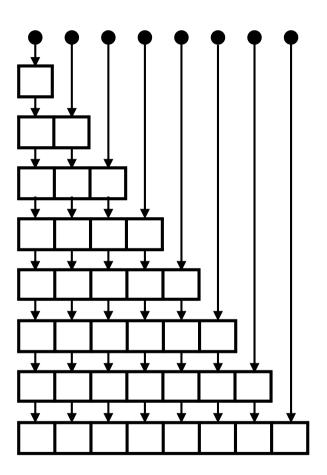
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Stack Implementation with Array

- Challenge. Can we implement a stack efficiently with arrays?
 - Do we need a fixed capacity?
 - Can we get linear space and constant time?

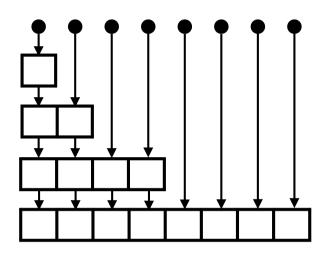
- Goal.
 - Implement a stack using arrays in O(n) space for n elements.
 - As fast as possible.
 - Focus on PUSH. Ignore POP and ISEMPTY for now.
- Solution 1
 - Start with array of size 1.
- PUSH(x):
 - Allocate new array of size + 1.
 - Move all elements to new array.
 - Delete old array.

- PUSH(x):
 - Allocate new array of size + 1.
 - Move all elements to new array.
 - Delete old array.
- Time. Time for n PUSH operations?
 - ith PUSH takes O(i) time.
 - \Rightarrow total time is 1 + 2 + 3 + 4 + ... + n = O(n²)
- Space. O(n)
- Challenge. Can we do better?



- Idea. Only copy elements some times
- Solution 2.
 - Start with array of size 1.
- PUSH(x):
 - If array is full:
 - Allocate new array of twice the size.
 - Move all elements to new array.
 - Delete old array.

- PUSH(x):
 - If array is full:
 - Allocate new array of twice the size.
 - Move all elements to new array.
 - Delete old array.
- Time. Time for n PUSH operations?
 - PUSH 2^k takes O(2^k) time.
 - All other PUSH operations take O(1) time.
 - \Rightarrow total time < 1 + 2 + 4 + 8 + 16 + ... + 2^{log n} + n = O(n)
- Space. O(n)



- Stack with dynamic array.
 - n PUSH operations in O(n) time and space.
 - Extends to n PUSH, POP og ISEMPTY operations in O(n) time.
- Time is amortized O(1) per operation.
- With more clever tricks we can deamortize to get O(1) worst-case time per operation.
- Queue with dynamic array.
 - Similar results as stack.
- Global rebuilding.
 - Dynamic array is an example of global rebuilding.
 - Technique to make static data structures dynamic.

Stack and Queues

Data structure	PUSH	Рор	ISEMPTY	Space
Array with capacity N	O(1)	O(1)	O(1)	O(N)
Linked List	O(1)	O(1)	O(1)	O(n)
Dynamic Array 1	O(n)	O(1)†	O(1)	O(n)
Dynamic Array 2	O(1)†	O(1)†	O(1)	O(n)
Dynamic Array 3	O(1)	O(1)	O(1)	O(n)

† = amortized

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