Errata:
Data-Driven Importance Distributions for Articulated Tracking
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This document provides a list of known issues for the paper “Data-Driven Importance Distributions for Articulated Tracking” [1]. Please contact Søren Hauberg in case you find further mistakes.

• Equation 6 of the paper states that

\[ p_{\text{proj}}(\theta_t|\theta_{t-1}) = \text{proj}_{\mathcal{M}}[\mathcal{N}(F(\theta_t)|F(\theta_{t-1}), \Sigma)]. \] (1)

This distribution is obviously not normalized correctly, and like other distributions discussed in the paper it is only stated up to an unknown constant:

\[ p_{\text{proj}}(\theta_t|\theta_{t-1}) \propto \text{proj}_{\mathcal{M}}[\mathcal{N}(F(\theta_t)|F(\theta_{t-1}), \Sigma)]. \] (2)

I apologize for this typo.

References