Errata:
Gaussian-like Spatial Priors for Articulated Tracking

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This document provides a list of known issues for the paper “Gaussian-like Spatial Priors for Articulated Tracking” [1]. Please contact Søren Hauberg in case you find further mistakes.

- Equation 5 of the paper states that

\[ p_{proj}(\theta_t | \theta_{t-1}) = \text{proj}_M [N(F(\theta_t)|F(\theta_{t-1}), \Sigma_{proj})]. \] (1)

This distribution is obviously not normalized correctly, and like other distributions discussed in the paper it is only stated up to an unknown constant:

\[ p_{proj}(\theta_t | \theta_{t-1}) \propto \text{proj}_M [N(F(\theta_t)|F(\theta_{t-1}), \Sigma_{proj})]. \] (2)

I apologize for this typo.

References