

# Compressed Sensing in Imaging Mass Spectrometry

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Joint work with

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# Outline

- 1 Imaging mass spectrometry (IMS)
- 2 Compressed sensing in IMS
- 3 Numerics: Implementation & Results
- 4 Conclusion







#### 1 Imaging mass spectrometry (IMS)

- 2 Compressed sensing in IMS
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# Mass spectrometry (MS)

Technique of analytical chemistry that identifies the elemental composition of a chemical sample based on mass-to-charge ratio of charged particles.

#### What is it used for?

- drug development
- detect/identify the use of drugs of abuse (dopings) in athlets
- identification of explosives and analysis of explosives in postblast residues (*puffer machine*)
- study the interaction of two (or more) bacterial cultures
- detection of disease biomarkers
- determination of proteins, peptides, metabolites
- and . . .



# MS methods

- Matrix-Assisted Laser Desorption/Ionization (MALDI)
- Secondary Ion Mass Spectrometry (SIMS)
- Desorption Electrospray Ionization (DESI)

- 1 sample is cut and mounted on glass slide
- 2 matrix solution is applied (acid crystalisation)
- 3 laser desorption of 'spots'  $(grid \sim 20 \ \mu m - 200 \ \mu m)$
- 4 computer aided analysis of m/z-slices





#### Matrix-assisted laser desorption/ionization



[Alexandrov et al.'11]

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### Matrix-assisted laser desorption/ionization



[Alexandrov et al.'11]







#### Matrix-assisted laser desorption/ionization



[Alexandrov et al.'11]

 $\implies$  IMS data: Hyperspectral data  $X \in \mathbb{R}^{n_X imes n_y imes c}_+$  (m/z-spectra and -images)

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#### The information disaster – data overflow

Data 
$$X \in \mathbb{R}^{n_x \times n_y \times c}_+$$
 typically contains <sup>B)</sup>  
**a**  $n_x \cdot n_y = 10,000 - 100,000$  pixels  
**b**  $c = 10,000 - 100,000$   $m/z$ -values  
**b**  $10^8 - 10^{10}$  values, altogether  
Write  $X \in \mathbb{R}^{n \times c}_+$ ,  $n = n_x \cdot n_y$ .

#### (General) Questions:

- $\rightsquigarrow$  How to interpret the data?
- → What is the *main* information?
- $\rightsquigarrow$  How to compress the data?
- $\rightsquigarrow$  Where to compress the data?





## **Compression perspectives**

Mass spectrometry data  $X \in \mathbb{R}^{n \times c}_+$  is typically large!

Nonnegative matrix factorization

 $X \approx MS$ ,

where  $M \in \mathbb{R}^{n \times \rho}_+$  and  $S \in \mathbb{R}^{\rho \times c}_+$  with  $\rho \ll \min\{n, c\}$ .

 $\rightsquigarrow \min_{M,S} \alpha \Theta_1(M) + \beta \Theta_2(S) \quad \text{s.t.} \quad \|X - MS\|_F \leq \varepsilon$ 

M – pseudo m/z-images, S – pseudo spectra
Compressed Sensing

$$Y = \Phi X \in \mathbb{R}^{m \times c}_+,$$

where 
$$\Phi \in \mathbb{R}^{m \times n}_+, m \ll n$$
.

$$\rightsquigarrow \min_{X} \alpha \Theta_1(X) + \beta \Theta_2(X) \quad \text{s.t.} \quad \|Y - \Phi X\|_F \leq \varepsilon$$

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# **Compressed Sensing in IMS**

Problems:

- MALDI measurements require several hours in time
- Data interpretation on full data

Example: Rat brain dataset  $\sim$  5 hours

Idea: Make use of compressed sensing with the knowledge of

- sparse m/z-spectra ( $\ell_1$  minimization) and
- sparse *m*/*z*-images (TV minimization)







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- sparse *m*/*z*-images (TV minimization)

 A.B., P. Dülk, D. Trede, T. Alexandrov and P. Maaß, "Compressed Sensing in Imaging Mass Spectrometry", *Inverse Problems*, **29**(12), 125015 (24pp), 2013.

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## CS-IMS model - The data

IMS data is a hyperspectral data cube consisting of  $n_x \cdot n_y$  (m/z-)spectra of length c (number of channels), whereas  $n_x$  and  $n_y$  are the number of pixels in each coordinate direction. Thus,

 $X \in \mathbb{R}^{n_x \times n_y \times c}_+.$ 

Concatenating each m/z-image as a vector the data X becomes

 $X \in \mathbb{R}^{n \times c}_+,$ 

where  $n := n_x \cdot n_y$ .

Each *column* corresponds to one m/z-image Each *row* to one m/z-spectrum.

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#### Sparsity in IMS data - m/z-spectra



Sparsity of the *spectra* in a basis  $\Psi \in \mathbb{R}^{c \times c}_+$ 

- Only a few peaks arise with high intensities
- $\implies$  Feature extraction via  $\ell_1$  minimization [Denis *et al.*'09]
- Shifted Gaussians:  $\psi_k(x) = \frac{1}{\pi^{1/4}\sigma^{1/2}} \exp\left(-\frac{(x-k)^2}{2\sigma^2}\right)$ , k = 1, ..., c



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### Sparsity in IMS data - m/z-spectra

Let  $X_{(k,\cdot)}^T \in \mathbb{R}_+^c$ , k = 1, ..., n, be the *k*-th row of  $X \in \mathbb{R}_+^{n \times c}$ , i.e. one spectrum. We assume the spectra to be *sparse* or *compressible* in a (known) basis  $\Psi \in \mathbb{R}_+^{c \times c}$ , i.e.

$$X_{(k,\cdot)}^{\mathcal{T}} = \Psi \lambda, \quad \lambda \in \mathbb{R}_{+}^{c}$$
(1)

at which  $\|\lambda\|_0 \ll c$ . With coefficient matrix  $\Lambda \in \mathbb{R}^{c \times n}_+$ , Eq. (1) reads

$$X^T = \Psi \Lambda$$

 $\implies$  Minimize *columns*  $\Lambda_{(\cdot,k)}$  of  $\Lambda$  w.r.t. the  $\ell_0$  'norm', i.e.

$$\|\Lambda_{(\cdot,k)}\|_0$$
 for  $k = 1, \ldots, n$ .

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## Sparsity in IMS data - m/z-spectra

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$$X^T = \Psi \Lambda$$

 $\implies$  Minimize *columns*  $\Lambda_{(\cdot,k)}$  of  $\Lambda$  w.r.t. the  $\ell_1$  'norm', i.e.

$$\|\Lambda_{(\cdot,k)}\|_1$$
 for  $k = 1, \ldots, n$ .

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## Sparsity in IMS data - m/z-images

Sparsity of the m/z-images



[Alexandrov et al.'10]:

m/z-images of imaging mass spectrometry data usually

- inherent large variance of noise
- are piecewise constant
- $\implies$  Apply TV denoising on each m/z-image.

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#### Sparsity in IMS data - m/z-images

Recall that  $\Lambda \in \mathbb{R}^{c \times n}_+$  is the coefficient matrix in  $X^T = \Psi \Lambda$ .  $\implies$  Minimize rows  $\Lambda_{(k,\cdot)}$  of  $\Lambda$  w.r.t. the *TV* norm, i.e.

$$\|\Lambda_{(j,\cdot)}\|_{TV}$$
 for  $j=1,\ldots,c.$ 



Instead of finding a reconstruction  $\tilde{X}^T = \Psi \tilde{\Lambda}$ , we aim to directly recover the *features*  $\tilde{\Lambda}$ .

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#### The compressed sensing process

*IMS data*  $X \in \mathbb{R}^{n \times c}_+$  *acquisition:* lonizing the given sample on each of the *n* pixels on a predefined grid







#### The compressed sensing process

*IMS data*  $X \in \mathbb{R}^{n \times c}_+$  *acquisition:* lonizing the given sample on each of the *n* pixels on a predefined grid  $\rightsquigarrow$  *Compressed sensing:*  $m \ll n$ .







#### The compressed sensing process

*IMS data*  $X \in \mathbb{R}^{n \times c}_+$  *acquisition:* lonizing the given sample on each of the *n* pixels on a predefined grid  $\rightsquigarrow$  *Compressed sensing:*  $m \ll n$ .

Take *m* measurements  $y_i \in \mathbb{R}^c_+$ , i = 1, ..., m:

$$y_{ij} = \langle \varphi_i, X_{(\cdot,j)} \rangle, \quad j = 1, .., c, \quad \varphi_i \in \mathbb{R}^n_+,$$

 $\varphi_i$  from sub-gaussian distribution

Each  $y_i$  for i = 1, ..., m is a *measurement-mean spectrum* since it is calculated by the mean intensities on each channel:

$$y_i^T = \varphi_i^T X = \sum_{k=1}^n \varphi_{ik} X_{(k,\cdot)},$$

 $\rightsquigarrow y_i^T$  are linear combinations of the original spectra  $X_{(k,\cdot)}$ , k = 1, ..., n.

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# **CS-IMS** model

*CS in IMS data acquisition:* Ionizing the given sample on randomly selected pixels on a predefined grid.





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#### **Theorem: Robustness**

A.B., P.Dülk, D.Trede, T.Alexandrov and P.Maaß, "CS in IMS", Inverse Problems, 29(12), 125015 (24pp), 2013.

Let  $\mathcal{M}: \mathbb{R}^{c \times n} \to \mathbb{R}^{4cm_1} \times \mathbb{R}^{m_2 \times c}$  be the linear operator with components

$$\mathcal{M}(\Lambda) = \left(\mathcal{A}^{0}\Lambda_{1}, \mathcal{A}_{0}\Lambda_{1}, \mathcal{A}'^{0}\Lambda_{1}, \mathcal{A}'_{0}\Lambda_{1}, \dots, \mathcal{A}^{0}\Lambda_{c}, \mathcal{A}_{0}\Lambda_{c}, \mathcal{A}'^{0}\Lambda_{c}, \mathcal{A}'_{0}\Lambda_{c}, \Phi\Lambda^{T}\Psi^{T}\right).$$

If noisy measurements  $Y = \mathcal{M}(\Lambda) + Z$  are observed with noise level  $\|Z\|_F \leq \varepsilon$ , then

$$\Lambda^{\diamond} = \operatorname*{argmin}_{W \in \mathbb{R}^{c \times n}} \|W\|_1 + \sum_{i=1}^{c} \|W_i\|_{TV} \quad \text{s.t.} \quad \|\mathcal{M}(W) - Y\|_F \leq \varepsilon$$

satisfies both

$$\|\Lambda - \Lambda^{\diamond}\|_{F} + \sum_{i=1}^{c} \|\nabla\Lambda_{i} - \nabla\Lambda_{i}^{\diamond}\|_{F} \lesssim \frac{1}{\sqrt{K}} \left(\|\Lambda - \Lambda_{S_{0}}\|_{1} + \sum_{i=1}^{c} \left\|\nabla\Lambda_{i} - (\nabla\Lambda_{i})_{S_{i}}\right\|_{1}\right) + \varepsilon,$$

and

$$\|\Lambda - \Lambda^{\diamond}\|_{1} + \sum_{i=1}^{c} \|\Lambda_{i} - \Lambda_{i}^{\diamond}\|_{\mathcal{T}V} \lesssim \|\Lambda - \Lambda_{S_{0}}\|_{1} + \sum_{i=1}^{c} \left\|\nabla\Lambda_{i} - (\nabla\Lambda_{i})_{S_{i}}\right\|_{1} + \sqrt{\mathcal{K}}\varepsilon.$$

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#### **Theorem: Robustness - The tools**

#### 1. RIP

The linear operator  $\mathcal{A} : \mathbb{R}^{n_x \times n_y} \to \mathbb{R}^{m \times p}$  has the *restricted* isometry property of order s and level  $\delta \in (0, 1)$  if

$$(1-\delta)\|X\|_F^2 \le \|\mathcal{A}(X)\|_F^2 \le (1+\delta)\|X\|_F^2$$

for all *s*-sparse  $X \in \mathbb{R}^{n_x \times n_y}$ .

 D-RIP (extends the RIP to matrices adapted to a dictionary) A linear operator A : ℝ<sup>n<sub>x</sub>×n<sub>y</sub></sup> → ℝ<sup>m×p</sup> has the D-RIP of order s and level δ\* ∈ (0,1), adapted to a dictionary D, if for all s-sparse X ∈ ℝ<sup>n<sub>x</sub>×n<sub>y</sub></sup> it holds

$$(1-\delta^*)\|DX\|_F^2 \le \|\mathcal{A}(DX)\|_F^2 \le (1+\delta^*)\|DX\|_F^2.$$

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#### **Theorem: Robustness - The tools**

#### 3. A-RIP

A matrix  $D \in \mathbb{R}^{n_x \times n_x}$  satisfies the *asymmetric restricted isometry property* (A-RIP), if for all *s*-sparse  $X \in \mathbb{R}^{n_x \times n_y}$  the following inequalities hold:

$$\mathcal{L}(D)\|X\|_{\mathsf{F}} \leq \|DX\|_{\mathsf{F}} \leq \mathcal{U}(D)\|X\|_{\mathsf{F}},$$

where  $\mathcal{L}(D)$  and  $\mathcal{U}(D)$  are the largest and the smallest constants for which the above inequalities hold. The restricted condition number of D is defined as

$$\xi(D) = \frac{\mathcal{U}(D)}{\mathcal{L}(D)} \le \frac{\max_{\|X\|_F=1} \|DX\|_F}{\min_{\|X\|_F=1} \|DX\|_F} = \kappa(D).$$

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#### **Theorem: Robustness - The tools**

$$\min_{\Lambda \in \mathbb{R}^{c \times n}} \sum_{j=1}^{c} \|\Lambda_{(j,\cdot)}\|_{TV} + \|\Lambda\|_{1}, \quad \text{s.t.} \quad \|Y - \underbrace{\Phi \Lambda^{T} \Psi^{T}}_{=:\mathcal{D}_{\Phi,\Psi} \Lambda} \|_{F} \le \varepsilon, \quad \Lambda \ge 0$$

#### Argue that

**D** $_{\Phi,\Psi}$  fulfils the D-RIP

Argument via Kronecker product and blockdiagonal RIP results [Eftekhari, A, *et al.*'12]

 $\Psi$  will consist of shifted Gaussians

 $\rightsquigarrow \Psi$  is invertible, i.e.  $\xi(\Psi)$  is bounded by  $\kappa(\Psi)$ 

$$\mathbf{B} = [\mathcal{A} \ \mathcal{A}', \dots, \mathcal{A} \ \mathcal{A}']$$

(operator with artificial gradient measurements) fulfils the RIP Argument similar as for  $\mathcal{D}_{\Phi,\Psi}$ .

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# Algorithm (PPXA)

We aim to solve the following problem

$$\min_{\Lambda \in \mathbb{R}^{c \times n}} \alpha \sum_{j=1}^{c} \|\Lambda_{(j,\cdot)}\|_{TV} + \beta \|\Lambda\|_{1}, \quad \text{s.t.} \quad \|Y - \Phi \Lambda^{T} \Psi^{T}\|_{F} \leq \varepsilon, \quad \Lambda \geq 0.$$

We use the *parallel proximal splitting algorithm* (PPXA) [Combettes&Pesquet'08] which solves problems of the kind:

$$\min_{x\in\mathcal{H}}\sum_{i=1}^{\ell}f_i(x),$$

where

- $\blacksquare \ \mathcal{H}$  is a Hilbert space and
- $(f_i)_{1 \le i \le \ell}$  are proper lower semicontinuous convex functions  $f_i : \mathcal{H} \to ] \infty, +\infty]$

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# Algorithm (PPXA)

Here: 
$$\mathcal{H} = \mathbb{R}^{c \times n}$$
,  $\ell = 4$  and  
 $f_1(\Lambda) = \alpha \sum_{i=1}^{c} \|\Lambda_i\|_{TV}, \qquad f_2(\Lambda) = \beta \|\Lambda\|_1,$   
 $f_3(\Lambda) = \iota_{\mathcal{B}_2^c}(\Lambda), \qquad f_4(\Lambda) = \iota_{\mathcal{B}_+}(\Lambda).$ 

 $\iota_{\mathcal{C}}$  is the indicator function,

$$u_{\mathcal{C}}(\Lambda) = egin{cases} 0 & ext{if } \Lambda \in \mathcal{C} \ +\infty & ext{otherwise} \end{cases},$$

applied to the convex sets

$$\begin{aligned} \mathcal{B}_2^{\varepsilon} &= \{A \in \mathbb{R}^{c \times n} : \|Y - \mathcal{D}_{\Phi, \Psi}A\|_F \leq \varepsilon\} \ \text{(Fidelity constraint)}, \\ \mathcal{B}_+ &= \{A \in \mathbb{R}^{c \times n} : A \geq 0\} \ \text{(Positive orthant)}. \end{aligned}$$

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## The proximity operator...

... is defined as

$$\mathsf{prox}_f:\mathcal{H}\to\mathcal{H}.$$

 $\operatorname{prox}_f(X)$  is the unique point in  $\mathcal{H}$  that satisfies

$$\operatorname{prox}_{f}(X) = \operatorname{argmin}_{Y \in \mathcal{H}} \frac{1}{2} \|X - Y\|_{F}^{2} + f(Y).$$

For  $f_1$  (TV-norm): Via an implementation from [Beck'09]. For  $f_2$  (1-norm):  $\operatorname{prox}_{\gamma \parallel \cdot \parallel_1}(Z) = \left( \max \left\{ 0, \left( 1 - \frac{\gamma}{|Z_{i,j}|} \right) \right\} Z_{i,j} \right)_{\substack{1 \leq i \leq c \\ 1 \leq j \leq n}}$ For  $f_3$  ( $\mathcal{B}_2^{\varepsilon}$ ): Via a Douglas-Rachford splitting scheme [Fadili'09] For  $f_4$  ( $\mathcal{B}_+$ ):  $\operatorname{prox}_{\gamma \iota_{\mathcal{B}_+}(\cdot)}(Z) = \left( \max\{0, Z_{i,j}\} \right)_{\substack{1 \leq i \leq c \\ 1 \leq j \leq n}}$ 

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## Parallel proximal splitting algorithm

Algorithm 1: PPXA

Input:  $Y, \Psi, \Phi, \alpha, \beta, \varepsilon, \gamma > 0$ Initializations: k = 0;  $\Lambda_0 = \Gamma_{1,0} = \Gamma_{2,0} = \Gamma_{3,0} = \Gamma_{4,0} \in \mathbb{R}^{c \times n}$  repeat

for 
$$j = 1 : 4$$
 do  
 $[P_{j,k} = \text{prox}_{\gamma f_j}(\Gamma_{j,k})]$   
 $\Lambda_{k+1} = (P_{1,k} + P_{2,k} + P_{3,k} + P_{4,k})/4$   
for  $j = 1 : 4$  do  
 $[\Gamma_{j,k+1} = \Gamma_{j,k} + 2\Theta_{k+1} - \Theta_k - P_{j,k}]$ 

until convergence

Implementations given in the UNLocBoX [Perraudin'14].

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## Test-Setting - Rat brain dataset

Part of a rat brain dataset:  $X \in \mathbb{R}^{n \times c}_+$ ,  $n = 121 \cdot 202$ , c = 2,000.

Assume mass spectra to be sparse in a basis  $\Psi$  consisting of shifted Gaussians [Denis *et al.*'09]

$$\psi_k(x) = rac{1}{\pi^{1/4}\sigma^{1/2}}\exp\left(-rac{(x-k)^2}{2\sigma^2}
ight)$$

Choose std. deviation of  $\Psi_k(x)$ 

- consistent with the data and
- such that the condition  $\kappa(\Psi)$  is small

 $\rightsquigarrow \sigma = 0.75.$ 

Elements of measurement matrix  $\Phi \in \mathbb{R}^{r \times n}$   $(r \ll n)$  chosen at random from an i.i.d. Gaussian distribution.

Noise level  $\varepsilon = 3.75 \times 10^3$ . Parameters  $\alpha, \beta$  set by hand.

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#### **Reconstructed mean spectrum**





## **Reconstructed** m/z-image



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## **Reconstructed** m/z-image - Cont.



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## Reconstructed m/z-image



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# **Others?**

Are there similar results for other MS systems?

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# **Others?**

Are there similar results for other MS systems?

 $\rightsquigarrow$  Yes!

Gao, Y., Zhu, L., Norton, I., Agar, N. Y. R., Tannenbaum, A. *Reconstruction and feature selection for desorption electrospray ionization mass spectroscopy imagery* Proc. SPIE 9036, Medical Imaging 2014, March 12, 2014. (DESI)

From the abstract:

"... time it takes for imaging and data analysis becomes a critical factor. Therefore, [...] we utilize compressive sensing to perform the sparse sampling of the tissue, which halves the scanning time."

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# Conclusions

- First model for compressed sensing in MALDI-IMS
- Reconstruction of whole dataset w.r.t. its features
- Robustness of reconstruction with respect to noise
  - combines  $\ell_1$  and TV
  - includes two sparsity aspects

# **Future Prospects**

- How to chose regularization parameters  $\alpha$  and  $\beta$ ?
- Noise models (e.g. Poisson noise, etc.)
- Numerics (alternating minimization, surrogate functionals)
- Include sparse representation

 $X \approx MS, \qquad M \in \mathbb{R}^{m imes \rho}_+, \qquad S \in \mathbb{R}^{\rho imes n}_+$ M – Matrix with m/z-images, S – Matrix with pseudo spectra

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#### **Outlook - Nonnegative matrix factorization**



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# Working group



# Thank you! bartels@math.uni-bremen.de

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