

# Sobol-Hoeffding Decomposition with Application to Global Sensitivity Analysis

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**UTOPIÆ** Uncertainty  
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## $L_2$ functions over unit-hypercubes

Let  $L_2(\mathcal{U}^d)$  be the space of real-valued **squared-integrable functions** over the  $d$ -dimensional hypercube  $\mathcal{U}$ :

$$f : \mathbf{x} \in \mathcal{U}^d \mapsto f(\mathbf{x}) \in \mathbb{R}, \quad f \in L_2(\mathcal{U}^d) \Leftrightarrow \int_{\mathcal{U}^d} f(\mathbf{x})^2 d\mathbf{x} < \infty.$$

$L_2(\mathcal{U}^d)$  is equipped with the inner product  $\langle \cdot, \cdot \rangle$ ,

$$\forall f, g \in L_2(\mathcal{U}^d), \quad \langle u, v \rangle := \int_{\mathcal{U}^d} f(\mathbf{x})g(\mathbf{x})d\mathbf{x},$$

and norm  $\| \cdot \|_2$ ,

$$\forall f \in L_2(\mathcal{U}^d), \quad \|f\|_2 := \langle f, f \rangle^{1/2}.$$

## $L_2$ functions over unit-hypercubes

Let  $L_2(\mathcal{U}^d)$  be the space of real-valued **squared-integrable functions** over the  $d$ -dimensional hypercube  $\mathcal{U}$ :

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**NB:** all subsequent developments immediately extend to product-type situations, where

$$\mathbf{x} \in A = A_1 \times \cdots \times A_d \subseteq \mathbb{R}^d,$$

and weighted spaces  $L_2(A, \rho)$ ,

$$\rho : \mathbf{x} \in A \mapsto \rho(\mathbf{x}) \geq 0, \quad \rho(\mathbf{x}) = \rho_1(x_1) \times \cdots \times \rho_d(x_d).$$

(e.g.:  $\rho$  is a pdf of a random vector  $\mathbf{x}$  with mutually independent components.)

## Ensemble notations

Let  $\mathcal{D} = \{1, 2, \dots, d\}$ .

Given  $i \subseteq \mathcal{D}$ , we denote  $i_{\sim} := \mathcal{D} \setminus i$  **its complement set in  $\mathcal{D}$** , such that

$$i \cup i_{\sim} = \mathcal{D}, \quad i \cap i_{\sim} = \emptyset.$$

For instance

- $i = \{1, 2\}$  and  $i_{\sim} = \{3, \dots, d\}$ ,
- $i = \mathcal{D}$  and  $i_{\sim} = \emptyset$ .

## Ensemble notations

Let  $\mathcal{D} = \{1, 2, \dots, d\}$ .

Given  $i \subseteq \mathcal{D}$ , we denote  $i_{\sim} := \mathcal{D} \setminus i$  **its complement set in  $\mathcal{D}$** , such that

$$i \cup i_{\sim} = \mathcal{D}, \quad i \cap i_{\sim} = \emptyset.$$

Given  $\mathbf{x} = (x_1, \dots, x_d)$ , we denote  $\mathbf{x}_i$  the vector having for components the  $x_{i \in i}$ , that is

$$\mathcal{D} \supseteq i = \{i_1, \dots, i_{|i|}\} \Rightarrow \mathbf{x}_i = (x_{i_1}, \dots, x_{i_{|i|}}),$$

where  $|i| := \text{Card}(i)$ . For instance

$$\int_{\mathcal{U}^{|i|}} f(\mathbf{x}) d\mathbf{x}_i = \int_{\mathcal{U}^{|i|}} f(x_1, \dots, x_d) \prod_{i \in i} dx_i,$$

and

$$\int_{\mathcal{U}^{d-|i|}} f(\mathbf{x}) d\mathbf{x}_{i_{\sim}} = \int_{\mathcal{U}^{d-|i|}} f(x_1, \dots, x_d) \prod_{i \in \mathcal{D}}^{i \notin i} dx_i,$$

## Sobol-Hoeffding decomposition

Any  $f \in L_2(\mathcal{U}^d)$  has a **unique hierarchical orthogonal decomposition** of the form

$$f(\mathbf{x}) = f(x_1, \dots, x_d) = f_0 + \sum_{i=1}^d f_i(x_i) + \sum_{i=1}^d \sum_{j=i+1}^d f_{i,j}(x_i, x_j) + \sum_{i=1}^d \sum_{j=i+1}^d \sum_{k=j+1}^d f_{i,j,k}(x_i, x_j, x_k) + \dots + f_{1,\dots,d}(x_1, \dots, x_d).$$

**Hierarchical:** 1st order functionals ( $f_i$ )  $\rightarrow$  2nd order functionals ( $f_{i,j}$ )  $\rightarrow$  3rd order functionals ( $f_{i,j,l}$ )  $\rightarrow \dots \rightarrow d$ -th order functional ( $f_{1,\dots,d}$ ).

### Decomposition in a sum of $2^k$ functionals

**Using ensemble notations:**

$$f(\mathbf{x}) = \sum_{\mathbf{i} \subseteq \mathcal{D}} f_{\mathbf{i}}(\mathbf{x}_{\mathbf{i}}).$$

## Sobol-Hoeffding decomposition

Any  $f \in L_2(\mathcal{U}^d)$  has a **unique hierarchical orthogonal decomposition** of the form

$$f(\mathbf{x}) = \sum_{i \subseteq \mathcal{D}} f_i(\mathbf{x}_i).$$

**Orthogonal:** the functionals if the S-H decomposition verify the following orthogonality relations:

$$\int_{\mathcal{U}} f_i(\mathbf{x}_i) dx_j = 0, \quad \forall i \subseteq \mathcal{D}, j \in i,$$

$$\int_{\mathcal{U}^d} f_i(\mathbf{x}_i) f_j(\mathbf{x}_j) d\mathbf{x} = \langle f_i, f_j \rangle = 0, \quad \forall i, j \subseteq \mathcal{D}, i \neq j.$$

It follows the hierarchical construction

$$f_\emptyset = \int_{\mathcal{U}^d} f(\mathbf{x}) d\mathbf{x} = \langle f \rangle_{\emptyset \sim \mathcal{D}}$$

$$f_{\{i\}} = \int_{\mathcal{U}^{d-1}} f(\mathbf{x}) d\mathbf{x}_{\{i\}^c} - f_\emptyset = \langle f \rangle_{\mathcal{D} \setminus \{i\}} - f_\emptyset \quad i \in \mathcal{D}$$

$$f_i = \int_{\mathcal{U}^{|\mathcal{D} \setminus i|}} f(\mathbf{x}) d\mathbf{x}_{\mathcal{D} \setminus i} - \sum_{j \subsetneq i} f_j = \langle f \rangle_{i \sim \mathcal{D}} - \sum_{j \subsetneq i} f_j \quad i \in \mathcal{D}, |i| \geq 2.$$



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## Parametric sensitivity analysis

Consider  $\mathbf{x}$  as a set of  $d$  independent random parameters uniformly distributed on  $\mathcal{U}^d$ , and  $f(\mathbf{x})$  a model-output depending on these random parameters. It is assumed that  $f$  is a 2nd order random variable:  $f \in L_2(\mathcal{U}^d)$ . Thus,  $f$  has a unique S-H decomposition

$$f(\mathbf{x}) = \sum_{i \subseteq \mathcal{D}} f_i(\mathbf{x}_i).$$

Further, the integrals of  $f$  with respect to  $i_{\sim}$  are in this context conditional expectations,

$$\mathbb{E}[f|\mathbf{x}_i] = \int_{\mathcal{U}^{|\mathcal{D}|-|i|}} f(\mathbf{x}) d\mathbf{x}_{i_{\sim}} = g(\mathbf{x}_i) \quad \forall i \subseteq \mathcal{D},$$

so the S-H decomposition follows the hierarchical structure

$$\begin{aligned} f_{\emptyset} &= \mathbb{E}[f] \\ f_{\{i\}} &= \mathbb{E}[f|\mathbf{x}_{\{i\}}] - \mathbb{E}[f] && i \in \mathcal{D} \\ f_i &= \mathbb{E}[f|\mathbf{x}_i] - \sum_{j \subsetneq i} f_j && i \subseteq \mathcal{D}, |i| \geq 2. \end{aligned}$$

## Variance decomposition

Because of the orthogonality of the S-H decomposition the variance  $\mathbb{V}[f]$  of the model-output can be decomposed as

$$\mathbb{V}[f] = \sum_{\substack{i \neq \emptyset \\ i \subseteq \mathcal{D}}} \mathbb{V}[f_i], \quad \mathbb{V}[f_i] = \langle f_i, f_i \rangle.$$

$\mathbb{V}[f_i]$  is interpreted as the contribution to the total variance  $\mathbb{V}[f]$  of the interaction between parameters  $x_{i \in i}$ .

The S-H decomposition thus provide a rich mean of analyzing the respective contributions of individual or sets of parameters to model-output variability. However, as there are  $2^d - 1$  contributions, so one needs more "abstract" characterizations.

## Sensitivity indices

To facilitate the hierarchization of the respective influence of each parameter  $x_i$ , the partial variances  $\mathbb{V}[f_i]$  are normalized by  $\mathbb{V}[f]$  to obtain the **sensitivity indices**:

$$S_i(f) = \frac{\mathbb{V}[f_i]}{\mathbb{V}[f]} \leq 1, \quad \sum_{i \subseteq \mathcal{D}} S_i(f) = 1.$$

The **order of the sensitivity indices**  $S_i$  is equal to  $|i| = \text{Card}(i)$ .

**1st order sensitivity indices.** The  $d$  **first order indices**  $S_{\{i\} \in \mathcal{D}}$  characterize the **fraction of the variance due the parameter  $x_i$  only**, *i.e.* **without any interaction with others**. Therefore,

$$1 - \sum_{i=1}^d S_{\{i\}}(f) \geq 0,$$

measures globally the effect on the variability of all interactions between parameters. **If  $\sum_{i=1}^d S_{\{i\}} = 1$ , the model is said additive**, because its S-H decomposition is

$$f(x_1, \dots, x_d) = f_0 + \sum_{i=1}^d f_i(x_i),$$

and the impact of the parameters can be studied separately.

## Sensitivity indices

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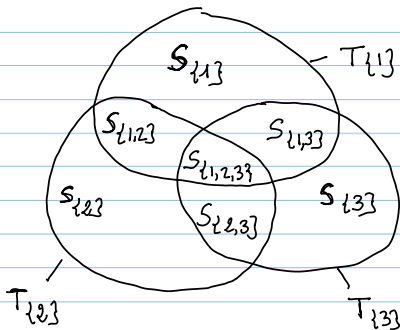
**Total sensitivity indices.** The first order SI  $S_{\{i\}}$  measures the variability due to parameter  $x_i$  alone. The **total SI  $T_{\{i\}}$  measures the variability due to the parameter  $x_i$ , including all its interactions** with other parameters:

$$T_{\{i\}} := \sum_{i \ni j} S_j \geq S_{\{i\}}.$$

**Important point:** for  $x_i$  to be deemed non-important or non-influent on the model-output,  $S_{\{i\}}$  and  $T_{\{i\}}$  have to be negligible.

Observe that  $\sum_{i \in \mathcal{D}} T_{\{i\}} \geq 1$ , the excess from 1 **characterizes the presence of interactions** in the model-output.

## Sensitivity indices



Case of  $d=3$ .

$$\sum S_i = 1$$

$$\sum S_{\{i,j\}} \leq 1$$

$$\sum T_{\{i,j\}} \geq 1$$

## Sensitivity indices

In many uncertainty problem, the **set of uncertain parameters can be naturally grouped into subsets** depending on the process each parameter accounts for. For instance, boundary conditions BC, material property  $\varphi$ , external forcing  $F$ , and  $\mathcal{D}$  is the union of these distinct subsets:

$$\mathcal{D} = \mathcal{D}_{BC} \cup \mathcal{D}_{\varphi} \cup \mathcal{D}_F.$$

The notion of **first order and total sensitivity indices can be extended to characterize the influence of the subsets of parameters**. For instance,

$$S_{\mathcal{D}_{\varphi}} = \sum_{i \subseteq \mathcal{D}_{\varphi}} S_i,$$

measures the fraction of variance induced by the material uncertainty alone, while

$$T_{\mathcal{D}_F} = \sum_{i \cap \mathcal{D}_F \neq \emptyset} S_i.$$

measures the fraction of variance due to the external forcing uncertainty and all its interactions.

## Example

Let  $(\xi_1, \xi_2)$  be two independent centered, normalized random variables

$$\xi_i \sim N(0, 1), \quad i = 1, 2.$$

Consider the model-output  $f : (\xi_1, \xi_2) \in \mathbb{R}^2 \mapsto \mathbb{R}$  given by

$$f(\xi_1, \xi_2) = (\mu_1 + \sigma_1 \xi_1) + (\mu_2 + \sigma_2 \xi_2).$$

- 1 Determine the S-H decomposition of  $f$
- 2 Compute the 1st order and total sensitivity indices of  $f$
- 3 Comment
- 4 Repeat for  $f(\xi_1, \xi_2) = (\mu_1 + \sigma_1 \xi_1) (\mu_2 + \sigma_2 \xi_2)$ .



## Example

$$f(\xi_1, \xi_2) = \mu_1 + \mu_2 + \sigma_1 \xi_1 + \sigma_2 \xi_2$$

- $\mathbb{E}[f] = (\mu_1 + \mu_2)$
- $\mathbb{E}[f|\xi_1] = (\mu_1 + \mu_2) + \sigma_1 \xi_1$   
 $\Rightarrow f_1(\xi_1) = \mathbb{E}[f|\xi_1] - \mathbb{E}[f] = \sigma_1 \xi_1$
- $\mathbb{E}[f|\xi_2] = (\mu_1 + \mu_2) + \sigma_2 \xi_2$   
 $\Rightarrow f_2(\xi_2) = \mathbb{E}[f|\xi_2] - \mathbb{E}[f] = \sigma_2 \xi_2$
- $\mathbb{E}[f|\xi_1, \xi_2] = f(\xi_1, \xi_2)$   
 $\Rightarrow f_{1,2}(\xi_1, \xi_2) = \mathbb{E}[f|\xi_1, \xi_2] - \mathbb{E}[f] - f_1(\xi_1) - f_2(\xi_2) = 0$
- Then,  $\mathbb{V}[f] = \sigma_1^2 + \sigma_2^2$ , so

$$S_1 = T_1 = \frac{\sigma_1^2}{\sigma_1^2 + \sigma_2^2} \text{ and } S_2 = T_2 = \frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2}$$

- Comment: obvious case, as  $f$  is a linear (additive) model.

## Example

$$f(\xi_1, \xi_2) = \mu_1\mu_2 + \mu_2\sigma_1\xi_1 + \mu_1\sigma_2\xi_2 + \sigma_1\sigma_2\xi_1\xi_2.$$

- $\mathbb{E}[f] = \mu_1\mu_2$
- $\mathbb{E}[f|\xi_1] = \mu_1\mu_2 + \mu_2\sigma_1\xi_1$   
 $\Rightarrow f_1(\xi_1) = \mathbb{E}[f|\xi_1] - \mathbb{E}[f] = \mu_2\sigma_1\xi_1$
- $\mathbb{E}[f|\xi_2] = \mu_1\mu_2 + \mu_1\sigma_2\xi_2$   
 $\Rightarrow f_2(\xi_2) = \mathbb{E}[f|\xi_2] - \mathbb{E}[f] = \mu_1\sigma_2\xi_2$
- $\mathbb{E}[f|\xi_1, \xi_2] = f(\xi_1, \xi_2)$   
 $\Rightarrow f_{1,2}(\xi_1, \xi_2) = \mathbb{E}[f|\xi_1, \xi_2] - \mathbb{E}[f] - f_1(\xi_1) - f_2(\xi_2) = \sigma_1\sigma_2\xi_1\xi_2$
- Then,  $\mathbb{V}[f] = \mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2$ , so

$$S_1 = \frac{\mu_2^2\sigma_1^2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2} \text{ and } S_2 = \frac{\mu_1^2\sigma_2^2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2},$$

$$T_1 = \frac{\mu_2^2\sigma_1^2 + \sigma_1\sigma_2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2} \text{ and } T_2 = \frac{\mu_1^2\sigma_2^2 + \sigma_1\sigma_2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2},$$

- Comment: fraction of variance due to interactions is

$$\sigma_1^2\sigma_2^2/(\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2)$$

## Example

$$f(\xi_1, \xi_2) = \mu_1\mu_2 + \mu_2\sigma_1\xi_1 + \mu_1\sigma_2\xi_2 + \sigma_1\sigma_2\xi_1\xi_2.$$

- Then,  $\mathbb{V}[f] = \mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2$ , so

$$S_1 = \frac{\mu_2^2\sigma_1^2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2} \text{ and } S_2 = \frac{\mu_1^2\sigma_2^2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2},$$

$$T_1 = \frac{\mu_2^2\sigma_1^2 + \sigma_1\sigma_2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2} \text{ and } T_2 = \frac{\mu_1^2\sigma_2^2 + \sigma_1\sigma_2}{\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2},$$

- Comment: fraction of variance due to interactions is

$$\sigma_1^2\sigma_2^2/(\mu_1^2\sigma_2^2 + \mu_2^2\sigma_1^2 + \sigma_1^2\sigma_2^2)$$

- Example:  $(\mu_1, \sigma_1) = (1, 3)$  and  $(\mu_2, \sigma_2) = (2, 2)$ , so

$$S_1 = 9/19, \quad S_2 = 1/19, \quad S_{1,2} = 9/19.$$

One can draw the conclusions:

- $\xi_1$  is the most influential variable as  $S_1 > S_2$  and  $T_1 > T_2$ .
- interactions are important as  $1 - S_1 - S_2 = 9/19 \approx 0.5$ , especially for  $\xi_2$  for which  $(T_2 - S_2)/T_2 = 9/10 \approx 1$ .

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## 1-st order sensitivity indices by Monte-Carlo sampling.

The  $S_i$  can be computed by MC sampling as follow. Recall that

$$S_{\{i\}}(f) = \frac{\mathbb{V}[f_{\{i\}}]}{\mathbb{V}[f]} = \frac{\mathbb{V}[\mathbb{E}[f|x_i]]}{\mathbb{V}[f]} = \frac{\mathbb{E}[\mathbb{E}[f|x_i]^2] - \mathbb{E}[\mathbb{E}[f|x_i]]^2}{\mathbb{V}[f]}.$$

**Observe:**  $\mathbb{E}[\mathbb{E}[f|x_i]] = \mathbb{E}[f]$ .

$\mathbb{E}[f]$  and  $\mathbb{V}[f]$  can be **estimated using MC sampling**.

Let  $\chi_M = \{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)}\}$  be a set of **independent samples drawn uniformly** in  $\mathcal{U}^d$ , the **mean and variance estimators** are:

$$\widehat{\mathbb{E}[f]} = \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}^{(l)}), \quad \widehat{\mathbb{V}[f]} = \frac{1}{M-1} \sum_{l=1}^M f(\mathbf{x}^{(l)})^2 - \widehat{\mathbb{E}[f]}^2.$$

It now remains to compute the variance of conditional expectations,  $\mathbb{V}[\mathbb{E}[f|\mathbf{x}_{\{i\}}]]$ .

**Any idea?**

## Monte-Carlo estimator for variance of conditional expectation.

Observe:

$$\begin{aligned}
 & \int_{\mathcal{U}^{d+|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}_{i_{\sim}}) f(\mathbf{x}_i, \mathbf{x}'_{i_{\sim}}) d\mathbf{x}_i d\mathbf{x}_{i_{\sim}} d\mathbf{x}'_{i_{\sim}} \\
 &= \int_{\mathcal{U}^{|i|}} d\mathbf{x}_i \int_{\mathcal{U}^{|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}_{i_{\sim}}) d\mathbf{x}_{i_{\sim}} \int_{\mathcal{U}^{|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}'_{i_{\sim}}) d\mathbf{x}'_{i_{\sim}} \\
 &= \int_{\mathcal{U}^{|i|}} d\mathbf{x}_i \left[ \int_{\mathcal{U}^{|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}_{i_{\sim}}) d\mathbf{x}_{i_{\sim}} \right]^2.
 \end{aligned}$$

## Monte-Carlo estimator for variance of conditional expectation.

Observe:

$$\begin{aligned}
 & \int_{\mathcal{U}^{d+|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}_{i_{\sim}}) f(\mathbf{x}_i, \mathbf{x}'_{i_{\sim}}) d\mathbf{x}_i d\mathbf{x}_{i_{\sim}} d\mathbf{x}'_{i_{\sim}}, \\
 &= \int_{\mathcal{U}^{|i|}} d\mathbf{x}_i \int_{\mathcal{U}^{|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}_{i_{\sim}}) d\mathbf{x}_{i_{\sim}} \int_{\mathcal{U}^{|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}'_{i_{\sim}}) d\mathbf{x}'_{i_{\sim}} \\
 &= \int_{\mathcal{U}^{|i|}} d\mathbf{x}_i \left[ \int_{\mathcal{U}^{|i_{\sim}|}} f(\mathbf{x}_i, \mathbf{x}_{i_{\sim}}) d\mathbf{x}_{i_{\sim}} \right]^2.
 \end{aligned}$$

$$\mathbb{V} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]] = \mathbb{E} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]^2] - \mathbb{E} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]]^2 = \mathbb{E} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]^2] - \mathbb{E} [f]^2$$

## Monte-Carlo estimator for variance of conditional expectation.

Observe:

$$\begin{aligned} & \int_{\mathcal{U}^{d+|i|}} f(\mathbf{x}_i, \mathbf{x}_{i\sim}) f(\mathbf{x}_i, \mathbf{x}'_{i\sim}) d\mathbf{x}_i d\mathbf{x}_{i\sim} d\mathbf{x}'_{i\sim} \\ &= \int_{\mathcal{U}^{|i|}} d\mathbf{x}_i \int_{\mathcal{U}^{|i\sim|}} f(\mathbf{x}_i, \mathbf{x}_{i\sim}) d\mathbf{x}_{i\sim} \int_{\mathcal{U}^{|i\sim|}} f(\mathbf{x}_i, \mathbf{x}'_{i\sim}) d\mathbf{x}'_{i\sim} \\ &= \int_{\mathcal{U}^{|i|}} d\mathbf{x}_i \left[ \int_{\mathcal{U}^{|i\sim|}} f(\mathbf{x}_i, \mathbf{x}_{i\sim}) d\mathbf{x}_{i\sim} \right]^2. \end{aligned}$$

$$\begin{aligned} \mathbb{V} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]] &= \mathbb{E} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]^2] - \mathbb{E} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]]^2 = \mathbb{E} [\mathbb{E} [f|\mathbf{x}_{\{i\}}]^2] - \mathbb{E} [f]^2 \\ &= \lim_{M \rightarrow \infty} \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\}\sim}^{(l)}, \mathbf{x}_{\{i\}}^{(l)}) f(\tilde{\mathbf{x}}_{\{i\}\sim}^{(l)}, \mathbf{x}_{\{i\}}^{(l)}) - \mathbb{E} [f]^2 \\ &\quad (\text{independent samples } \mathbf{x}_{\{i\}\sim}^{(l)}, \tilde{\mathbf{x}}_{\{i\}\sim}^{(l)} \text{ and } \mathbf{x}_{\{i\}}^{(k)}) \end{aligned}$$



## Monte-Carlo estimators for 1st order SI $S_{\{i\}}$ .

- ① Draw 2 independent sample sets, with size  $M$ ,  $\chi_M$  and  $\tilde{\chi}_M$
- ② Compute estimators  $\widehat{\mathbb{E}}[f]$  and  $\widehat{\mathbb{V}}[f]$  from  $\chi_M$  (or  $\tilde{\chi}_M$ ) [ $M$  model evaluations]
- ③ For  $i = 1, 2, \dots, d$ :
  - Estimate variance of conditional expectation through

$$\mathbb{V}[\widehat{\mathbb{E}}[f|\mathbf{x}_{\{i\}}]] = \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\}}^{(l)}, \mathbf{x}_{\{i\}}^{(l)}) f(\tilde{\mathbf{x}}_{\{i\}}^{(l)}, \mathbf{x}_{\{i\}}^{(l)}) - \widehat{\mathbb{E}}[f]^2$$

[ $M$  new model evaluations at  $(\tilde{\mathbf{x}}_{\{i\}}^{(l)}, \mathbf{x}_{\{i\}}^{(l)})$ ]

- Estimator of the 1-st order SI:

$$\widehat{S}_{\{i\}}(f) = \frac{\mathbb{V}[\widehat{\mathbb{E}}[f|\xi_{\{i\}}]]}{\widehat{\mathbb{V}}[f]}.$$

**Requires  $(d + 1) \times M$  model evaluations.**

## Monte-Carlo estimation

$$\mathbf{x}_M : \begin{bmatrix} x_1^{(1)} & \dots & x_i^{(1)} & \dots & x_d^{(1)} \\ \vdots & & \vdots & & \vdots \\ x_1^{(l)} & \dots & x_i^{(l)} & \dots & x_d^{(l)} \\ \vdots & & \vdots & & \vdots \\ x_1^{(M)} & \dots & x_i^{(M)} & \dots & x_d^{(M)} \end{bmatrix}$$

$$\bar{\mathbf{x}}_M : \begin{bmatrix} \bar{x}_1^{(1)} & \dots & \bar{x}_i^{(1)} & \dots & \bar{x}_d^{(1)} \\ \vdots & & \vdots & & \vdots \\ \bar{x}_1^{(l)} & \dots & \bar{x}_i^{(l)} & \dots & \bar{x}_d^{(l)} \\ \vdots & & \vdots & & \vdots \\ \bar{x}_1^{(M)} & \dots & \bar{x}_i^{(M)} & \dots & \bar{x}_d^{(M)} \end{bmatrix}$$

$$\bar{\mathbf{x}}_M^{\{i\}} : \begin{bmatrix} \bar{x}_1^{(1)} & \dots & x_i^{(1)} & \dots & \bar{x}_d^{(1)} \\ \vdots & & \vdots & & \vdots \\ \bar{x}_1^{(l)} & \dots & x_i^{(l)} & \dots & \bar{x}_d^{(l)} \\ \vdots & & \vdots & & \vdots \\ \bar{x}_1^{(M)} & \dots & x_i^{(M)} & \dots & \bar{x}_d^{(M)} \end{bmatrix}$$

$$\mathbb{V} [\mathbb{E} [f | \mathbf{x}_{\{i\}}]] \approx \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\} \sim}, \mathbf{x}_{\{i\} \sim}) f(\bar{\mathbf{x}}_{\{i\} \sim}, \mathbf{x}_{\{i\} \sim}) - \left( \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\} \sim}, \mathbf{x}_{\{i\} \sim}) \right)^2$$

## Total sensitivity indices by Monte-Carlo sampling.

The  $T_{\{i\}}$  can be computed by MC sampling as follow. Recall that

$$T_{\{i\}}(f) = \sum_{i \ni \{i\}} S_i(f) = 1 - \sum_{i \subseteq \mathcal{D} \setminus \{i\}} S_i(f) = 1 - \frac{\mathbb{V}[\mathbb{E}[f|\mathbf{x}_{\{i\}\sim}]]}{\mathbb{V}[f]}.$$

As for  $\mathbb{V}[\mathbb{E}[f|\mathbf{x}_{\{i\}}]]$ , we can derive the following Monte-Carlo estimator for  $\mathbb{V}[\mathbb{E}[f|\mathbf{x}_{\{i\}\sim}]]$ , using the two independent sample sets  $\chi_M$  and  $\tilde{\chi}_M$

$$\mathbb{V}[\mathbb{E}[\widehat{f|\mathbf{x}_{\{i\}\sim}}]] = \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\}\sim}^{(l)}, \mathbf{x}_{\{i\}}^{(l)}) f(\mathbf{x}_{\{i\}\sim}^{(l)}, \tilde{\mathbf{x}}_{\{i\}}^{(l)}) - \mathbb{E}[f]^2,$$

so finally

$$\widehat{T_{\{i\}}}(f) = 1 - \frac{1}{\widehat{\mathbb{V}[f]}} \left( \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\}\sim}^{(l)}, \mathbf{x}_{\{i\}}^{(l)}) f(\mathbf{x}_{\{i\}\sim}^{(l)}, \tilde{\mathbf{x}}_{\{i\}}^{(l)}) - \mathbb{E}[f]^2 \right)$$

The MC estimation of the  $T_{\{i\}}$  needs  $d \times M$  additional model evaluations.

## Monte-Carlo estimation

$$\mathbf{x}_M : \begin{bmatrix} x_1^{(1)} & \dots & x_i^{(1)} & \dots & x_d^{(1)} \\ \vdots & & \vdots & & \vdots \\ x_1^{(l)} & \dots & x_i^{(l)} & \dots & x_d^{(l)} \\ \vdots & & \vdots & & \vdots \\ x_1^{(M)} & \dots & x_i^{(M)} & \dots & x_d^{(M)} \end{bmatrix} \quad \bar{\mathbf{x}}_M : \begin{bmatrix} \bar{x}_1^{(1)} & \dots & \bar{x}_i^{(1)} & \dots & \bar{x}_d^{(1)} \\ \vdots & & \vdots & & \vdots \\ \bar{x}_1^{(l)} & \dots & \bar{x}_i^{(l)} & \dots & \bar{x}_d^{(l)} \\ \vdots & & \vdots & & \vdots \\ \bar{x}_1^{(M)} & \dots & \bar{x}_i^{(M)} & \dots & \bar{x}_d^{(M)} \end{bmatrix}$$

$$\bar{\mathbf{x}}_M^{\{i\}} : \begin{bmatrix} x_1^{(1)} & \dots & \bar{x}_i^{(1)} & \dots & x_d^{(1)} \\ \vdots & & \vdots & & \vdots \\ x_1^{(l)} & \dots & \bar{x}_i^{(l)} & \dots & x_d^{(l)} \\ \vdots & & \vdots & & \vdots \\ x_1^{(M)} & \dots & \bar{x}_i^{(M)} & \dots & x_d^{(M)} \end{bmatrix}$$

$$\mathbb{V} [\mathbb{E} [f | \mathbf{x}_{\{i\}}]] \approx \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\} \sim}, \mathbf{x}_{\{i\} \sim}) f(\mathbf{x}_{\{i\} \sim}, \bar{\mathbf{x}}_{\{i\} \sim}) - \left( \frac{1}{M} \sum_{l=1}^M f(\mathbf{x}_{\{i\} \sim}, \mathbf{x}_{\{i\} \sim}) \right)^2$$

## MC estimation of 1st order and total sensitivity indices:

- requires  $M \times (2d + 1)$  **simulations**
- convergence of estimators in  $\mathcal{O}(1/\sqrt{M})$
- slow convergence, but  $d$ -independent
- convergence not related to smoothness of  $f$
- works also (in practice) with advanced sampling schemes (QMC, LHS, ...). [How to proceed with QMC/LHS?](#)

## S-H decomposition from PC expansions.

Consider the model-output  $f : \xi \in \Xi \subset \mathbb{R}^d \mapsto \mathbb{R}$ , where  $\xi = (\xi_1, \dots, \xi_d)$  are independent real-valued r.v. with joint-probability density function

$$p_{\xi}(x_1, \dots, x_d) = \prod_{i=1}^d p_i(x_i).$$

Let  $\{\Psi_{\alpha}\}$  be the set of  $d$ -variate orthogonal polynomials,

$$\Psi_{\alpha}(\xi) = \prod_{i=1}^d \psi_{\alpha_i}^{(i)}(\xi_i),$$

with  $\psi_{l \geq 0}^{(i)} \in \pi_l$  the uni-variate polynomials mutually orthogonal with respect to the density  $p_i$ .

If  $f \in L_2(\Xi, p_{\xi})$ , it has a convergent PC expansion

$$f(\xi) = \lim_{N_0 \rightarrow \infty} \sum_{|\alpha| \leq N_0} \Psi_{\alpha}(\xi) f_{\alpha}, \quad |\alpha| = \sum_{i=1}^d |\alpha_i|.$$

## S-H decomposition from PC expansions.

Given the truncated PC expansion of  $f$ ,

$$\hat{f}(\xi) = \sum_{|\alpha| \leq \mathcal{A}} \Psi_{\alpha}(\xi) f_{\alpha},$$

one can readily obtain the PC approximation of the S-H functionals through

$$\hat{f}_i(\xi_i) = \sum_{|\alpha| \leq \mathcal{A}(i)} \Psi_{\alpha}(\xi_i) f_{\alpha},$$

where the multi-index set  $\mathcal{A}(i)$  is given by

$$\mathcal{A}(i) = \{\alpha \in \mathcal{A}; \alpha_j > 0 \text{ for } j \in i, \alpha_j = 0 \text{ for } j \notin i\} \subsetneq \mathcal{A}.$$

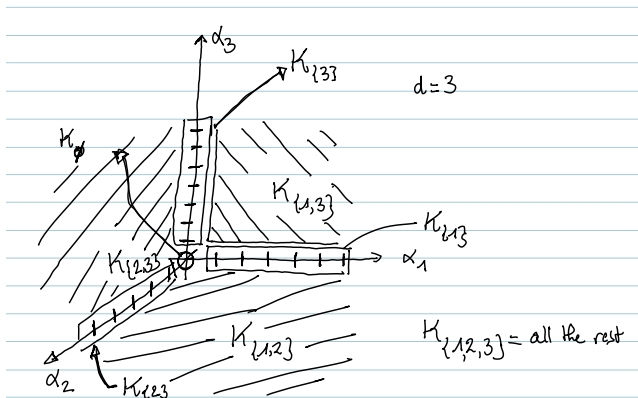
For the sensitivity indices it comes

$$S_i(\hat{f}) = \frac{\sum_{\alpha \in \mathcal{A}(i)} f_{\alpha}^2 \langle \Psi_{\alpha}, \Psi_{\alpha} \rangle}{\sum_{\alpha \in \mathcal{A}} f_{\alpha}^2 \langle \Psi_{\alpha}, \Psi_{\alpha} \rangle}, \quad T_{\{i\}}(\hat{f}) = \frac{\sum_{\alpha \in \mathcal{T}(i)} f_{\alpha}^2 \langle \Psi_{\alpha}, \Psi_{\alpha} \rangle}{\sum_{\alpha \in \mathcal{A}} f_{\alpha}^2 \langle \Psi_{\alpha}, \Psi_{\alpha} \rangle},$$

where

$$\mathcal{T}(i) = \{\alpha \in \mathcal{A}; \alpha_j > 0 \text{ for } j \in i\}$$

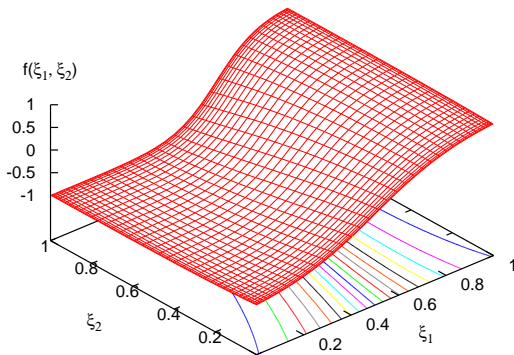
## Subsets of PC multi-indices for S-H functionals

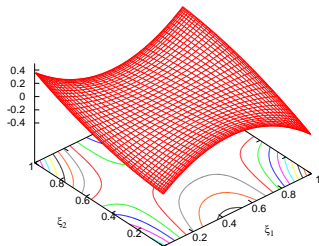
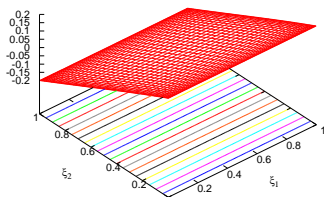
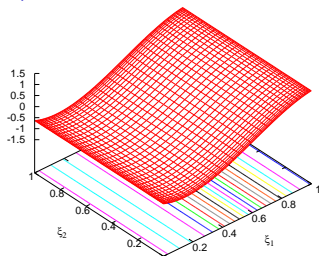
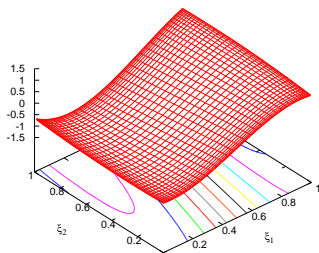


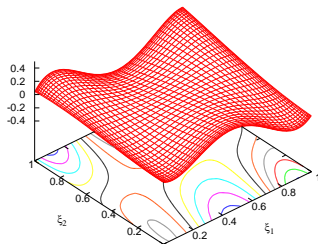
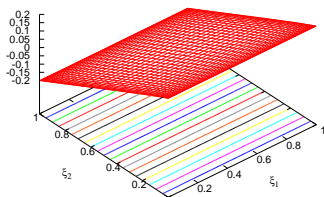
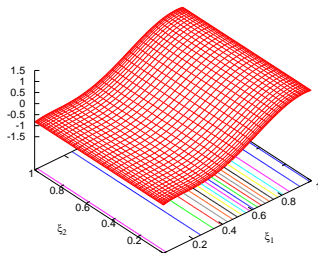
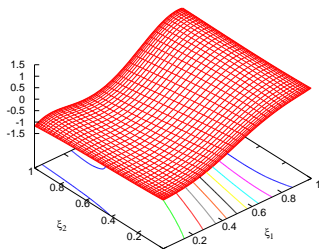


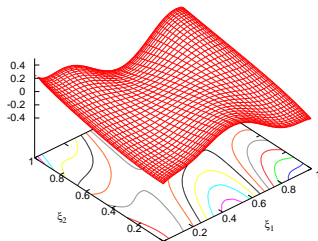
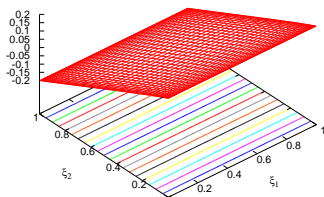
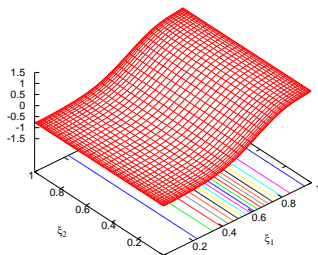
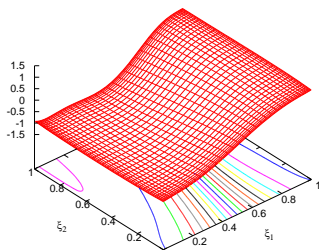
**Example:** Let  $(\xi_1, \xi_2)$  be two independent random variables with uniform distributions on the unit interval. Consider the model-output  $f : (\xi_1, \xi_2) \in [0, 1]^2 \mapsto \mathbb{R}$  given by

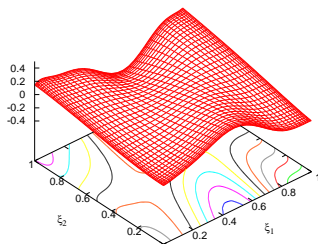
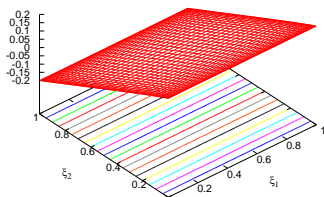
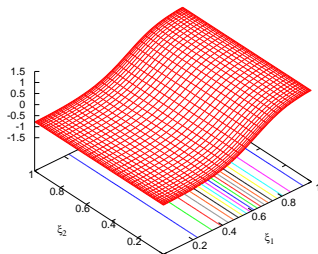
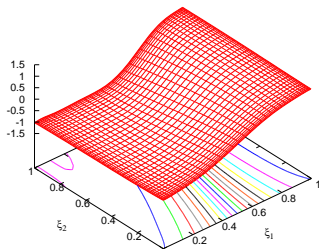
$$f(\xi_1, \xi_2) = \tanh(3(\xi_1 - 0.2\xi_2 - .5)(1 + \xi_2)).$$



S-H decomposition at  $N_0 = 3$  ( $P = 10$ ):

S-H decomposition at  $N_0 = 5$ : ( $P = 21$ )

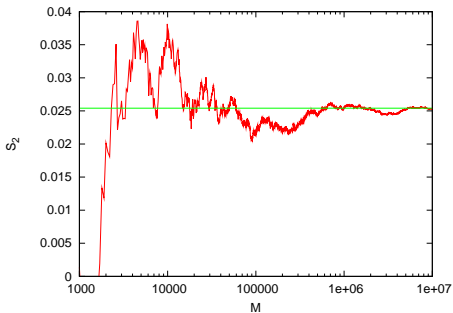
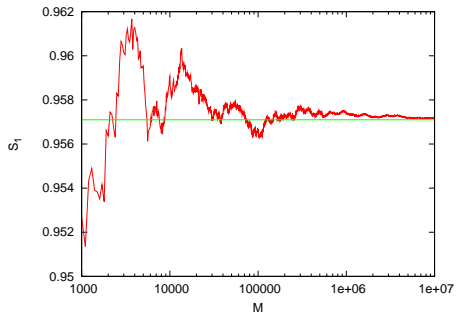
S-H decomposition at  $N_0 = 7$ : ( $P = 36$ )

S-H decomposition at  $N_0 = 9$ : ( $P = 55$ )

## Convergence of sensitivity indices:

No	Card( $\mathcal{A}$ )	$S_{\{1\}}(\hat{f})$	$S_{\{2\}}(\hat{f})$	$S_{\{1,2\}}(\hat{f})$	$\ \hat{f} - f\ _2$
3	10	9.604 (-1)	2.567 (-2)	1.390 (-2)	7.1 (-2)
5	21	9.578 (-1)	2.545 (-2)	1.676 (-2)	2.6 (-2)
7	36	9.572 (-1)	2.542 (-2)	1.734 (-2)	9.6 (-3)
9	55	9.571 (-1)	2.542 (-2)	1.745 (-2)	3.6 (-3)
15	136	9.571 (-1)	2.542 (-2)	1.748 (-2)	1.9 (-4)

## Convergence of sensitivity indices for **naïve** MC sampling:



## Homework: Homma-Saltelli function

$$f(x_1, x_2, x_3) = \sin(x_1) + a \sin^2(x_2) + bx_3^4 \sin(x_1),$$

where  $x_1, x_2$  and  $x_3$  are i.i.d. random variables uniformly distributed on  $[-\pi, \pi]$ .  
Letting  $\langle \cdot \rangle$  be the expectation (over  $[-\pi, \pi]^3$ ), we have

$$\langle \sin \rangle = 0, \quad \langle \sin^2 \rangle = 1/2, \quad \langle \sin^4 \rangle = 3/8, \quad \langle x^n \rangle = \begin{cases} \frac{\pi^n}{n+1}, & n \text{ even,} \\ 0, & n \text{ odd.} \end{cases}$$

- 1 Compute the SH decomposition of  $f$  and the associated sensitivity indices.

Solution:

$$f(x_1, x_2, x_3) = a/2 + \sin(x_1)(1 + b\pi^2/4) + a(\sin^2(x_2) - 1/2) + b \sin(x_1)(x_3^4 - \pi^4/5).$$

- 2 Compute PC expansion of  $f$  by non-intrusive spectral projection for polynomial degrees 1 to 6 and extract 1st order and total sensitivity indices for  $a = 7$  and  $b = 0.1$ .
- 3 Compute 1-st order and total sensitivity indices by Monte-Carlo simulation.



## Further readings:

- Hoeffding, W. (1948). A class of statistics with asymptotically normal distribution. *The annals of Mathematical Statistics*, **19**, pp. 293-325.
- Sobol, I. M. (1993). Sensitivity estimates for nonlinear mathematical models. *Wiley*, **1**, pp. 407-414.
- Sobol, I. M. (2001). Global sensitivity indices for nonlinear mathematical models and their Monte Carlo estimates. *Mathematics and Computers in Simulations*, **55**, pp. 271-281.
- Homma T., Saltelli A., (1996). Importance measures in global sensitivity analysis of nonlinear models. *Reliab. Eng. Syst. Safety*, **52**:1, pp. 1-17.
- Crestaux T., Le Maître O. and Martinez J.M., (2009). Polynomial Chaos expansion for sensitivity analysis. *Reliab. Eng. Syst. Safety*, **94**:7, pp. 1161-1172.