

Spectral Methods for Uncertainty Quantification

Olivier Le Maître¹
with Colleague & Friend
Omar Knio



¹LIMSIS, CNRS
UPR-3251, Orsay, France
<https://perso.limsi.fr/olm/>



UTOPIÆ Uncertainty
Treatment and
Optimisation in
Aerospace
Engineering

Handling the unknown at the edge of tomorrow

PhD course on UQ - DTU



Overview

Objectives of the lecture

- Introduce Parametric Uncertainty Quantification & Propagation
- Discuss a first spectral expansion: the Karhunen-Loève decomposition
- Formalism and essential ingredients of Wiener's PC expansions
- Generalize finite dimensional PC expansions to arbitrary measures
- Shortly discuss alternative construction approaches.

Table of content

- 1 Parametric Data Propagation**
 - Data uncertainty
 - Alternative UQ& P methods
- 2 Spectral expansions**
 - Karhunen-Loeve expansion
 - Wiener-Hermite expansion
 - Generalized PC expansions
- 3 PC Expansions of Stochastic Quantities**
 - Random variables and vectors
 - Random fields
 - PC expansions in practice

Simulation framework.

Basic ingredients

- Understanding of the physics involved (**optional?**):
selection of the **mathematical model**.
- **Numerical method**(s) to solve the model.
- Specify a set of **data**:
select a system among the class spanned by the model.

Simulation framework.

Basic ingredients

- Understanding of the physics involved (**optional?**):
selection of the **mathematical model**.
- **Numerical method**(s) to solve the model.
- Specify a set of **data**:
select a system among the class spanned by the model.

Simulation errors

- **Model errors**: physical approximations and simplifications.
- **Numerical errors**: discretization, approximate solvers, finite arithmetics.
- **Data error**: **boundary/initial conditions, model constants and parameters, external forcings, ...**

Sources of data uncertainty

- Inherent **variability** (e.g. industrial processes).
- **Epistemic** uncertainty (e.g. model constants).
- **May not be fully reducible, even theoretically.**

Probabilistic framework

- Define an abstract probability space $(\Theta, \mathcal{A}, d\mu)$.
- Consider **data** D as **random** quantity: $D(\theta)$, $\theta \in \Theta$.
- **Simulation output** S is **random** and on $(\Theta, \mathcal{A}, d\mu)$.

Sources of data uncertainty

- Inherent **variability** (e.g. industrial processes).
- **Epistemic** uncertainty (e.g. model constants).
- **May not be fully reducible, even theoretically.**

Probabilistic framework

- Define an abstract probability space $(\Theta, \mathcal{A}, d\mu)$.
- Consider **data** D as **random** quantity: $D(\theta)$, $\theta \in \Theta$.
- **Simulation output** S is **random** and on $(\Theta, \mathcal{A}, d\mu)$.
- **Data D and simulation output S are dependent random quantities (through the mathematical model \mathcal{M}):**

$$\mathcal{M}(S(\theta), D(\theta)) = 0, \quad \forall \theta \in \Theta.$$

Deterministic methods

Simulation techniques

Monte-Carlo

- Generate a **sample set of data** realizations and compute the corresponding **sample set of model output**.
- Use sample set based **random estimates** of abstract characterizations (moments, correlations, ...).
- Plus: **Very robust** and re-use **deterministic codes**: (parallelization, complex data uncertainty).
- Minus: **slow convergence of the random estimates** with the sample set dimension.

Spectral Methods

Deterministic methods

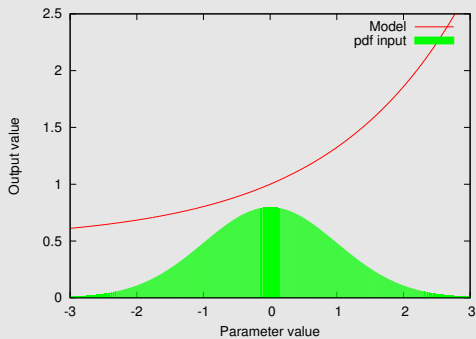
Simulation techniques

Monte-Carlo

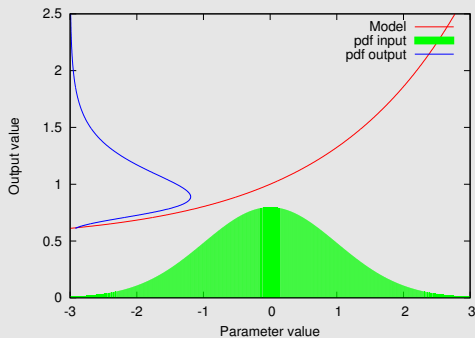
Spectral Methods

- Parameterization of the data with **random variables** (RVs).
- **⊥ projection** of solution on the (L_2) space spanned by the RVs.
- Plus: **arbitrary level of uncertainty, deterministic approach, convergence rate, information contained.**
- Minus: **parameterizations** (limited # of RVs), **adaptation of simulation tools** (legacy codes), **robustness** (non-linear problems, non-smooth output, ...).
- **Not suited for model uncertainty**

Propagation of data uncertainty

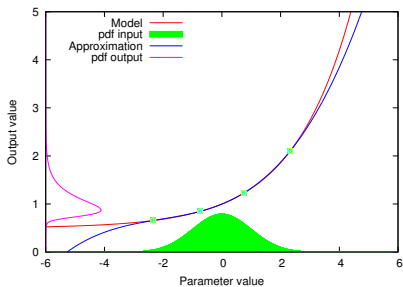
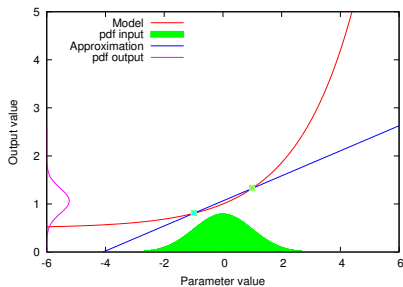


Propagation of data uncertainty



- Large number of parameters
- Costly model evaluation (PDE)
- Estimation of $p(S)$ is not the end of the story!

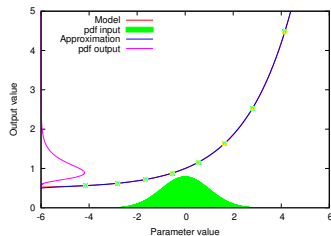
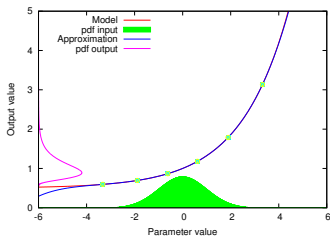
Alternative UQ& P methods



Approximate the model output $S(D)$ through a functional representation of the form

$$S(D) \approx \sum_{k=0}^P S_k \psi_k(D) \doteq S^P(D)$$

Alternative UQ& P methods



$$S(D) \approx \sum_{k=0}^P S_k \Psi_k(D) \doteq S^P(D)$$

- Exploit (whenever possible) the smoothness of $S(D)$ to have a fast convergence of $S^P(D)$ toward $S(D)$
- Determine S^P at a low computational cost
- Base UQ analysis on the surrogate $S^P(D)$ (cheap evaluations).

Example (Elliptic equations)

Let $\Omega \in \mathbb{R}^2$ be a closed domain, and the Dirichlet problem

$$\begin{aligned} \nabla \cdot (\nu(\mathbf{x}) \nabla u(\mathbf{x})) &= -f(\mathbf{x}) & \forall \mathbf{x} \in \Omega, \\ u(\mathbf{x}) &= 0 & \mathbf{x} \in \partial\Omega. \end{aligned}$$

with $0 < \epsilon < \nu(\mathbf{x}) < +\infty$ and f given.

Introducing a suitable functional space $V := H_0^1$, the solution $u \in V$ is such that

$$\begin{aligned} a(u, v; \nu) &= b(v) & \forall v \in V, \\ a(u, v; \nu) &= \int_{\Omega} \nu \nabla u \cdot \nabla v d\mathbf{x} & b(v) = \int_{\Omega} f v d\mathbf{x}. \end{aligned}$$

The solution is unique.

Example (Uncertainty)

The unique solution to

$$a(u, v; \nu) = b(v) \quad \forall v \in V,$$

depends (continuously) on ν :

$$u := u(\mathbf{x}, \nu)$$

Now, if ν is uncertain and model as a random process defined on a probability space $(\Theta, \Sigma, d\mu)$

$$(\Omega \times \Theta) \ni (\mathbf{x} \times \theta) \mapsto \nu(\mathbf{x}, \theta) \in \mathbb{R}.$$

$\nu(\cdot, \theta)$ is a function with domain Ω , $\nu(\mathbf{x}, \cdot)$ is a random variable.

$\implies u(\mathbf{x}, \nu)$ is now random, we write $U(\mathbf{x}, \theta)$.

The stochastic solution $U(\mathbf{x}, \theta)$ solves almost surely

$$a(U(\cdot, \theta), v; \nu(\theta)) = b(v) \quad \forall v \in V.$$

We need to compute $U(\mathbf{x}, \theta)$.

Example (Spectral expansion)

Often $U(\mathbf{x}, \theta)$ is smooth in \mathbf{x} and with respect to $\nu(\theta)$. We seek for a spectral approximation using a **rapidly converging** series

$$U(\mathbf{x}, \theta) = \sum_{n \geq 0} u_n(\mathbf{x}) \eta_n(\theta),$$

where $u_n(\mathbf{x}) \in V$ and $\eta_n(\theta)$ is defined on $(\Theta, \Sigma, d\mu)$.

Table of content

- 1 Parametric Data Propagation**
 - Data uncertainty
 - Alternative UQ& P methods
- 2 Spectral expansions**
 - Karhunen-Loeve expansion
 - Wiener-Hermite expansion
 - Generalized PC expansions
- 3 PC Expansions of Stochastic Quantities**
 - Random variables and vectors
 - Random fields
 - PC expansions in practice

Observe : K is a symmetric positive operator so the eigenfunctions are orthonormal:

$$(u_n, u_{n'}) = \delta_{nn'}$$

The optimal decomposition is

$$U(\mathbf{x}\theta) \approx \sum_{n=1}^m \sqrt{\lambda_n} u_n(\mathbf{x}) \eta_n(\theta),$$

where $\lambda_1 \geq \lambda_2 \geq \dots \geq 0$ and

$$\eta_n(\theta) = (U(\cdot, \theta), u_n), \quad \mathbb{E}[\eta_n] = 0, \quad \mathbb{E}[\eta_n^2] = 1.$$

- optimality and convergence in the mean-squared sense
- can be applied only if U is known
- how to represent the stochastic coefficient?

Example (Parametrization)

The KL expansion is often used to construct **parametrizations** of the uncertain model input which are known.

For instance, ν is frequently model as a **log-normal** random field:

$$\nu(\mathbf{x}, \theta) = C \exp G(\mathbf{x}, \theta),$$

where G is a zero-mean Gaussian random field with prescribed auto-correlation kernel $K_G(\mathbf{x}, \mathbf{y})$:

$$G(\mathbf{x}, \theta) \approx \sum_{n=1}^m g_n(\mathbf{x}) \xi_n(\theta),$$

where the ξ_n 's are **independent normalized Gaussian random variables**. Setting $\xi = (\xi_1 \cdots \xi_m)$, we finally seek for the **approximate** $U^m(\mathbf{x}, \xi)$ such that a.s.

$$a(U^m(\mathbf{x}, \xi), \nu; \nu(\mathbf{x}, \xi)) = b(\nu) \quad \forall \nu \in V.$$

Table of content

- 1 Parametric Data Propagation**
 - Data uncertainty
 - Alternative UQ& P methods
- 2 Spectral expansions**
 - Karhunen-Loeve expansion
 - Wiener-Hermite expansion
 - Generalized PC expansions
- 3 PC Expansions of Stochastic Quantities**
 - Random variables and vectors
 - Random fields
 - PC expansions in practice

Consider a \mathbb{R} -valued random variable defined on a probability space (Θ, Σ, dP) :

$$U : \Theta \mapsto \mathbb{R}.$$

We denote $L^2(\Theta, dP)$ the space of **second order random variables**:

$$U \in L^2(\Theta, dP) \Leftrightarrow \mathbb{E} [U^2] := \int_{\Theta} U(\theta)^2 dP(\theta) < +\infty.$$

Let $\{\xi_i\}_{i=1}^{\infty}$ be a sequence of **centered, normalized, mutually orthogonal (uncorrelated) Gaussian random variables**:

$$\mathbb{E} [\xi_i] = 0, \quad \mathbb{E} [\xi_i \xi_j] = \delta_{i,j} \quad \forall i, j = 1, 2, \dots$$

We denote for $p = 0, 1, 2, \dots$:

- $\hat{\Gamma}_p$ the space of orthogonal polynomials in $\{\xi_i\}_{i=1}^{\infty}$ with degree $\leq p$.
- Γ_p the set of polynomials belonging to $\hat{\Gamma}_p$ and \perp to $\hat{\Gamma}_{p-1}$.
- $\tilde{\Gamma}_p$ the (sub) space spanned by Γ_p .

We have

$$\hat{\Gamma}_p = \hat{\Gamma}_{p-1} \oplus \tilde{\Gamma}_p, \quad L^2(\Theta, dP) = \bigoplus_{p=0}^{p=\infty} \tilde{\Gamma}_p.$$

- $\tilde{\Gamma}_p$ is called the p -th Homogeneous Chaos.
- Γ_p is called the Polynomial Chaos of order p .
- Γ_p consists of orthogonal polynomials with degree p , involving all combinations of the r.v. $\{\xi_i\}$.

Note: functions of r.v. are r.v. themselves and are regarded as functionals.

Fundamental Result:

[Wiener, 1938]

Any well-behaved random variable, e.g. second order ones, has a PC representation of the form

$$\begin{aligned}
 U(\theta) = & u_0 \Gamma_0 + \sum_{i_1=1}^{\infty} u_{i_1} \Gamma_1(\xi_{i_1}(\theta)) + \sum_{i_1=1}^{\infty} \sum_{i_2=1}^{i_1} u_{i_1, i_2} \Gamma_2(\xi_{i_1}(\theta), \xi_{i_2}(\theta)) \\
 & + \sum_{i_1=1}^{\infty} \sum_{i_2=1}^{i_1} \sum_{i_3=1}^{i_2} u_{i_1, i_2, i_3} \Gamma_3(\xi_{i_1}(\theta), \xi_{i_2}(\theta), \xi_{i_3}(\theta)) \\
 & + \sum_{i_1=1}^{\infty} \sum_{i_2=1}^{i_1} \sum_{i_3=1}^{i_2} \sum_{i_4=1}^{i_3} u_{i_1, i_2, i_3, i_4} \Gamma_4(\xi_{i_1}(\theta), \xi_{i_2}(\theta), \xi_{i_3}(\theta), \xi_{i_4}(\theta)) + \dots
 \end{aligned}$$

The series converges in the **mean-square sense**:

$$\lim_{p \rightarrow \infty} \mathbb{E} \left[\left(u_0 \Gamma_0 + \dots + \sum_{i_1=1}^{\infty} \dots \sum_{i_p=1}^{i_{p-1}} \Gamma_p(\xi_{i_1}, \dots, \xi_{i_p}) - U \right)^2 \right] = 0.$$

PC expansion of U :

$$\begin{aligned}
 U(\theta) = & u_0 \Gamma_0 + \sum_{i_1=1}^{\infty} u_{i_1} \Gamma_1(\xi_{i_1}(\theta)) + \sum_{i_1=1}^{\infty} \sum_{i_2=1}^{i_1} u_{i_1, i_2} \Gamma_2(\xi_{i_1}(\theta), \xi_{i_2}(\theta)) \\
 & + \sum_{i_1=1}^{\infty} \sum_{i_2=1}^{i_1} \sum_{i_3=1}^{i_2} u_{i_1, i_2, i_3} \Gamma_3(\xi_{i_1}(\theta), \xi_{i_2}(\theta), \xi_{i_3}(\theta)) \\
 & + \sum_{i_1=1}^{\infty} \sum_{i_2=1}^{i_1} \sum_{i_3=1}^{i_2} \sum_{i_4=1}^{i_3} u_{i_1, i_2, i_3, i_4} \Gamma_4(\xi_{i_1}(\theta), \xi_{i_2}(\theta), \xi_{i_3}(\theta), \xi_{i_4}(\theta)) + \dots
 \end{aligned}$$

- We denote $\xi := \{\xi_i\}_{i=1}^{\infty}$.
- We shall write $U(\xi)$ for the PC expansion of U .

Few important properties:

- **Vanishing expectation:** $\mathbb{E}[\Gamma_p] = 0$ for $p > 0$.
- One can express the expectation of U in the Gaussian space spanned by ξ_i with the measure

$$p_{\xi}(\mathbf{y}) = \prod_{i=1}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left[-y_i^2/2\right].$$

- that is

$$\begin{aligned} \mathbb{E}[U] &= \int_{\Theta} U(\theta) dP(\theta) = \int_{\Theta} U(\xi(\theta)) dP(\theta) \\ &= \int \cdots \int U(\mathbf{y}) p_{\xi}(\mathbf{y}) d\mathbf{y} =: \langle U \rangle. \end{aligned}$$

- The **orthogonality of the polynomials** is with regard to the Gaussian measure.

Truncated PC expansions: in practice a finite number of r.v. is used

$$\xi = \{\xi_1, \dots, \xi_N\}$$

N is called the stochastic dimension and ξ is often referred as the stochastic germ.

Example of two dimensional PC expansion:

$$\begin{aligned} U(\xi_1, \xi_2) = & u_0 \Gamma_0 + u_1 \Gamma_1(\xi_1) + u_2 \Gamma_2(\xi_2) \\ & + u_{11} \Gamma_2(\xi_1, \xi_1) + u_{21} \Gamma_2(\xi_2, \xi_1) + u_{22} \Gamma_2(\xi_2, \xi_2) \\ & + u_{111} \Gamma_3(\xi_1, \xi_1, \xi_1) + u_{211} \Gamma_3(\xi_2, \xi_1, \xi_1) + u_{221} \Gamma_3(\xi_2, \xi_2, \xi_1) \\ & + u_{222} \Gamma_3(\xi_2, \xi_2, \xi_2) + u_{1111} \Gamma_4(\xi_1, \xi_1, \xi_1, \xi_1) + \dots \end{aligned}$$

With the introduction of an indexation scheme, the expansion can be recast as

$$U(\xi) = \sum_{k=0}^{\infty} u_k \Psi_k(\xi), \quad u_k \in \mathbb{R}.$$

The u_k are the PC coefficients of U and Ψ_k are (orthogonal) polynomial. We here use the convention $\Psi_0 = \Gamma_0 = 1$.

1-D PC expansion:

Recall that the **chaos polynomials are orthogonal** wrt the probability density of ξ (centered, normalized, Gaussian):

$$p_{\xi}(y) = \frac{1}{\sqrt{2\pi}} \exp \left[-y^2/2 \right]. \quad (1)$$

By $\psi_p(\xi)$ we denote the 1D polynomial of order p .

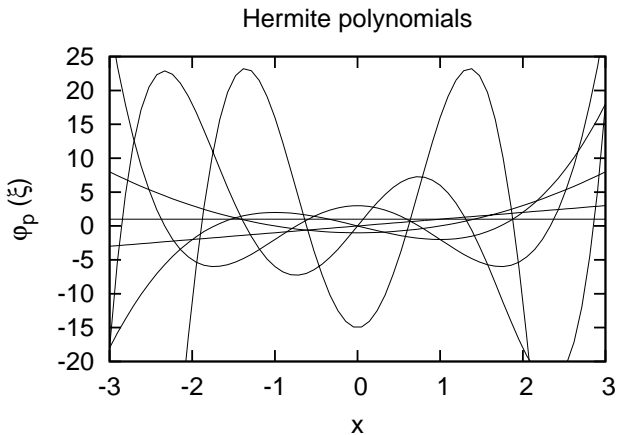
Following the indexation convention, $\psi_0(\xi) = 1$.

The **orthogonality condition** is:

$$\mathbb{E} [\psi_i \psi_j] = \int_{\mathbb{R}} \psi_i(y) \psi_j(y) p_{\xi}(y) dy = \delta_{ij} \langle \psi_i^2 \rangle.$$

- The ψ_i is the well known **Hermite polynomial** of degree i .
- the Hermite polynomials are normalized s.t. $\langle \psi_i^2 \rangle = i!$.

First Hermite polynomials (1-D):



One-dimensional Hermite polynomials, $\psi_p(\xi)$, for $p = 0, \dots, 6$.

Multi-dimensional PC basis:

The N -variate polynomials ψ_i are constructed as product of 1-D Hermite polynomials.

Let $\gamma := \{\gamma_1 \dots \gamma_N\} \in \mathbb{N}^N$ be a **multi-index** and $\lambda(p)$ the multi-index set

$$\lambda(p) = \left\{ \gamma : \sum_{i=1}^N \gamma_i = p \right\}.$$

The p -th order polynomial chaos is constructed according to:

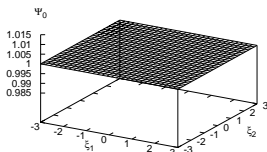
$$\Gamma_p = \left\{ \bigcup_{\gamma \in \lambda(p)} \prod_{\gamma_i} \psi_{\gamma_i}(\xi_i) \right\}.$$

Example for $N = 2$:

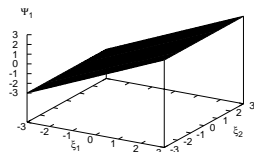
$$\begin{aligned} U(\xi_1, \xi_2) &= u_0 \psi_0 + u_1 \psi_1(\xi_1) + u_2 \psi_1(\xi_2) + u_{11} \psi_2(\xi_1) + u_{21} \psi_1(\xi_2) \psi_1(\xi_1) \\ &+ u_{22} \psi_2(\xi_2) + u_{111} \psi_3(\xi_1) + u_{211} \psi_1(\xi_2) \psi_2(\xi_1) \\ &+ u_{221} \psi_2(\xi_2) \psi_1(\xi_1) + u_{222} \psi_3(\xi_2) + u_{1111} \psi_4(\xi_1) + \dots \end{aligned}$$

Wiener-Hermite expansion

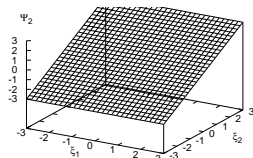
The Hermite polynomials for $p \leq 2$ ($N = 2$)



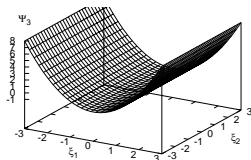
$$\Psi_0 = 1$$



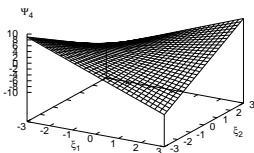
$$\Psi_1 = \xi_1$$



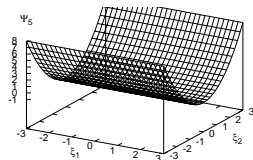
$$\Psi_2 = \xi_2^2$$



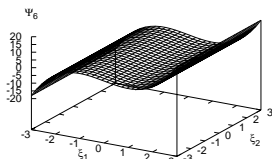
$$\Psi_3 = \xi_1^2 - 1$$



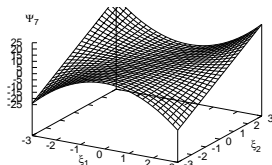
$$\Psi_4 = \xi_1 \xi_2$$



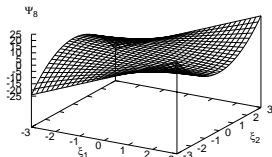
$$\Psi_5 = \xi_2^2 - 1$$

The Hermite polynomials for $p = 3$ ($N = 2$)

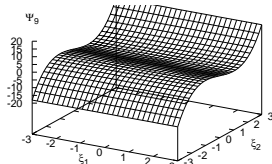
$$\Psi_6 = \xi_1^3 - 3\xi_1$$



$$\Psi_7 = \xi_1^2 \xi_2 - \xi_2$$



$$\Psi_8 = \xi_1 \xi_2^2 - \xi_1$$



$$\Psi_9 = \xi_2^3 - 3\xi_2$$

Truncated PC expansion

In addition to a finite number of random variables, N , we need to **truncate the PC expansion to a finite order p**

$$U(\xi) \approx U^p(\xi) = \sum_{k=0}^P u_k \Psi_k(\xi), \quad P + 1 = \frac{(N + p)!}{N!p!}$$

Dependence of $(P + 1)$ on N and p :

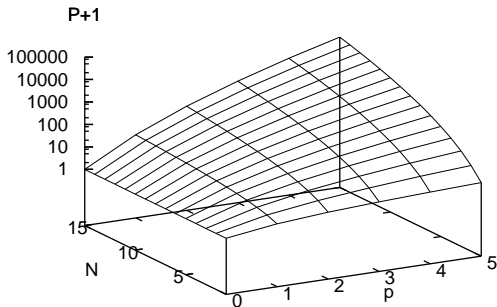
p/N	1	2	3	4	5	6
1	2	3	4	5	6	7
2	3	6	10	15	21	28
3	4	10	20	35	56	84

p/N	1	2	3	4	5	6
4	5	15	35	70	126	210
5	6	21	56	126	252	462
6	7	28	84	210	462	924

Fast increase with both N and p .

Other truncature strategies may be used.

Wiener-Hermite expansion



Number of terms in the PC expansion plotted against the order, p , and the number of dimensions, N .

The truncated expansion of a random variable U is

$$U(\theta) \approx U^P(\xi) + \epsilon(N, p) = \sum_{k=0}^P u_k \Psi_k(\xi) + \epsilon(N, p).$$

The truncation error depends both on N and p .

The error is a random variable.

The expansion converges in the mean-square sense as N and p go to infinity [Cameron & Martin, 1947]:

$$\lim_{N, p \rightarrow \infty} \langle \epsilon^2(N, p) \rangle = 0.$$

In light of the dependence of P on the order and the number of random variables, the PC representation will be computationally efficient if the convergence is fast in both N and p .

Hilbert space (fixed finite N)

- The polynomials $\{\Psi_k\}_{k=0}^{\infty}$ forms an **orthogonal basis of $L^2(\mathbb{R}^N, p_{\xi})$** .
- $L^2(\mathbb{R}^N, p_{\xi})$ is equipped with the **inner product**

$$\langle U, V \rangle := \mathbb{E}[UV] = \int_{\mathbb{R}^N} U(\mathbf{y})V(\mathbf{y})p_{\xi}(\mathbf{y})d\mathbf{y}$$

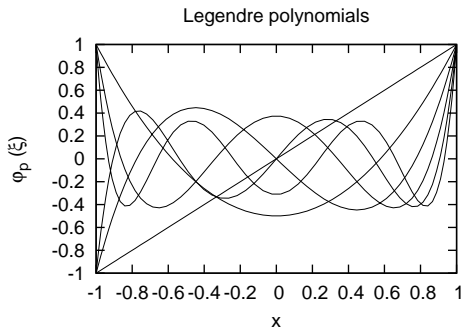
and norm $\|U\|_{L^2(\mathbb{R}^N, p_{\xi})} := \langle U, U \rangle^{1/2}$.

- The convergence of the truncated expansion $U^P \rightarrow U$ depends on the probability law of U .
- For instance, **if U is Gaussian, it has an exact first order expansion.**
- Suggests the construction of **polynomial spaces based on non-Gaussian distributions.**

Generalized Polynomial Chaos (GPC) [Xiu & Karniadakis, 2002]

	Distribution ξ	Polynomials $\psi_k(\xi)$	Support
Continuous RV	Gaussian	Hermite	$(-\infty, \infty)$
	γ	Laguerre	$[0, \infty)$
	β	Jacobi	$[a, b]$
	Uniform	Legendre	$[a, b]$
Discrete RV	Poisson	Charlier	$\{0, 1, 2, \dots\}$
	Binomial	Krawtchouk	$\{0, 1, 2, \dots, n\}$
	Negative binomial	Meixner	$\{0, 1, 2, \dots\}$
	Hypergeometric	Hahn	$\{0, 1, 2, \dots, n\}$

Families of probability laws and corresponding families of orthogonal polynomials.



One-dimensional Legendre polynomials of order $p = 0, \dots, 6$.

- If the r.v. in ξ are independent,

$$\rho_{\xi}(\mathbf{y}) = \prod_{i=1}^N \rho_i(y_i),$$

the Ψ_k can be obtained by tensorization of one-dimensional polynomials constructed on the probability distribution of each ξ_j .

- We denote $\{\psi_l^{(i)}\}_{l=0}^p$ the family of 1-D polynomials with degree $\leq p$ orthogonal w.r.t. to the measure p_i associated to ξ_j , $i = 1, \dots, N$, that is

$$\int \psi_l(y) \psi_{l'}(y) p_i(y) dy = \delta_{l,l'} \int \psi_l(y)^2 p_i(y) dy.$$

- The m -th order GPC is constructed according to:

$$\Gamma_m^G = \left\{ \bigcup_{\gamma \in \lambda(m)} \prod_{\gamma_1}^{\gamma_N} \psi_{\gamma_1}^{(1)}(\xi_1) \right\}, \quad \bigoplus_{m=0}^{m=p} \Gamma_m^G = \{\Psi_k\}_{k=0}^{k=P}.$$

- For general distributions of the independent ξ_i , one can rely on **numerical orthogonalization** procedure (Gram-Schmidt) to construct the 1-D family of polynomials.
- Anticipating forthcoming lectures, one can think of using **other types of functionals** in the construction.
- These include piecewise polynomial functions, sine and cosine functions (uniform measure), wavelets, ...
- In fact any basis of the Hilbert space $L^2(\Xi, p_\xi)$, where Ξ is the support of p_ξ .
- An important aspect to **keep in mind is the dimension** of the expansion.

(Really) Generalized PC:

[Soize & Ghanem, 2004]

Case of a germ ξ with dependent components ξ_j

- The joint probability distribution p_ξ can not be factorized.
- Denote p_i the marginal distribution of ξ_j :

$$p_i(y) = \int dy_1 \cdots \int dy_{i-1} \int dy_{i+1} \cdots \int dy_N p_\xi(y_1, \dots, y_N).$$

- Let $\{\phi_p^{(i)}(\xi)\}$ be the corresponding sets of 1-D polynomials satisfying

$$\langle \phi_p^{(i)}, \phi_{p'}^{(i)} \rangle_{p_i} \equiv \int \phi_p^{(i)}(y) \phi_{p'}^{(i)}(y) p_i(y) dy = \delta_{pp'}.$$

(Really) Generalized PC:

[Soize & Ghanem, 2004]

Case of a germ ξ with dependent components ξ_j

- The joint probability distribution p_{ξ} can not be factorized.
- Denote p_i the marginal distribution of ξ_j :

$$p_i(y) = \int dy_1 \cdots \int dy_{i-1} \int dy_{i+1} \cdots \int dy_N p_{\xi}(y_1, \dots, y_N).$$

- The Chaos function associated to the multi-index $\gamma \in \mathbb{N}^N$ writes

$$\Psi_{\gamma}(\xi) = \left[\frac{p_1(\xi_1) \cdots p_N(\xi_N)}{p_{\xi}(\xi)} \right]^{1/2} \phi_{\gamma_1}^{(1)}(\xi_1) \cdots \phi_{\gamma_N}^{(N)}(\xi_N).$$

- It can be checked that the Ψ 's are orthogonal and form a basis of $L^2(\Xi, p_{\xi})$.
- This is no more a polynomial expansion!

Table of content

- 1 Parametric Data Propagation**
 - Data uncertainty
 - Alternative UQ& P methods
- 2 Spectral expansions**
 - Karhunen-Loeve expansion
 - Wiener-Hermite expansion
 - Generalized PC expansions
- 3 PC Expansions of Stochastic Quantities**
 - Random variables and vectors
 - Random fields
 - PC expansions in practice

- Let U^P be given by a **truncated (G)PC expansion**

$$U^P(\boldsymbol{\xi}) = \sum_{k=0}^P u_k \Psi_k(\boldsymbol{\xi}),$$

where the chaos polynomials $\{\Psi_0, \dots, \Psi_P\}$ are orthogonal (with the convention $\Psi_0 = 1$).

- The **mathematical expectation of U** is

$$\mathbb{E} [U^P] = \langle U^P(\boldsymbol{\xi}) \rangle = \langle \Psi_0, U^P(\boldsymbol{\xi}) \rangle = \sum_{k=0}^P u_k \langle \Psi_0, \Psi_k \rangle = u_0.$$

- Let U^P be given by a **truncated (G)PC expansion**

$$U^P(\boldsymbol{\xi}) = \sum_{k=0}^P u_k \Psi_k(\boldsymbol{\xi}),$$

where the chaos polynomials $\{\Psi_0, \dots, \Psi_P\}$ are orthogonal (with the convention $\Psi_0 = 1$).

- Its variance $\sigma_{U^P}^2$ is in turn

$$\begin{aligned} \sigma_{U^P}^2 &= \mathbb{E} \left[\left(U^P - \mathbb{E} [U^P] \right)^2 \right] = \mathbb{E} \left[\left(\sum_{k=1}^P u_k \Psi_k \right)^2 \right] \\ &= \sum_{k,l=1}^P u_k u_l \langle \Psi_k, \Psi_l \rangle = \sum_{k=1}^P u_k^2 \langle \Psi_k^2 \rangle. \end{aligned}$$

The variance of U^P is given as a **weighted sum of its squared PC coefficients**.

- Let U^P be given by a truncated (G)PC expansion

$$U^P(\boldsymbol{\xi}) = \sum_{k=0}^P u_k \Psi_k(\boldsymbol{\xi}),$$

where the chaos polynomials $\{\Psi_0, \dots, \Psi_P\}$ are orthogonal (with the convention $\Psi_0 = 1$).

- Similar expressions for the higher order moments of U^P in terms of its PC coefficients (but more complex).
- More complex statistical characterizations can be obtained by means of sampling strategies:
 - 1 sampling of Ξ with probability density $p_{\boldsymbol{\xi}}$,
 - 2 generation of realization of U^P by evaluating the PC expansion,
 - 3 analysis of the sample set (density estimation, probability of events, ...).
- Will be shown in subsequent lectures.

Consider a \mathbb{R}^d -random vectors: $\mathbf{U} : \Xi \mapsto \mathbb{R}^d$.

Denoting U_i the i -th component of the random vector, its truncated PC expansion writes

$$U_i(\boldsymbol{\xi}) \approx \sum_{k=0}^P (u_i)_k \Psi_k(\boldsymbol{\xi}).$$

- The expansion of \mathbf{U} can be recast in the vector form

$$\mathbf{U} = \sum_{k=0}^P \mathbf{u}_k \Psi_k(\boldsymbol{\xi}),$$

where $\mathbf{u}_k = ((u_1)_k \cdots (u_d)_k)^t \in \mathbb{R}^d$ is the vector containing the k -th PC coefficients of the random vector components.

- \mathbf{u}_k is called the k -th **stochastic mode of the random vector**.

Random variables and vectors

Consider a \mathbb{R}^d -random vectors: $\mathbf{U} : \Xi \mapsto \mathbb{R}^d$.

Denoting U_i the i -th component of the random vector, its truncated PC expansion writes

$$U_i(\boldsymbol{\xi}) \approx \sum_{k=0}^P (u_i)_k \Psi_k(\boldsymbol{\xi}).$$

- Two components U_i and U_j are orthogonal iff

$$\sum_{k=0}^P (u_i)_k (u_j)_k \langle \Psi_k^2 \rangle = 0.$$

- The correlation and covariance matrices of the vector \mathbf{U} can be respectively expressed as:

$$\mathbf{r} = \sum_{k=0}^P \mathbf{u}_k \mathbf{u}_k^T \langle \Psi_k^2 \rangle, \quad \mathbf{c} = \sum_{k=1}^P \mathbf{u}_k \mathbf{u}_k^T \langle \Psi_k^2 \rangle.$$

Consider a 2nd order stochastic process

$$\Omega \times \Theta \ni (\mathbf{x}, \theta) \mapsto U(\mathbf{x}, \theta) \in \mathbb{R}.$$

Its PC approximation writes

$$U(\mathbf{x}, \theta) \approx U^p(\mathbf{x}, \xi(\theta)) = \sum_{k=0}^p u_k(\mathbf{x}) \Psi_k(\xi(\theta)).$$

- Functions $u_k : \mathbf{x} \in \Omega \mapsto \mathbb{R}$ are called the **stochastic modes** of U .
- Owing to the orthogonality of the chaos polynomials,

$$\mathbb{E}[U(\mathbf{x}, \cdot) \Psi_k] = \sum_l u_l(\mathbf{x}) \mathbb{E}[\Psi_l \Psi_k] = u_k(\mathbf{x}) \langle \Psi_l^2 \rangle.$$

- From the convention $\Psi_0 = 1$, $u_0(\mathbf{x})$ is the mean of the stochastic process
- $$\mathbb{E}[U^p(\mathbf{x}, \cdot)] = \sum_{k=0}^p u_k(\mathbf{x}) \langle \Psi_k \rangle = u_0(\mathbf{x}).$$

Consider a 2nd order stochastic process

$$\Omega \times \Theta \ni (\mathbf{x}, \theta) \mapsto U(\mathbf{x}, \theta) \in \mathbb{R}.$$

It PC approximation writes

$$U(\mathbf{x}, \theta) \approx U^P(\mathbf{x}, \xi(\theta)) = \sum_{k=0}^P u_k(\mathbf{x}) \psi_k(\xi(\theta)).$$

- the correlation function of U^P expresses as

$$\begin{aligned} R_{U^P}(\mathbf{x}, \mathbf{x}') &= \left\langle U^P(\mathbf{x}, \cdot) U^P(\mathbf{x}', \cdot) \right\rangle = \left\langle \left(\sum_{k=0}^P u_k(\mathbf{x}) \psi_k \right) \left(\sum_{l=0}^P u_l(\mathbf{x}') \psi_l \right) \right\rangle \\ &= \sum_{k=0}^P \sum_{l=0}^P u_k(\mathbf{x}) u_l(\mathbf{x}') \langle \psi_k \psi_l \rangle = \sum_{k=0}^P u_k(\mathbf{x}) u_k(\mathbf{x}') \langle \psi_k^2 \rangle. \end{aligned}$$

- It shows that an infinite number of stochastic processes share the same correlation function.

Relation with the KL decomposition of $U(\mathbf{x}, \theta)$ (zero mean S.P.)

Recall that U can be decomposed in

$$U(\mathbf{x}, \theta) = \sum_l u_l^{(KL)} \sqrt{\lambda_l} \eta^l(\theta), \quad \left(u_k^{(KL)}, u_{l'}^{(KL)} \right)_\Omega = \delta_{kl}, \quad \mathbb{E} \left[\eta^l \eta^{l'} \right] = \delta_{ll'}.$$

$u_l^{(KL)}$ are the eigenfunctions of the covariance function.

- $\eta^l \in L^2(\Theta, dP)$ has a PC expansion:

$$\eta^l(\theta) = \sum_k \eta_k^l \psi_k(\xi(\theta)).$$

- Inserting the expansions of the η and rearranging the summations

$$U(\mathbf{x}, \theta) = \sum_k \left[\sum_l u_l^{(KL)}(\mathbf{x}) \sqrt{\lambda_l} \eta_k^l \right] \psi_k(\xi(\theta)).$$

- In addition, it comes

$$\left(u_k, u_{k'} \right)_\Omega = \sum_l \sum_{l'} \sqrt{\lambda_l \lambda_{l'}} \left(u_l^{(KL)}, u_{l'}^{(KL)} \right)_\Omega \eta_k^l \eta_{k'}^{l'} = \sum_l \lambda_l \eta_k^l \eta_{k'}^l$$

which in general is not zero.

Table of content

- 1 Parametric Data Propagation**
 - Data uncertainty
 - Alternative UQ& P methods
- 2 Spectral expansions**
 - Karhunen-Loeve expansion
 - Wiener-Hermite expansion
 - Generalized PC expansions
- 3 PC Expansions of Stochastic Quantities**
 - Random variables and vectors
 - Random fields
 - PC expansions in practice

Truncated PC expansions can be used to approximate stochastic quantities U (random variables, vectors, fields, ...)

This calls for procedures / strategies to determine

- the number of **random variables** N in the germ (and eventually their distributions)
- the **polynomial order** p of the expansion
- the **coefficients of the expansion** (stochastic modes)

We distinguish **two fundamentally different situations**

- 1 the **particular situation** where, given the germ ξ , information on $U(\xi)$ can be assessed
- 2 the **general case** where only information on $U(\theta)$ is available can be assessed

$U(\xi)$ can be assessed:

This case corresponds to situation found in **parametric uncertainty propagation**, where for each realization $\xi(\theta)$ one can **compute / measure the particular realization $U(\xi(\theta))$** .

One can then exploit the mapping $\Xi \ni \xi \mapsto U(\xi)$

to compute the coefficients u_k in the expansion,

$$U(\xi) \approx U^P(\xi) = \sum_{k=0}^P u_k \Psi_k(\xi)$$

For instance, exploiting the orthogonality of the Ψ

$$u_k = \frac{\langle U, \Psi_k \rangle}{\langle \Psi_k, \Psi_k \rangle} = \frac{1}{\langle \Psi_k, \Psi_k \rangle} \int_{\Xi} U(\mathbf{y}) \Psi_k(\mathbf{y}) p_{\xi}(\mathbf{y}) d\mathbf{y}.$$

This is the L^2 -projection of U onto $\text{span}\{\Psi_k, k = 0, \dots, P\}$.

Other type of projections and computational strategies will be extensively discussed in the following.

This is the most general situation where:

- a random quantity $U(\theta)$ has to be approximated by means of a PC expansion,
- $U(\theta)$ may be known partially or completely through, e.g., **sample set of realizations, moments, estimated probability law, ...**
- from the **available information**, one need to define a germ, expansion order and to specify $U^P(\xi(\theta))$ that approximate $U(\theta)$.

One cannot exploit the mapping $\Xi \ni \xi \mapsto U(\xi)$

to compute the coefficients u_k in the expansion,

$$U(\theta) \approx U^P(\xi(\theta)) = \sum_{k=0}^P u_k \Psi_k(\xi(\theta))$$

as there is no *explicit* relation between $U(\theta)$ and $\xi(\theta)$.

This is the typical situation faced when **constructing stochastic models of uncertainty** in particular to model stochastic fields.

- It essentially amounts to the **resolution of optimization problems** to identify /estimate the germ and expansion order that best fit the available information.
- Optimization can be based on **moments matching, likelihood, entropy maximization, ...**

Questions & Discussion