## Spectral/hp-FEM

Linear interpolants are easy to use and implement, but offer only algebraic h-refinement convergence. One option is to use piecewise P-order polynomials as basis functions for the approximating solution. This approach opens a new avenue of convergence, namely the p-type, where the order P is increased.

There are two interchangeable ways for representing an approximation locally on any triangular element: Modal representation by Proriol's orthonormal basis for the P-order polynomial space

$$\phi_m(r,s) = \sqrt{2}(1-s)^j P_i^{(0,0)} \left(2\frac{1+r}{1-s} - 1\right) P_j^{(2i+1,0)}(s)$$

on the triangle T given by  $-1 \le r, s$  and  $r+s \le 0$ where the index is  $m = j + (P+1)i + 1 - \frac{1}{2}i(i-1)$ with  $0 \le i, j$  and  $i + j \le P$  being valid subindices. Nodal representation by Lagrange polynomials

$$\hat{u}(r,s) = \sum_{k=1}^{M_P} \hat{u}_k N_k^{(n)}(r,s), \quad (r,s) \in T$$

defined by  $M_P = \frac{1}{2}(P+1)(P+2)$  interpolation nodes  ${(r_n, s_n)}_{n=1}^{M_P}$  adequately placed on the triangle T.

The cardinal property of the interpolating functions establishes a linear relationship between these forms. It is given by the generalized Vandermonde matrix

$$(\mathcal{V})_{n,m} = \phi_m(r_n, s_n)$$

with derivatives defined by

$$(\mathcal{V}_r)_{n,m} = \phi_{m,r}(r_n, s_n)$$
  
 $(\mathcal{V}_s)_{n,m} = \phi_{m,s}(r_n, s_n)$ 

To take this from T to any triangular element  $E_n$ , one applies the transfinite interpolation formula

$$\begin{bmatrix} x \\ y \end{bmatrix} = -\frac{r+s}{2} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} + \frac{1+r}{2} \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} + \frac{1+s}{2} \begin{bmatrix} x_3 \\ y_3 \end{bmatrix}$$

# **Spectral**/*hp*-**FEM for the Helmholtz, Poisson and Laplace Equations in 1D/2D**

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#### Spectral elements

Elemental contributions can be computed exactly by exploiting orthonormality

 $\int_{E_n} N_i^{(n)} N_j^{(n)} d\mu = J_n ((\mathcal{V}\mathcal{V}^T)^{-1})_{i,j}$  $\int_{E_n} (N_i^{(n)})_x (N_j^{(n)})_x d\mu = J_n (\mathcal{D}_x^T (\mathcal{V}\mathcal{V}^T)^{-1} \mathcal{D}_x)_{i,j}$  $\int_{E_n} (N_i^{(n)})_y (N_j^{(n)})_y d\mu = J_n (\mathcal{D}_y^T (\mathcal{V}\mathcal{V}^T)^{-1} \mathcal{D}_y)_{i,j}$ 

where the matrices  $\mathcal{D}_x$  and  $\mathcal{D}_y$  are

 $\mathcal{D}_x = r_x \mathcal{V}_r \mathcal{V}^{-1} + s_x \mathcal{V}_s \mathcal{V}^{-1}$  $\mathcal{D}_u = r_u \mathcal{V}_r \mathcal{V}^{-1} + s_u \mathcal{V}_s \mathcal{V}^{-1}$ 

and  $J_n$  is the Jacobian of the transform  $T \to E_n$ .

### Strong and weak formulations

The Helmholtz, Poisson and Laplace equations can be approached via the general strong form

$$(\lambda_1 u_x)_x + (\lambda_2 u_y)_y - ku = -q \quad \text{in} \quad \Omega$$
$$u = f \quad \text{on} \quad \partial \Omega$$

The weak form of this is to find u such that

$$\int_{\Omega} (\lambda_1 u_x v_x + \lambda_2 u_y v_y) + kuv \, d\mu = \int_{\Omega} qv \, d\mu$$

is satisfied for any test function  $v \in H_0^1(\Omega)$ .

#### **Convergence** rates

We test h and p-type rates on two trial problems: In 1D on  $u''(x) = e^{4x}$  in (-1, 1) with  $u(\pm 1) = 0$ , and in 2D on a Poisson equation BVP given by

 $u_{xx} + u_{yy} = -q \qquad \text{in} \quad (0, \frac{2}{3}\pi)^2$  $u(x, y) = \cos(x^2 + y^2) \quad \text{on} \quad \partial(0, \frac{2}{3}\pi)^2$ 

with  $q(x, y) = 4\sin(x^2 + y^2) + 4(x^2 + y^2)\cos(x^2 + y^2)$ . Successive h-refinement is by mesh equipartitioning.

Convergence by h-refinement is algebraic with the order depending on P, whereas p-type is exponential with rate depending on h.

Figure 3: Weights (red) of an order P = 2 approximation to  $\phi$ with the vertex nodes connected. Error is shown in Figure 4.

As an illustration of both strengths and weaknesses of the hp-FEM, we consider a Laplace equation BVP corresponding to a fluid flow velocity potential  $\phi$ surrounding an infinite cylinder

where  $\Omega$  is an annulus with inner radius R = 0.25and outer boundary  $\Gamma$  of radius r = 1.



Figure 2: Convergence by equipartitioning the square  $[0, \frac{2}{3}\pi]^2$ . Figure 1: Convergence by equipartitioning the interval [-1, 1]. Sample plot: Order P = 2 with  $2^7$  (left) and  $2^9$  (right) elements. Sample plot: Order P = 3 with  $2^4$  elements.



### Flow surrounding a cylinder

$$\phi_{xx} + \phi_{yy} = 0 \quad \text{in} \quad \Omega$$
  
$$\phi(x, y) = (1 + (R^2/r^2))x \quad \text{on} \quad \Gamma$$



#### Figure 4: Convergence by mesh refinement near the cylinder. Refinements are the same for each order P.

Failure to accurately represent the BVP geometry adds error that can only be lessened by h-refinement. Increasing P adds flexibility in existing elements, but does not lessen error due to a curved geometry. Nodes are added, but the mesh remains unchanged. Thus p-convergence can not replace h-refinement. This is illustrated by the flow surrounding a cylinder, the behaviour of total error is shown in Figure 4. Increasing P without refinement causes higher error.

In general, h and p-types must be combined to have full effect.



#### Geometry and *p*-convergence