

Predecessor

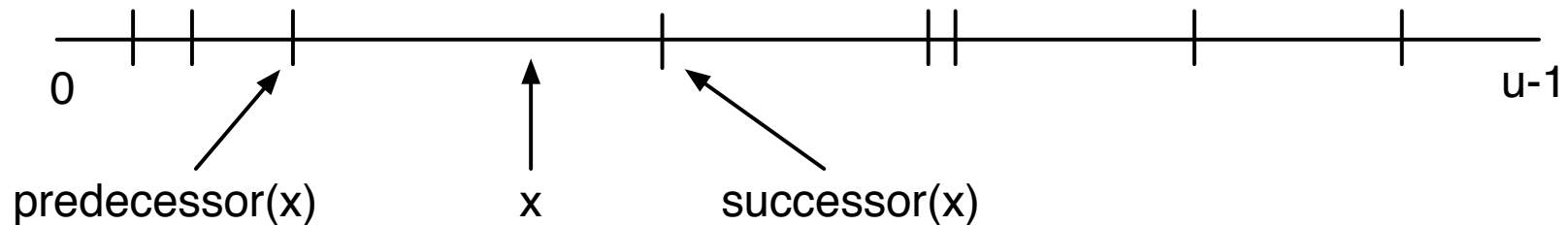
- Predecessor Problem
- van Emde Boas
- Tries

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Predecessors

- **Predecessor problem.** Maintain a set $S \subseteq U = \{0, \dots, u-1\}$ supporting
 - predecessor(x): return the largest element in S that is $\leq x$.
 - successor(x): return the smallest element in S that is $\geq x$.
 - insert(x): set $S = S \cup \{x\}$
 - delete(x): set $S = S - \{x\}$



Predecessors

- Applications.
 - Simplest version of **nearest neighbor problem**.
 - Several applications in other algorithms and data structures.
 - Probably most practically solved problem in the world: Out all computational resources globally a huge fraction is used to solve the predecessor problem!

Predecessors

- Routing IP-Packets

- Where should we forward the packet to?
- To address matching the **longest prefix** of 192.110.144.123.
- Equivalent to predecessor problem.
- Best practical solutions based on advanced predecessor data structures [Degermark, Brodnik, Carlsson, Pink 1997]



?

192.110.142.255

192.110.144.120

192.150.111.000

Predecessors

- Which solutions do we know?
 - Linked list
 - Balanced binary search trees.
 - Bitvectors

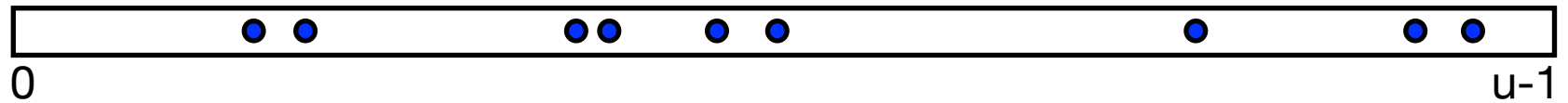
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van Emde Boas

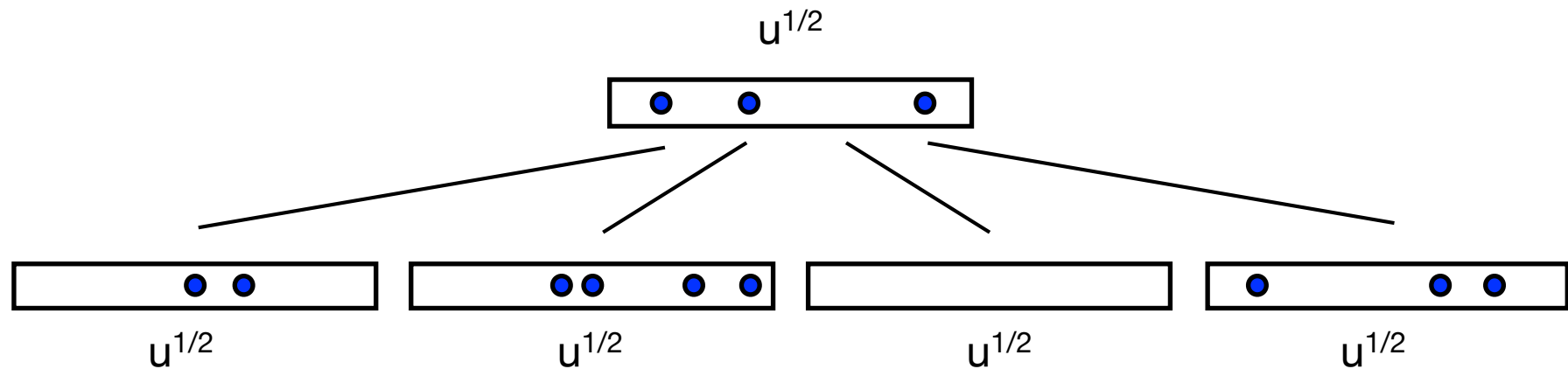
- **Goal.** Static predecessor with $O(\log \log u)$ query time.
- **Solution in 5 steps.**
 - **Bitvector.** Very slow
 - **Two-level bitvector.** Slow.
 -
 - **van Emde Boas [Boas 1975].** Fast.

Solution 1: Bitvector



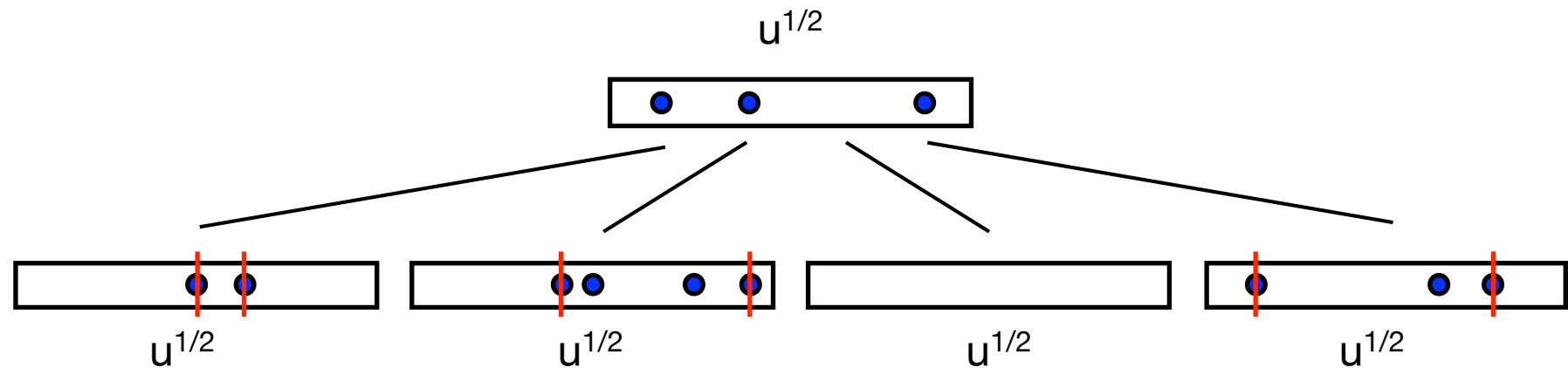
- **Data structure.** Bitvector.
- **Predecessor(x):** Walk left.
- **Time.** $O(u)$

Solution 2: Two-Level Bitvector



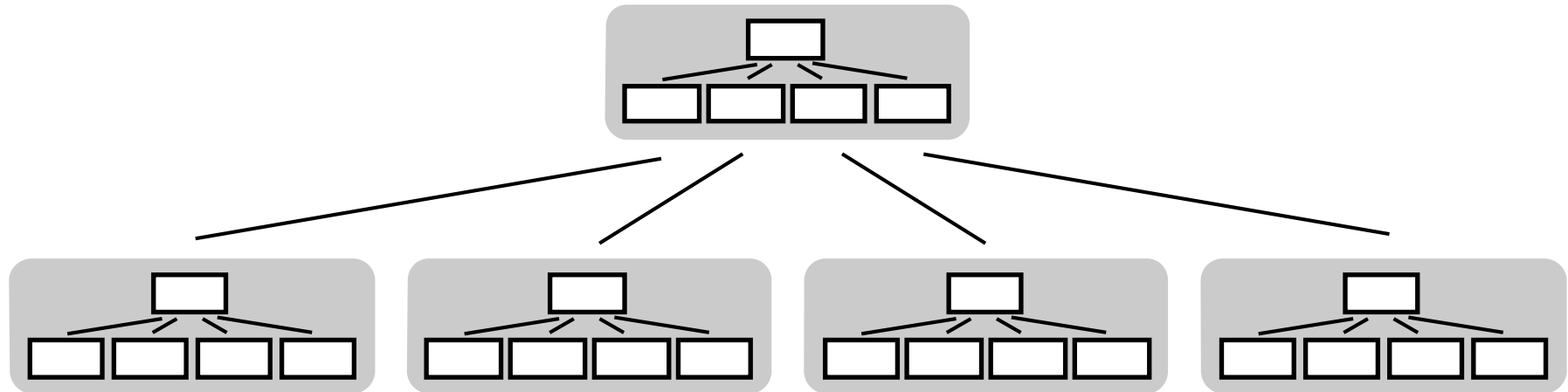
- **Data structure.** Top bitvector + $u^{1/2}$ bottom bitvectors.
- **Predecessor(x):** Walk left in bottom + walk left in top + walk left bottom.
- **Time.** $O(u^{1/2} + u^{1/2} + u^{1/2}) = O(u^{1/2})$
- To find indices in top and bottom write $x = hi(x) \cdot u^{1/2} + lo(x)$
- Index in top is $hi(x)$ and index in bottom is $lo(x)$.

Solution 3: Two-Level Bitvector with less Walking



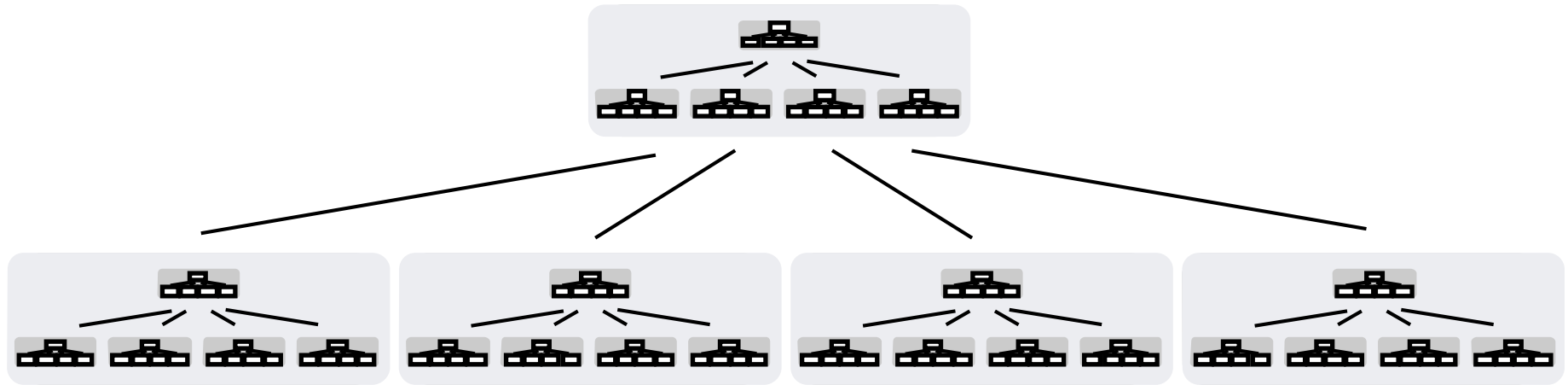
- **Data structure.** Solution 2 with **min** and **max** for each bottom structure.
- **Predecessor(x):**
 - If $hi(x)$ in top and $lo(x) \geq \min$ in bottom [$lo(x)$] walk left in bottom.
 - if $hi(x)$ in top and $lo(x) < \min$ or $hi(x)$ not in top walk left in top. Return max at first non-empty position in top.
- We **either** walk in bottom or top.
- **Time.** $O(u^{1/2})$
- **Observation.**
 - Query is walking left in one vector of size $u^{1/2} + O(1)$ extra work.
 - Why not walk using a predecessor data structure?

Solution 4: Two-Level Bitvector within Top and Bottom



- **Data structure.** Apply solution 3 to top and bottom structures of solution 3.
- Walking left in vector of size $u^{1/2}$ now takes $O((u^{1/2})^{1/2}) = O(u^{1/4})$ time.
- Each level adds $O(1)$ extra work.
- **Time.** $O(u^{1/4})$
- Why not do this recursively?

Solution 5: van Emde Boas



- **Data structure.** Apply recursively until size of vectors is constant.
- **Time.** $T(u) = T(u^{1/2}) + O(1) = O(\log \log u)$
- **Space.** $O(u)$
 - Combined with perfect hashing we can reduce it to $O(n)$ [Mehlhorn and Näher 1990].

van Emde Boas

- **Theorem.** We can solve the static predecessor problem in
 - $O(n)$ space.
 - $O(\log \log u)$ time.
- Can also be made dynamic.

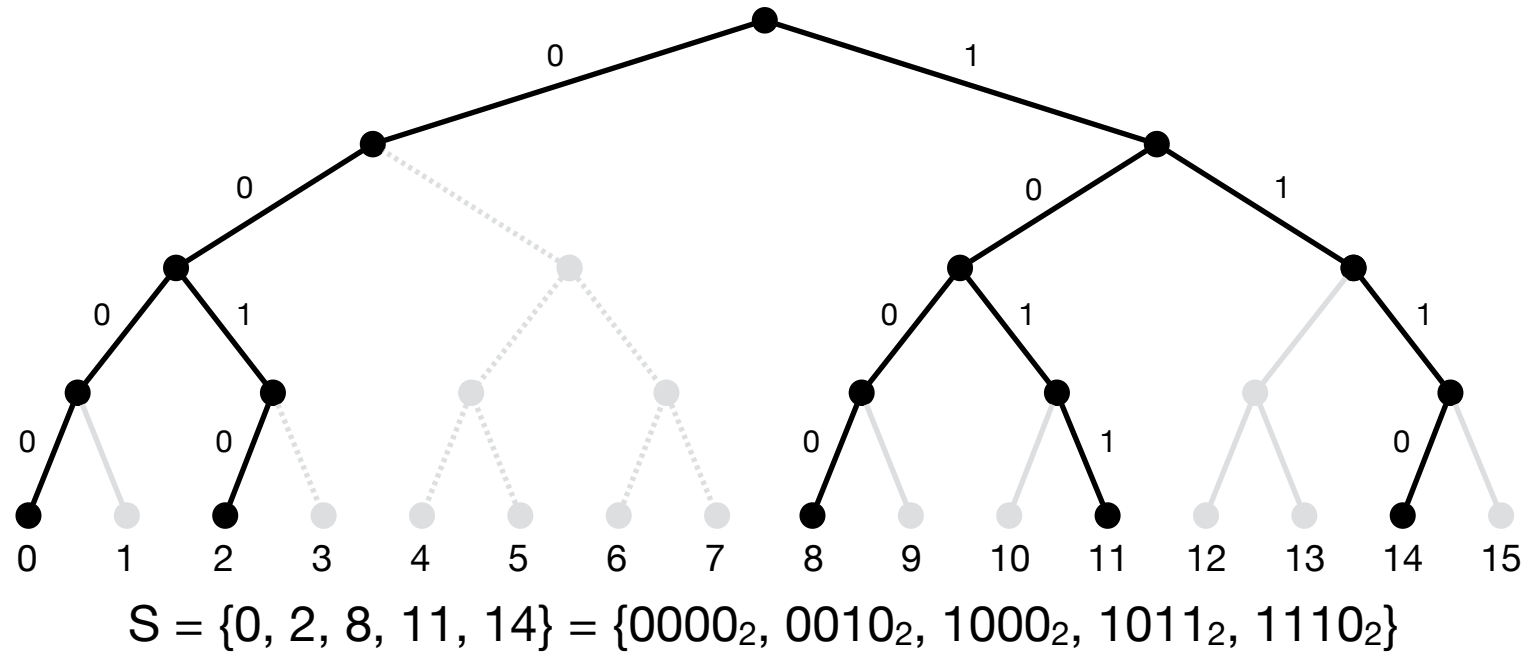
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Tries

- **Goal.** Static predecessor with $O(n)$ space and $O(\log \log u)$ query time.
- Equivalent to van Emde Boas but different perspective. Simpler?
- **Solution in 3 steps.**
 - **Trie.** Slow and too much space.
 - **X-fast trie.** Fast but too much space.
 - **Y-fast trie.** Fast and little space.

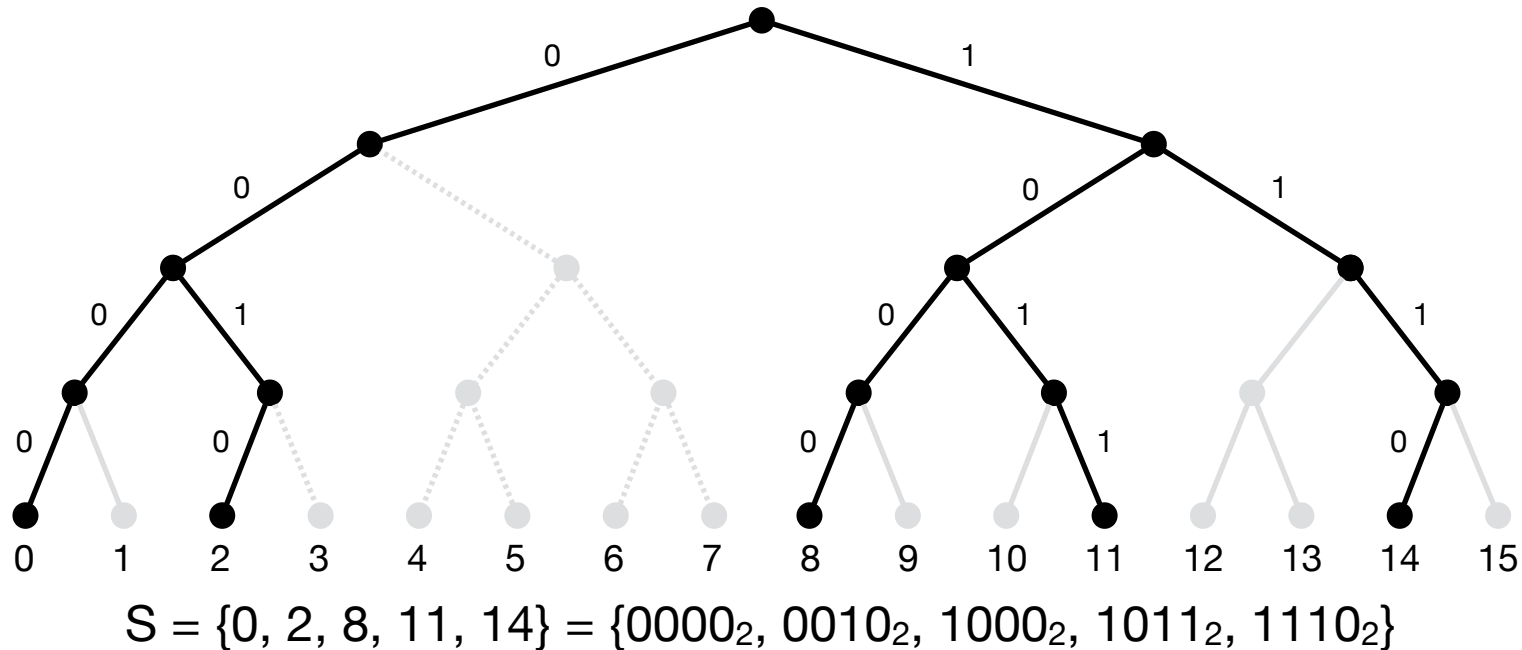
Tries



$S = \{0, 2, 8, 11, 14\} = \{0000_2, 0010_2, 1000_2, 1011_2, 1110_2\}$

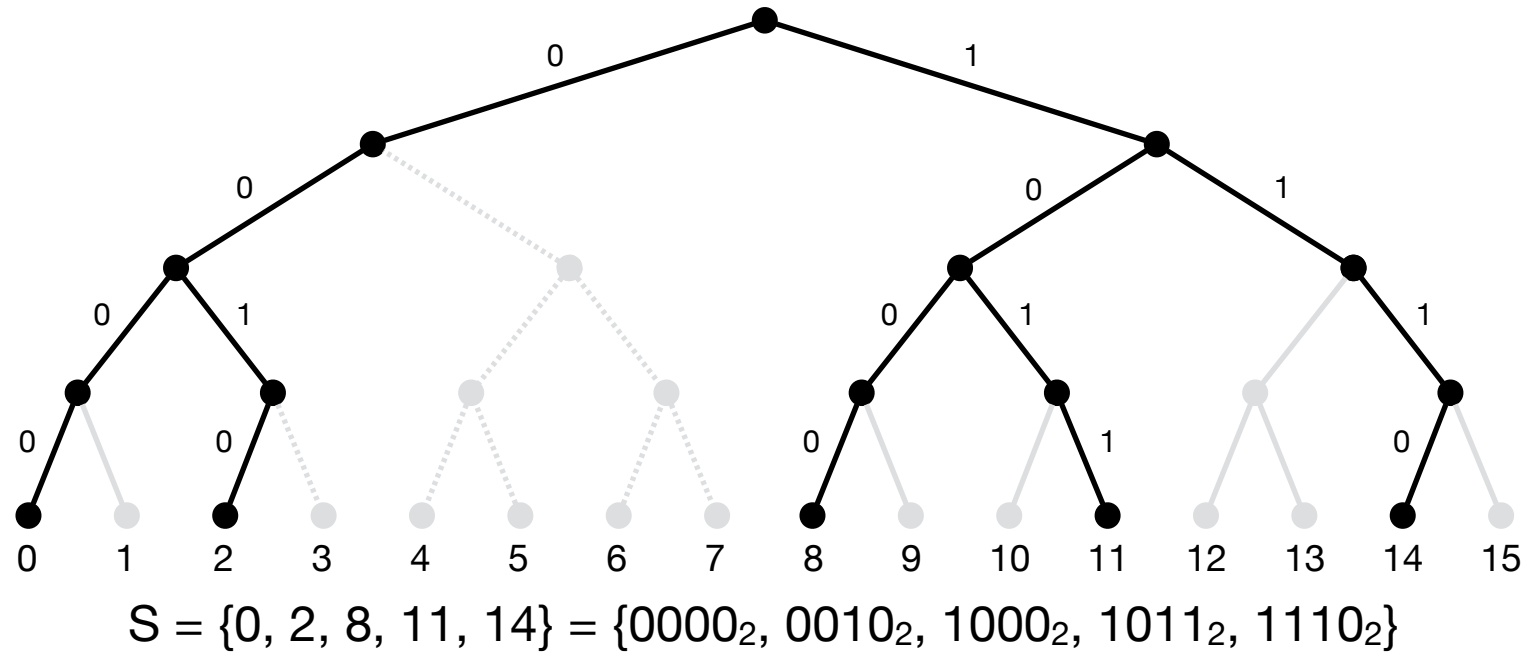
- **Trie.** Tree T of prefixes of binary representation of keys in S.
 - Depth of T is $\log u$
 - Number of nodes in T is $O(n \log u)$.

Solution 1: Top-down Traversal



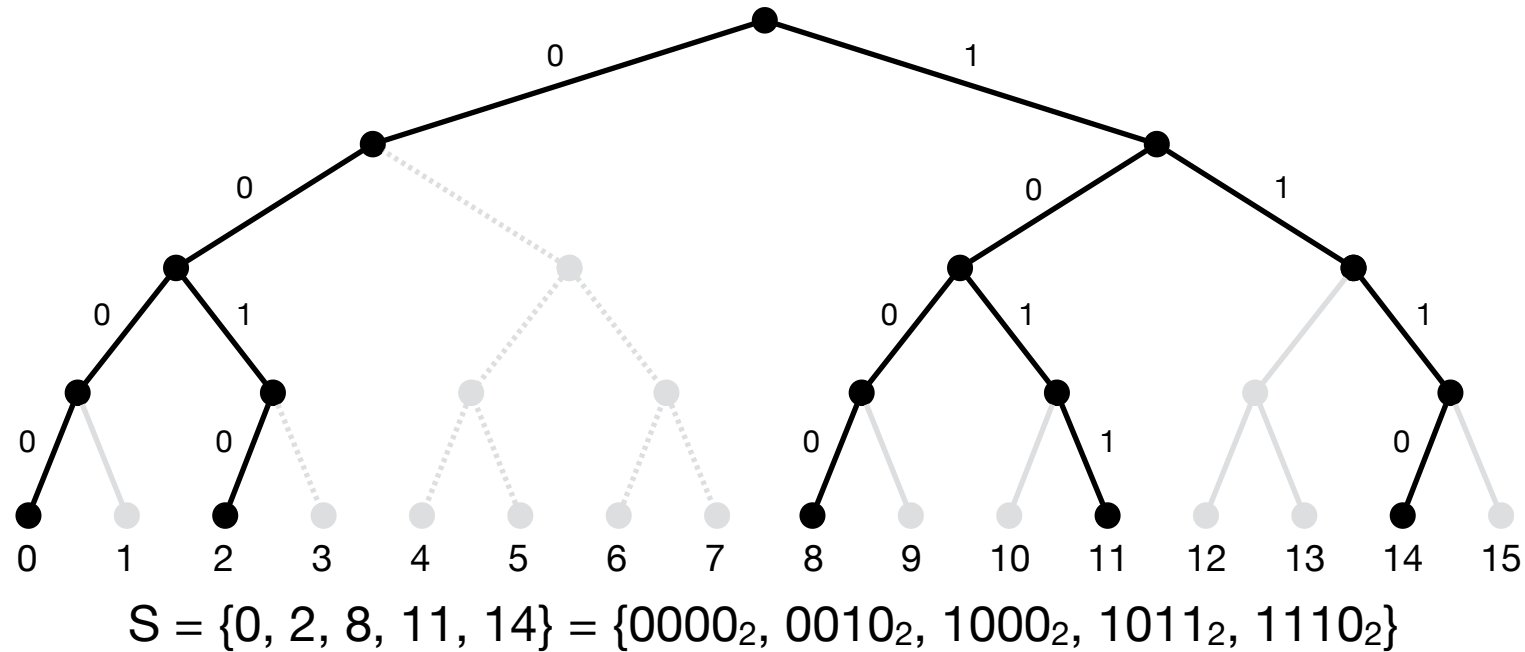
- **Data structure.**
 - T as binary tree with min and max for each node + keys ordered in a linked list.
- **Predecessor(x):** Top-down traversal to find the **longest common prefix** of x with T.
 - x branches of T to right \Rightarrow Predecessor(x) is max of sibling branch.
 - x branches of T to left \Rightarrow Successor(x) is min of sibling branch. Use linked list to get predecessor(x).
- **Time.** $O(\log u)$
- **Space.** $O(n \log u)$

Solution 2: X-Fast Trie



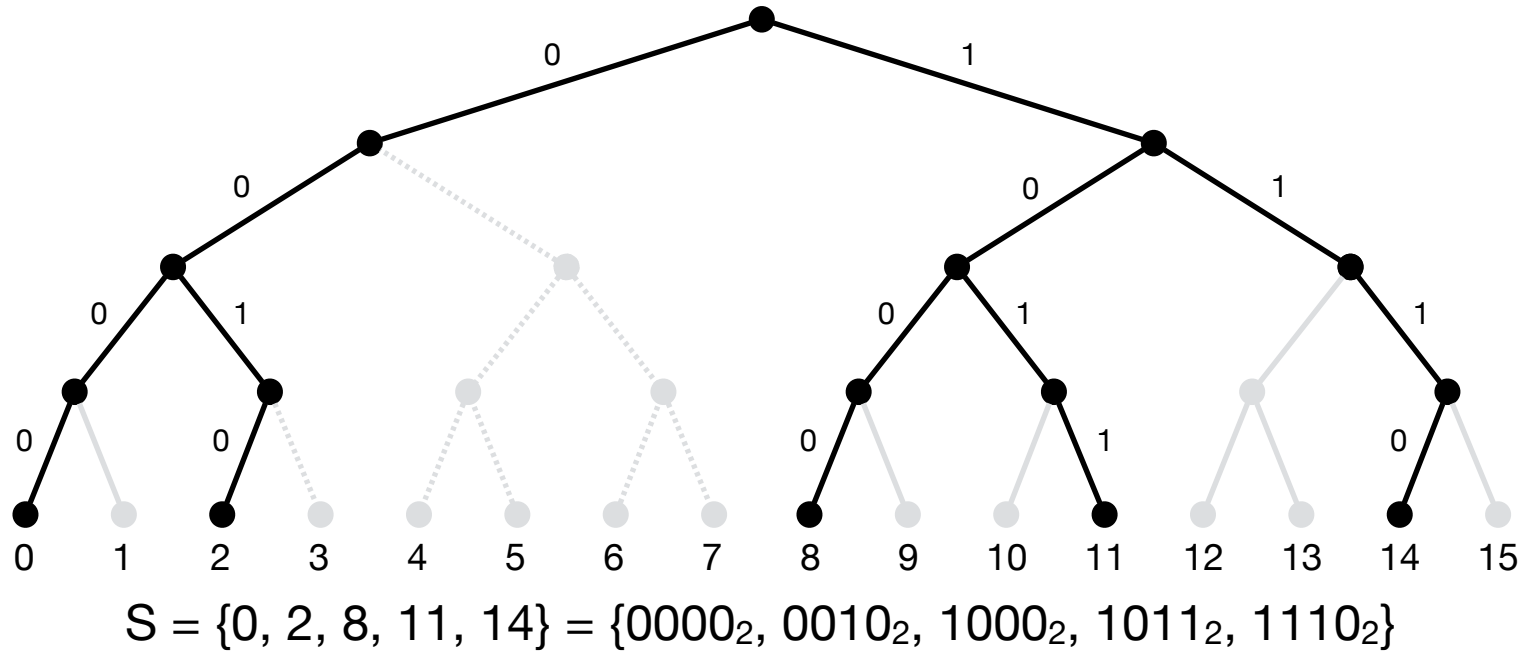
- **Data structure.**
 - For each level store a dictionary of prefixes of keys + solution 1.
 - **Example.** $d_1 = \{0,1\}$, $d_2 = \{00, 10, 11\}$, $d_3 = \{000, 001, 100, 101, 111\}$, $d_4 = S$
- **Space.** $O(n \log u)$

Solution 2: X-Fast Trie



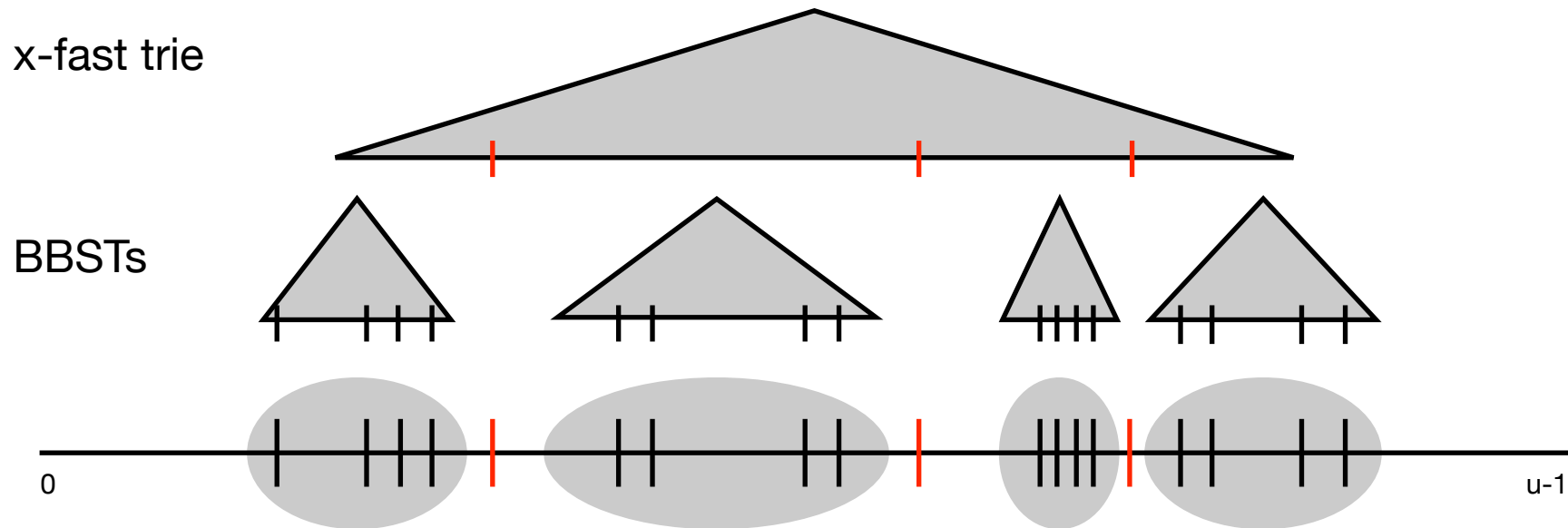
- **Predecessor(x):** Binary search over **levels** to find longest matching prefix with x.
- **Example.** Predecessor($9 = 1001_2$):
 - 10_2 in d_2 exists \Rightarrow continue in bottom 1/2 of tree.
 - 100_2 in d_3 exists \Rightarrow continue in bottom 1/4 of tree.
 - 1001_2 in d_4 does not exist $\Rightarrow 100_2$ is longest prefix.
- **Time.** $O(\log \log u)$

Solution 2: X-Fast Trie



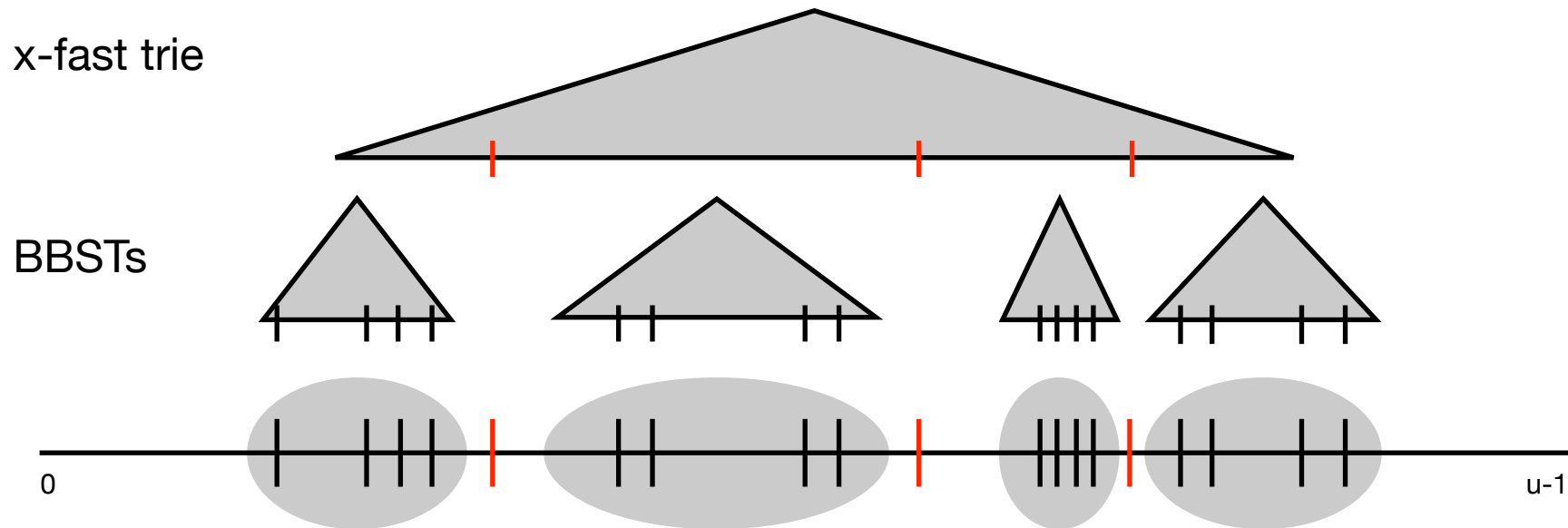
- **Theorem.** We can solve the static predecessor problem in
 - $O(\log \log u)$ time
 - $O(n \log u)$ space.
- How do we get linear space?

Solution 3: Y-Fast Trie



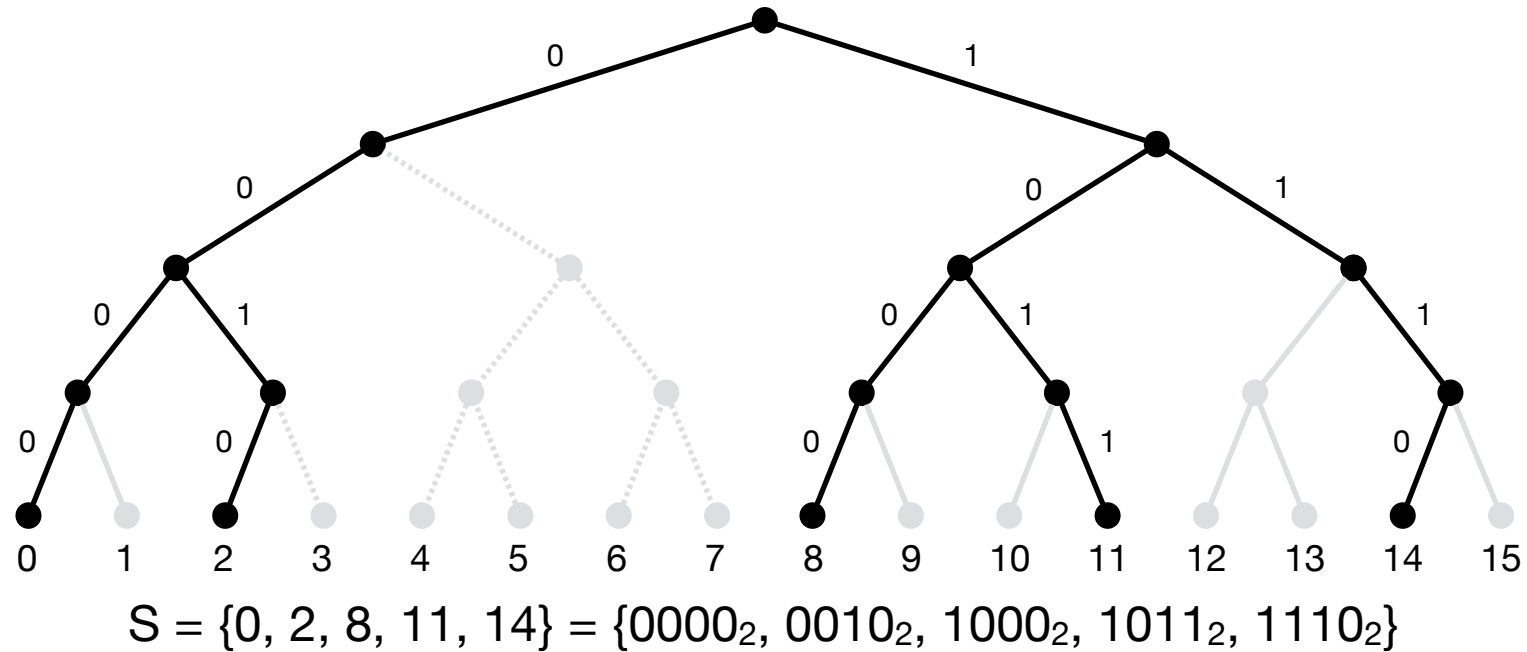
- **Bucketing.**
 - Partition S into $O(n / \log u)$ groups of $\log u$ consecutive keys.
 - Compute $S' =$ set of **split keys** between groups. $|S'| = O(n/\log u)$
- **Data structure.** x-fast trie over S' + balanced binary search trees for each group.
- **Space.**
 - x-fast trie: $O(|S'| \log u) = O(n/\log u \cdot \log u) = O(n)$.
 - Balanced binary search trees: $O(n)$.
 - $\Rightarrow O(n)$ in total.

Solution 3: Y-Fast Trie



- **Predecessor(x):**
 - Compute $s = \text{predecessor}(x)$ in x-fast trie.
 - Compute $\text{predecessor}(x)$ in BBST to the left or right of s .
- **Time.**
 - x-fast trie: $O(\log \log u)$
 - balanced binary search tree: $O(\log(\text{group size})) = O(\log \log u)$.
 - $\Rightarrow O(\log \log u)$ in total.

Solution 3: Y-Fast Trie



- **Theorem.** We can solve the static predecessor problem in
 - $O(\log \log u)$ time
 - $O(n)$ space.

Y-Fast Tries

- **Theorem.** We can solve the static predecessor problem in
 - $O(n)$ space.
 - $O(\log \log u)$ time.
- What about updates?
- **Theorem.** We can solve the dynamic predecessor problem in
 - $O(n)$ space
 - $O(\log \log u)$ **expected** time for predecessor and updates.

From dynamic hashing



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