- Union Find
- Quick Find
- Quick Union
- · Weighted Quick Union
- Path Compression
- Dynamic Connectivity

Philip Bille

Union Find

- Union find. Maintain a dynamic family of sets supporting the following operations:
 - INIT(n): construct sets {0}, {1},..., {n-1}
 - UNION(i,j): forms the union of the two sets that contain i and j. If i and j are in the same set nothing happens.
 - FIND(i): return a representative for the set that contains i.

INIT(9)
{0} {1} {2} {3} {4} {5} {6} {7} {8}

{1, 0, 6} {8, 3, 2, 7} {4, 5} UNION(5,0) {1, 0, 6, 4, 5} {8, 3, 2, 7}

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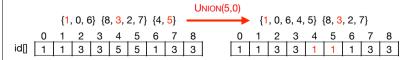
Union Find

- · Applications.
 - · Dynamic connectivity.
 - · Minimum spanning tree.
 - · Unification in logic and compilers.
 - · Nearest common ancestors in trees.
 - · Hoshen-Kopelman algorithm in physics.
 - · Games (Hex and Go)
 - Illustration of clever techniques in data structure design.

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Quick Find

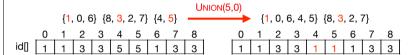


- · Time.
 - O(n) time for INIT, O(n) time for UNION, and O(1) tid for FIND.

Quick Find

- Quick find. Maintain array id[0..n-1] such that id[i] = representative for i.
 - INIT(n): set elements to be their own representative.
 - UNION(i,j): if FIND(i) ≠ FIND(j), update representative for all elements in one of the sets.
 - FIND(i): return representative.

INIT(9) {0} {1} {2} {3} {4} {5} {6} {7} {8} 0 1 2 3 4 5 6 7 8 id[0 1 2 3 4 5 6 7 8

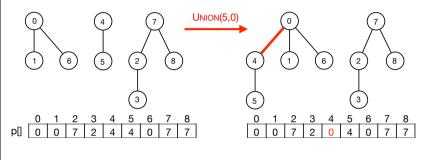


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Quick Union

- · Quick union. Maintain each sets as a rooted tree.
- Store trees as array p[0..n-1] such that p[i] is the parent of i and p[root] = root. Representative is the root of tree.
 - INIT(n): create n trees with one element each.
 - UNION(i,j): if FIND(i) ≠ FIND(j), make the root of one tree the child of the root of the other tree.
 - FIND(i): follow path to root and return root.

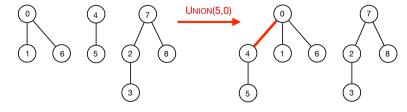


Quick Union

- INIT(n): create n trees with one element each.
- UNION(i,j): if FIND(i) ≠ FIND(j), make the root of one tree the child of the root of the other tree.
- FIND(i): follow path to root and return root.
- Exercise. Show data structure after each operation in the following sequence.
 - INIT(7), UNION(0,1), UNION(2,3), UNION(5,1), UNION(5,0), UNION(0,3), UNION(5,2), UNION(4,3), UNION(4,6).

Quick Union

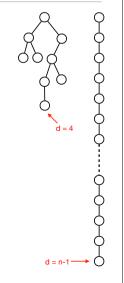
UNION(i,j): $r_i = FIND(i)$ $r_j = FIND(j)$ if $(r_i \neq r_j)$ $p[r_i] = r_j$



- · Time.
 - $\bullet\,$ O(n) time for Init, O(d) tid for Union and Find, where d is the depth of the tree.

Quick Union

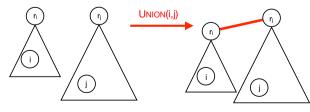
- UNION and FIND depend on the depth of the tree.
- Bad news. Depth can be n-1.
- · Challenge. Can combine trees to limit the depth?



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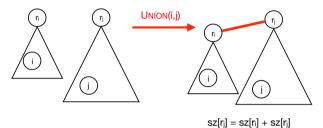
Weighted Quick Union

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\begin{split} & \text{UNION(i,j):} \\ & r_i = \text{FIND(i)} \\ & r_j = \text{FIND(j)} \\ & \text{if } (r_i \neq r_j) \\ & \text{if } (\text{sz}[r_i] < \text{sz}[r_j]) \\ & p[r_i] = r_j \\ & \text{sz}[r_j] = \text{sz}[r_i] + \text{sz}[r_j] \\ & \text{else} \\ & p[r_j] = r_i \\ & \text{sz}[r_i] = \text{sz}[r_i] + \text{sz}[r_j] \end{split}
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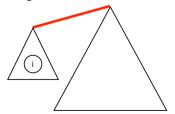
Weighted Quick Union

- · Weighted quick union. Extension of quick union.
- Maintain extra array sz[0..n-1] such sz[i] = the size of the subtree rooted at i.
 - INIT: as before + initialize sz[0..n-1].
 - · FIND: as before.
 - UNION(i,j): if FIND(i) ≠ FIND(j), make the root of the smaller tree the child of the root of the larger tree.
- Intuition. UNION balances the trees.



Weighted Quick Union

- · Lemma. With weighted quick union the depth of a node is at most log2 n.
- · Proof.
 - · Consider node i with depth di.
 - Initially $d_i = 0$.
 - \cdot d_i increases with 1 when the tree is combined with a larger tree.
 - The combined tree is at least twice the size.
 - · We can double the size of trees at most log₂ n times.
 - $\Longrightarrow d_i \le log_2 n$.

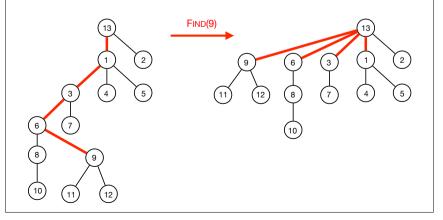


Data structure	Union	FIND
quick find	O(n)	O(1)
quick union	O(n)	O(n)
weighted quick union	O(log n)	O(log n)

· Challenge. Can we do even better?

Path Compression

- Path compression. Compress path on FIND. Make all nodes on the path children of the root.
- No change in running time for a single FIND. Subsequent FIND become faster.
- · Works with both quick union and weighted quick union.

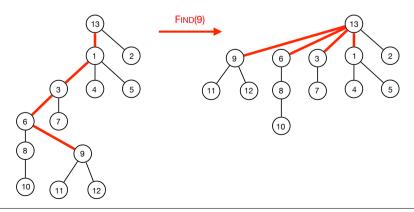


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Path Compression

- Theorem [Tarjan 1975]. With path compression any sequence of m FIND og UNION operations on n elements take O(n + m α(m,n)) time.
- $\alpha(m,n)$ is the inverse of Ackermanns function. $\alpha(m,n) \le 5$ for any practical input.
- Theorem [Fredman-Saks 1985]. It is not possible to support m FIND og UNION operations O(n+m) time.



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Dynamic Connectivity

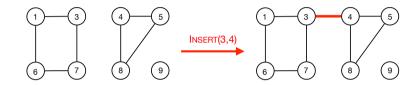
- · Implementation with union find.
 - INIT(n): initialize a union find data structure with n elements.
 - CONNECTED(u,v): FIND(u) == FIND(v).
 - INSERT(u, v): UNION(u,v)



- Time
 - O(n) time for INIT, O(log n) time for CONNECTED, and O(log n) time for INSERT

Dynamic Connectivity

- Dynamic connectivity. Maintain a dynamic graph supporting the following operations:
 - INIT(n): create a graph G med n vertices and no edges.
 - CONNECTED(u,v): determine if u og v are connected.
 - INSERT(u, v): add edge (u,v). We assume (u,v) does not already exists.



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